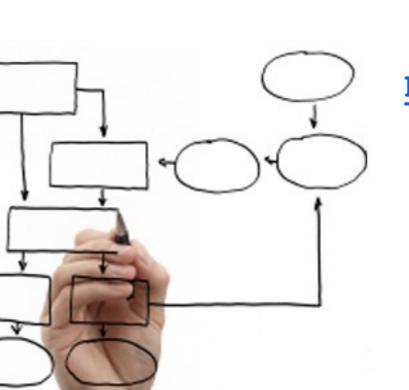
Business Processes Modelling MPB (6 cfu, 295AA)

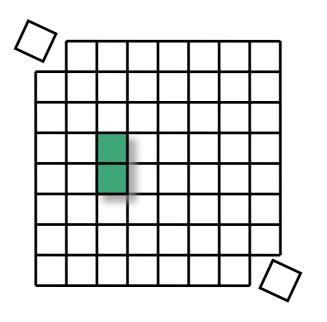


Roberto Bruni

http://www.di.unipi.it/~bruni

11 - Invariants

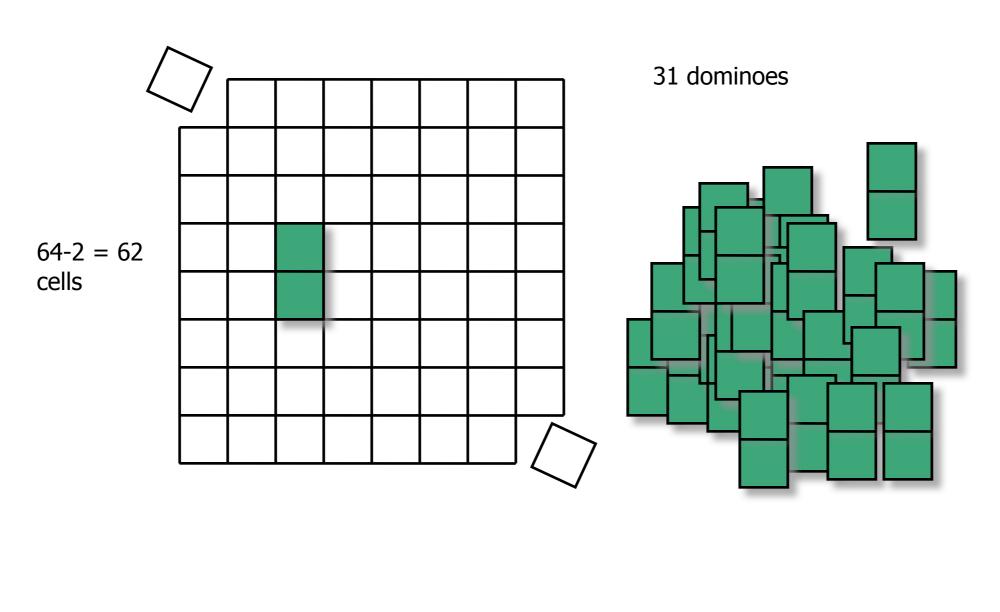
Object



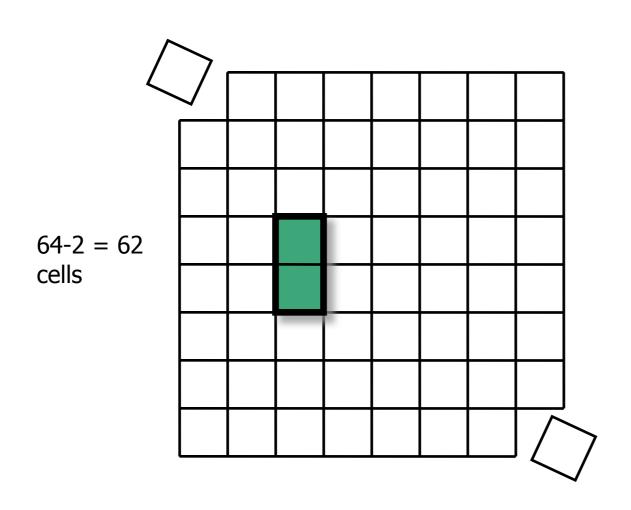
We introduce two relevant kinds of invariants for Petri nets

Free Choice Nets (book, optional reading)

https://www7.in.tum.de/~esparza/bookfc.html

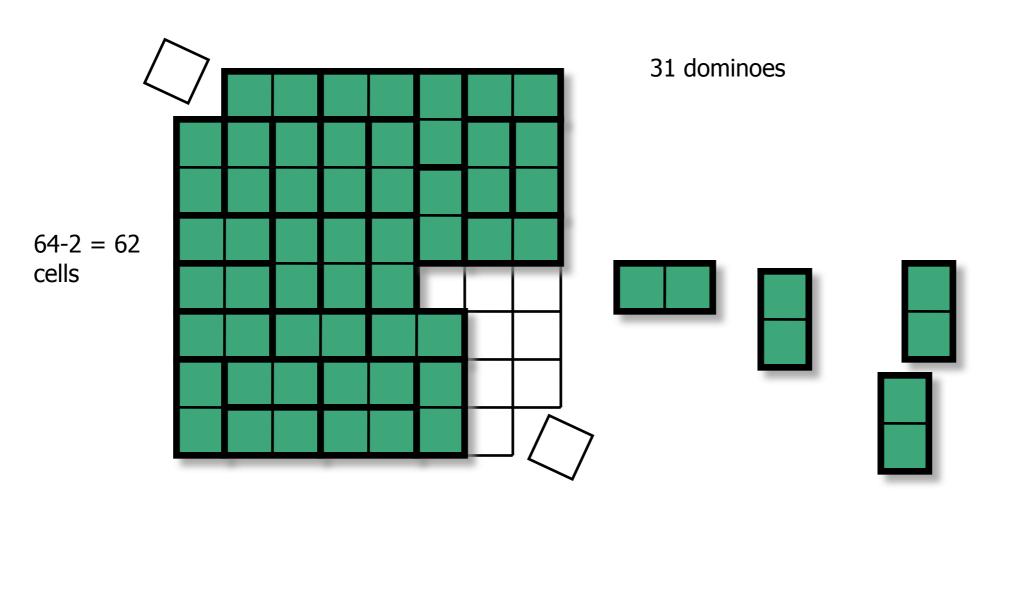


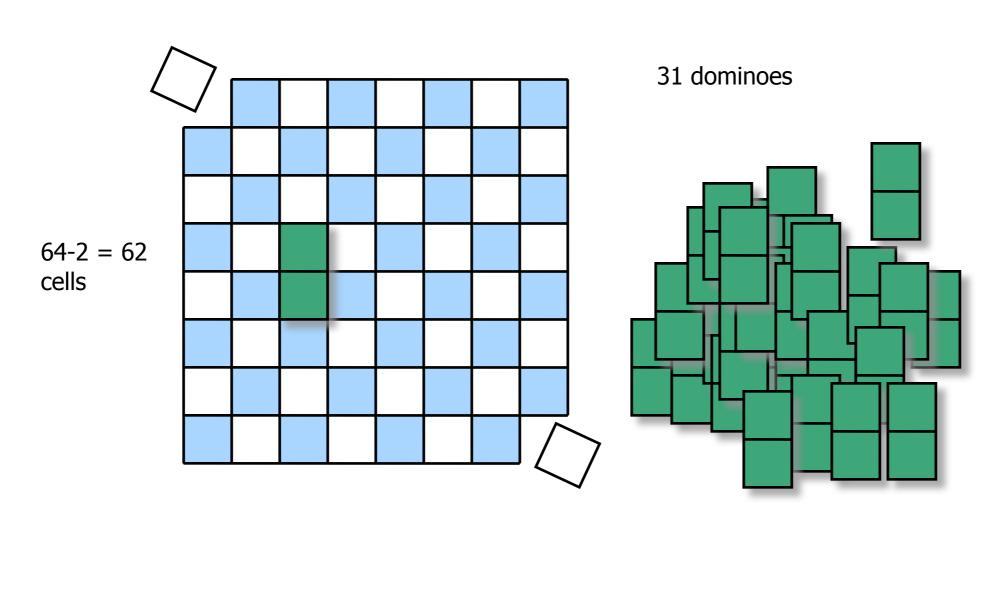




31 dominoes









Invariant

An invariant of a dynamic system is an assertion that holds at every reachable state

Examples:
liveness of a transition t
deadlock freedom
boundedness

Recall: Liveness, formally

$$(P, T, F, M_0)$$

$$\forall t \in T, \quad \forall M \in [M_0], \quad \exists M' \in [M], \quad M' \stackrel{t}{\longrightarrow}$$

Liveness as invariant

Lemma

If (P, T, F, M_0) is live and $M \in [M_0]$, then (P, T, F, M) is live.

Let $t \in T$ and $M' \in [M]$.

Since $M \in [M_0]$, then $M' \in [M_0]$.

Since (P, T, F, M_0) is live, $\exists M'' \in [M']$ with $M'' \stackrel{t}{\longrightarrow}$.

Therefore (P, T, F, M) is live.

Recall: Deadlock freedom, formally

$$(P, T, F, M_0)$$

$$\forall M \in [M_0\rangle, \exists t \in T, M \xrightarrow{t}$$

Deadlock freedom as invariant

Lemma: If (P, T, F, M_0) is deadlock-free and $M \in [M_0]$, then (P, T, F, M) is deadlock-free.

Let $M' \in [M]$.

Since $M \in [M_0]$, then $M' \in [M_0]$.

Since (P, T, F, M_0) is deadlock-free, $\exists t \in T$ with $M' \stackrel{t}{\longrightarrow}$.

Therefore (P, T, F, M) is deadlock-free.

Exercise

Give the formal definition of Boundedness

Then prove that Boundedness is an invariant

Or give a counter-example

Exercise

Give the formal definition of Cyclicity

Then prove that Cyclicity is an invariant

Or give a counter-example

Puzzle: from MI to MU

You can compose words using symbols M, I, U

Given the initial word **MI**, you can apply the following transformations, in any order, as many times as you like:

- 1. Add a **U** to the end of any string ending in **I** (e.g., **MI** to **MIU**).
- 2. Double the string after the M (e.g., MIU to MIUIU).
- 3. Replace any III with a U (e.g., MUIIIU to MUUU).
- 4. Remove any UU (e.g., MUUU to MU).

Can you transform **MI** to **MU**? (*Hint*: count the **I**s modulo 3)

Structural invariants

In the case of Petri nets, it is possible to compute certain vectors of **rational** numbers^(*) (directly from the structure of the net) (independently from the initial marking) which induce nice invariants, called

S-invariants

T-invariants

(*) it is not necessary to consider real-valued solutions, because incidence matrices only have integer entries

Why invariants?

Can be calculated efficiently (polynomial time for a basis)

Independent of initial marking

Structural property with behavioural consequences

However, the main reason is didactical! You only truly understand a model if you think about it in terms of invariants!

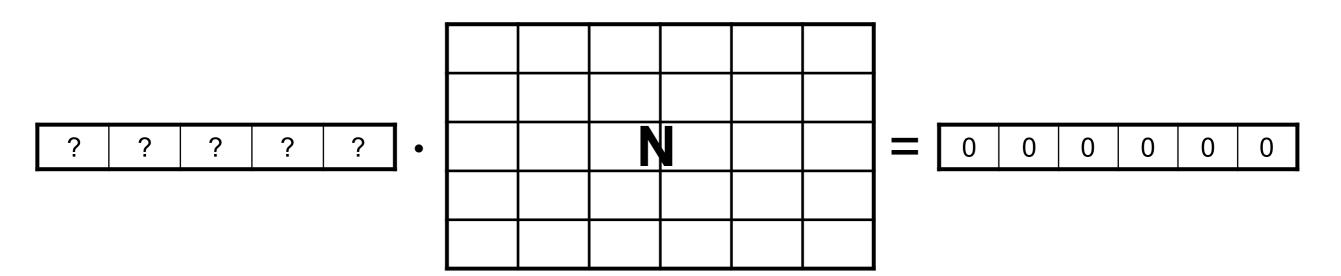


S-invariants

S-invariant (aka place-invariant)

Definition: An S-invariant of a net N=(P,T,F) is a rational-valued solution **x** of the equation

$$\mathbf{x} \cdot \mathbf{N} = \mathbf{0}$$



Fundamental property of S-invariants

Proposition: Let \mathbf{I} be an invariant of N.

For any $M \in [M_0]$ we have $\mathbf{I} \cdot M = \mathbf{I} \cdot M_0$

Fundamental property of S-invariants

Proposition: Let I be an invariant of N.

For any $M \in [M_0]$ we have $\mathbf{I} \cdot M = \mathbf{I} \cdot M_0$

Fundamental property of S-invariants

Proposition: Let \mathbf{I} be an invariant of N.

For any $M \in [M_0]$ we have $\mathbf{I} \cdot M = \mathbf{I} \cdot M_0$

Since $M \in [M_0]$, there is σ s.t. $M_0 \xrightarrow{\sigma} M$ By the marking equation: $M = M_0 + \mathbf{N} \cdot \vec{\sigma}$

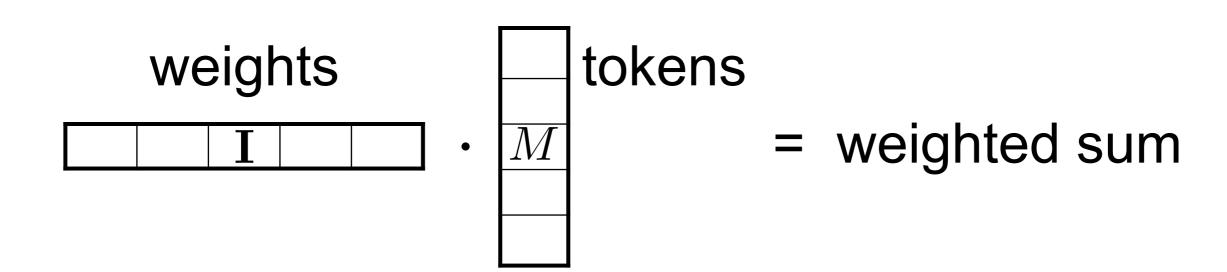
Therefore:
$$\mathbf{I} \cdot M = \mathbf{I} \cdot (M_0 + \mathbf{N} \cdot \vec{\sigma})$$

$$= \mathbf{I} \cdot M_0 + \mathbf{I} \cdot \mathbf{N} \cdot \vec{\sigma}$$

$$= \mathbf{I} \cdot M_0 + \mathbf{0} \cdot \vec{\sigma}$$

$$= \mathbf{I} \cdot M_0$$

Place-invariant, intuitively



Place-invariant, intuitively

A place-invariant assigns a weight to each place such that the weighted token sum remains constant during any computation

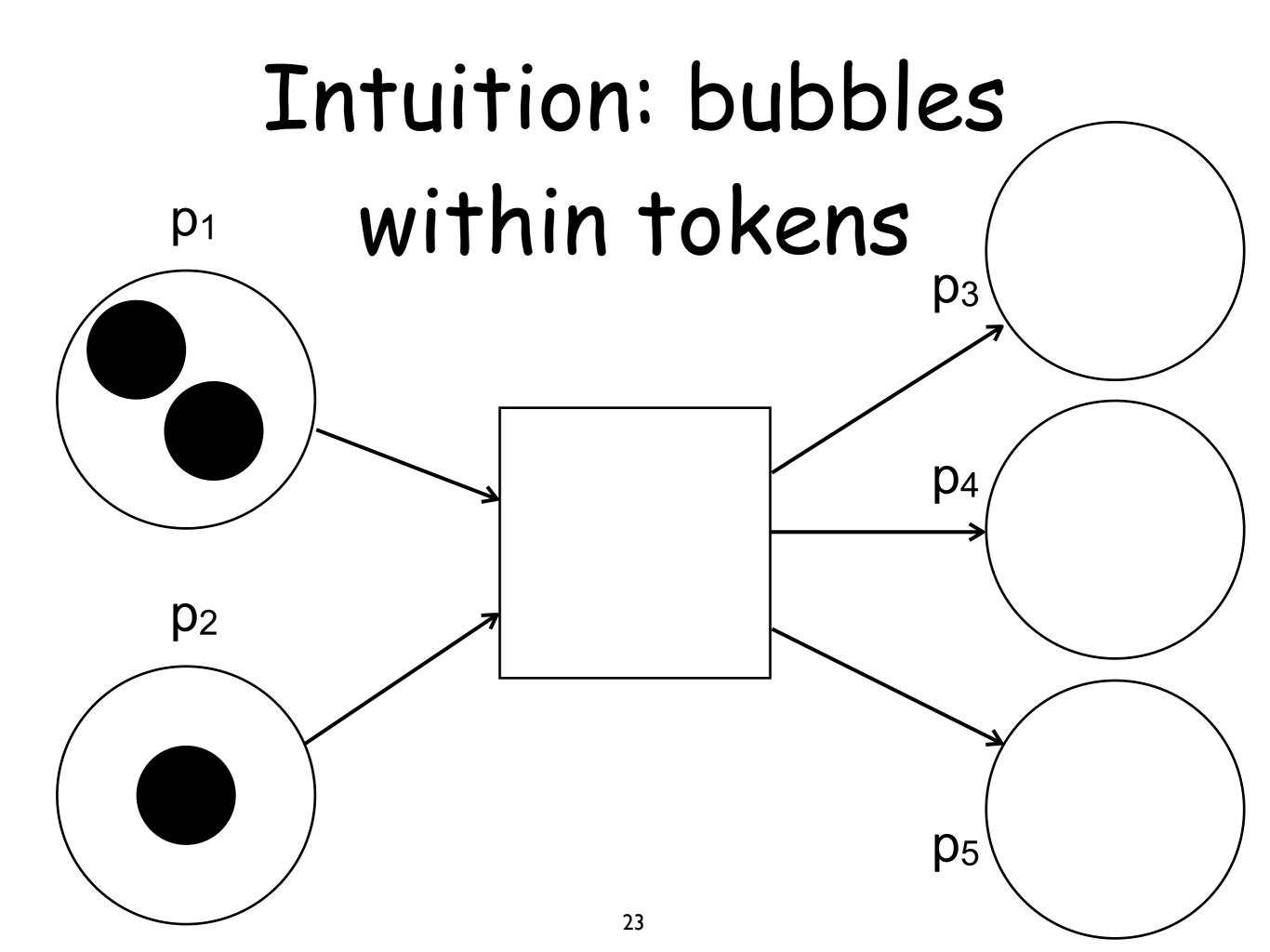
For example, you can imagine that tokens are coins, places are the different kinds of available coins, the S-invariant assigns a value to each coin: the value of a marking is the sum of the values of the tokens/coins in it and it is not changed by firings

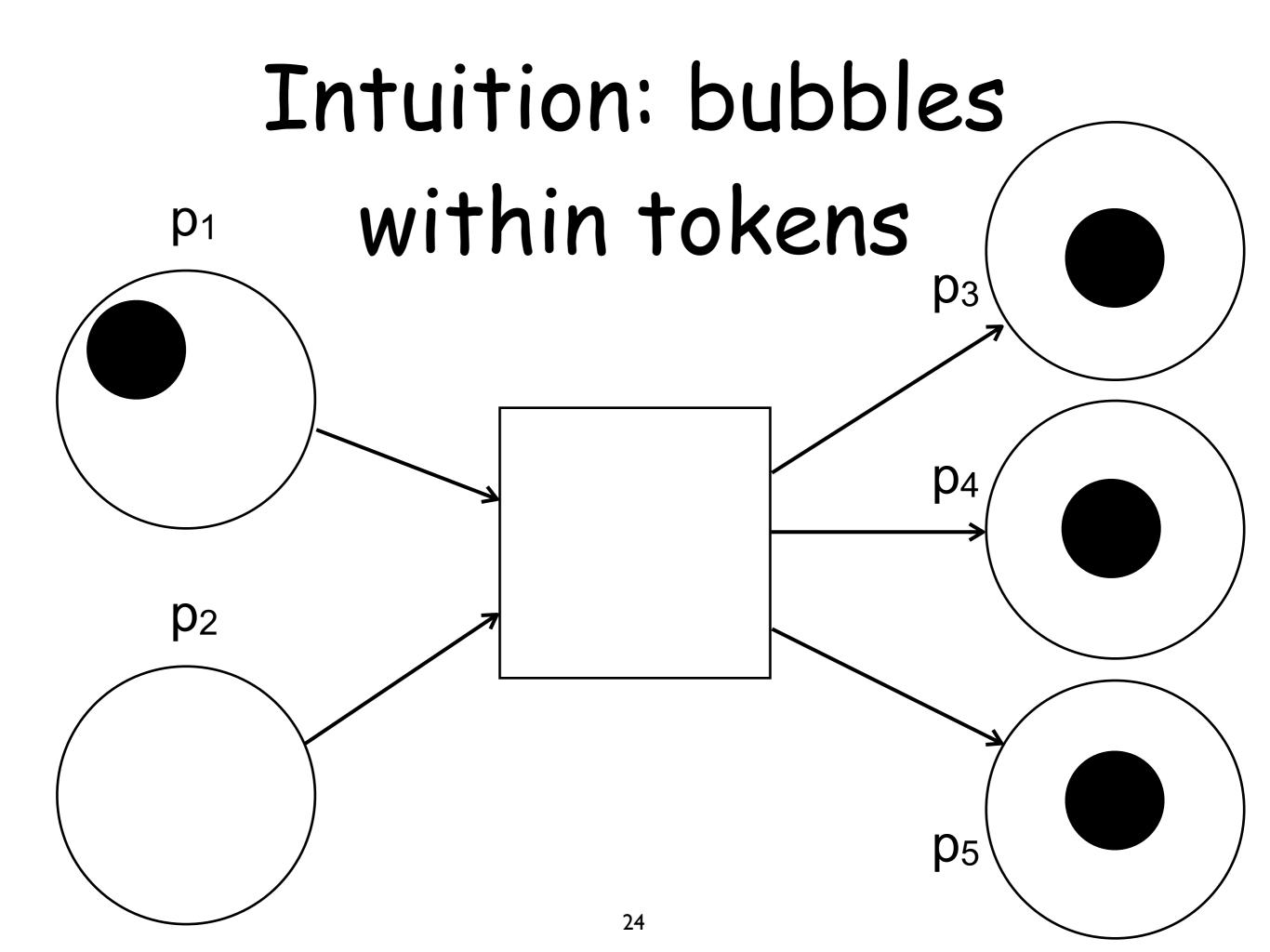
Place-invariant, intuitively

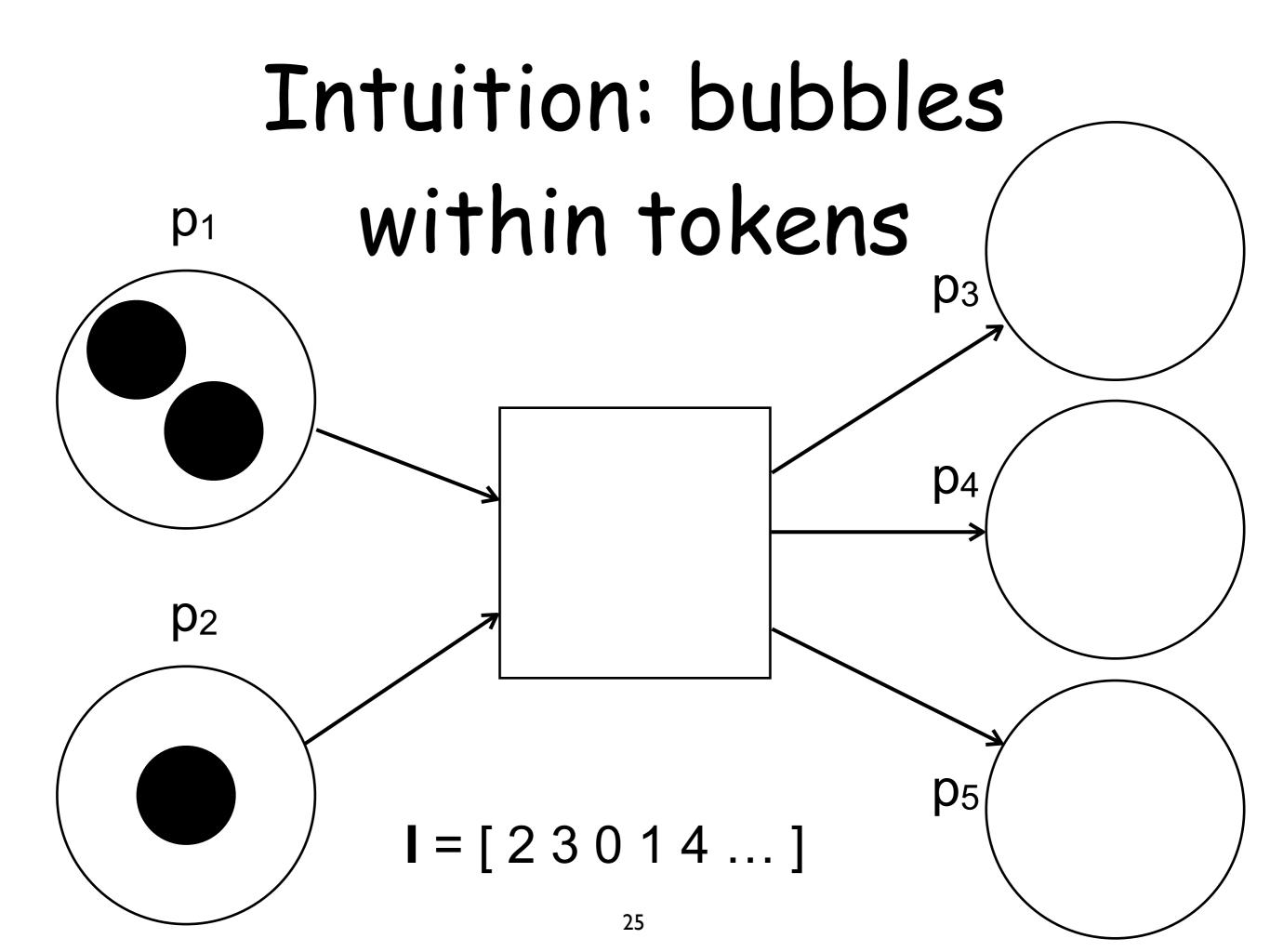
A place-invariant assigns a weight to each place such that the weighted token sum remains constant during any computation

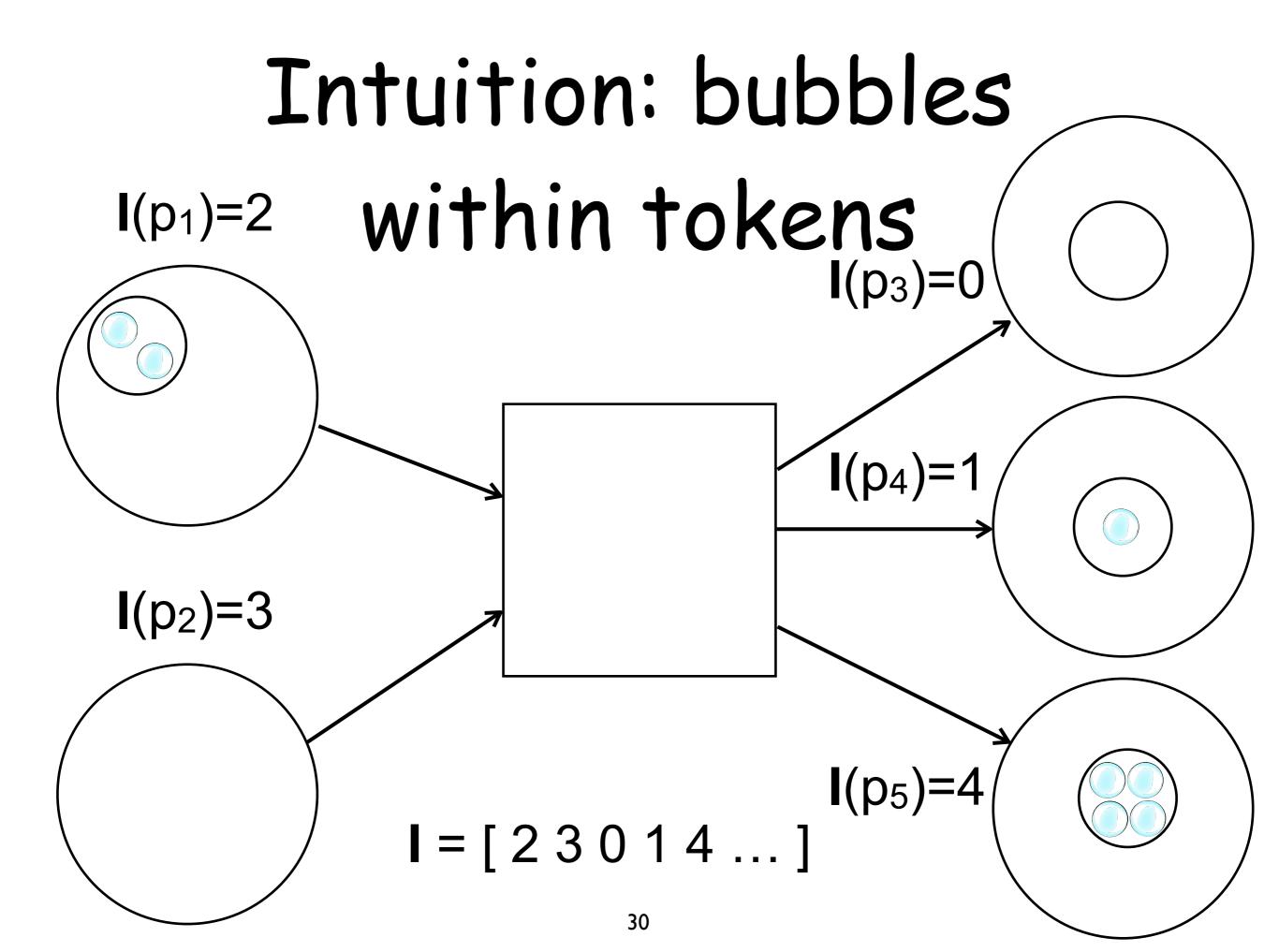
For example, you can imagine that tokens are molecules, places are different kinds of molecules, the S-invariant assigns the number of atoms needed to form each molecule:

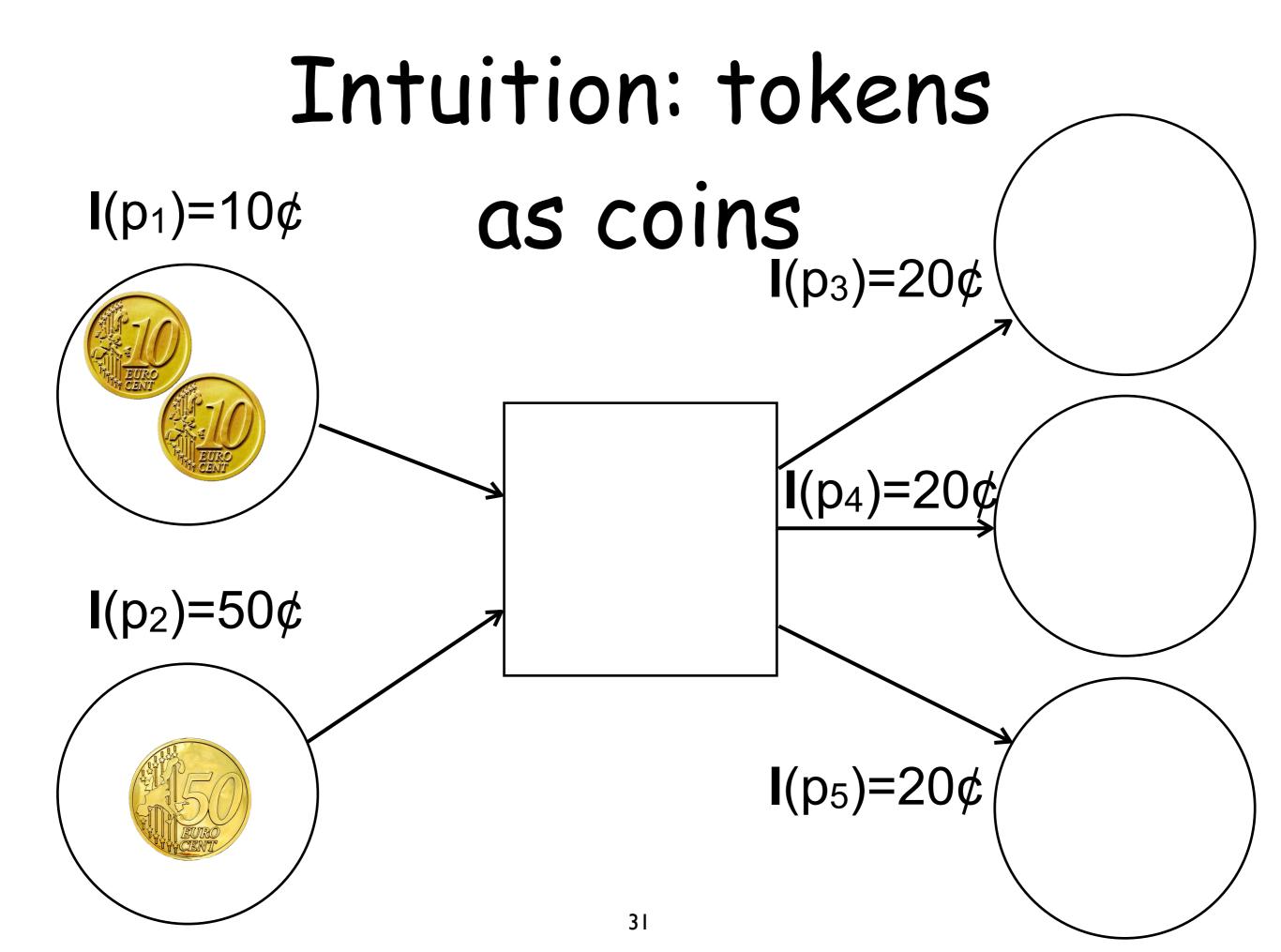
the overall number of atoms is not changed by firings

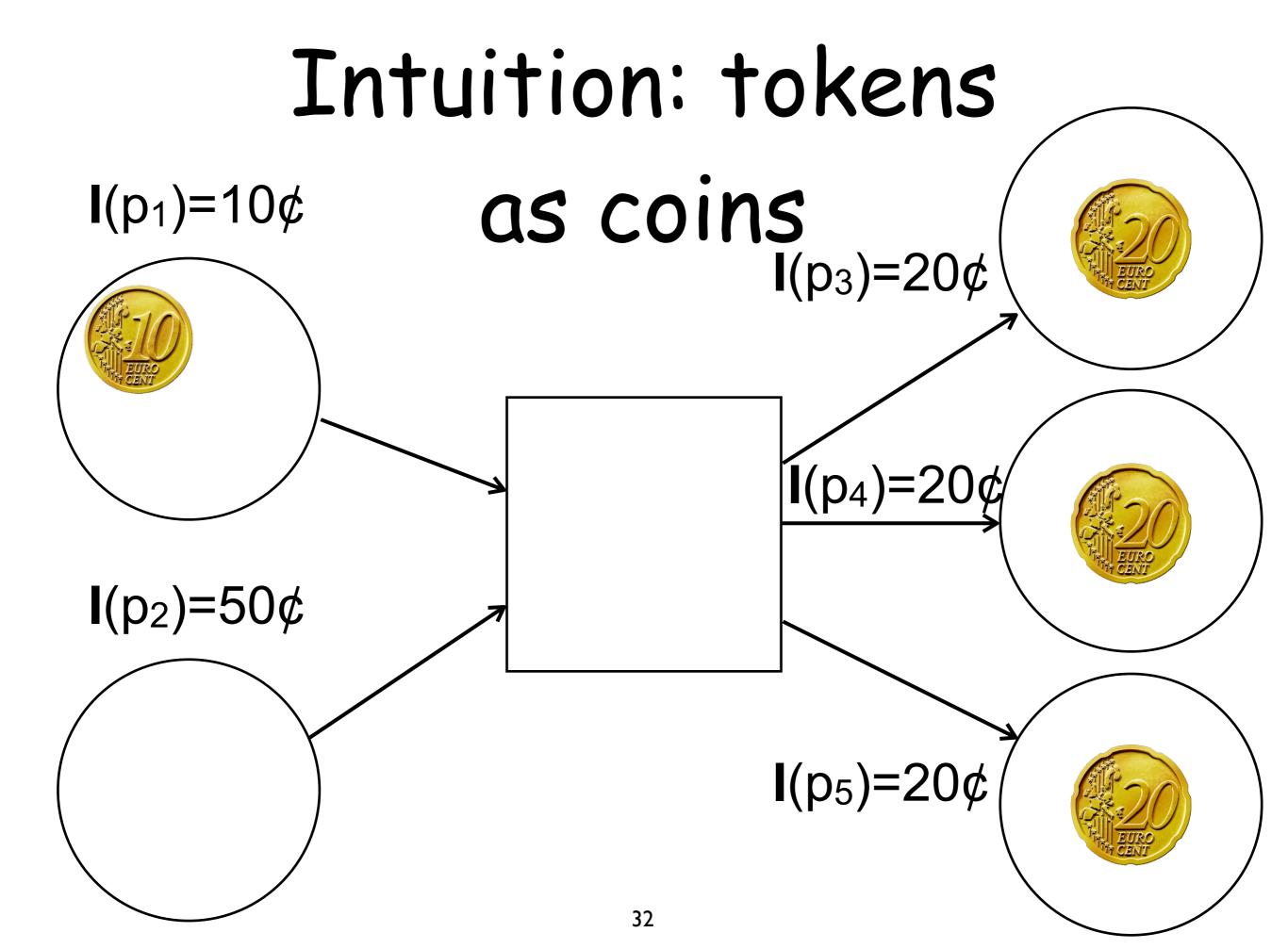












Linear combination

Proposition:

Any linear combination of S-invariants is an S-invariant

Take any two S-Invariants I_1 and I_2 and any two values k_1, k_2 . We want to prove that $k_1 I_1 + k_2 I_2$ is an S-invariant.

$$(k_1 \mathbf{I}_1 + k_2 \mathbf{I}_2) \cdot \mathbf{N} = k_1 \mathbf{I}_1 \cdot \mathbf{N} + k_2 \mathbf{I}_2 \cdot \mathbf{N}$$

$$= k_1 \mathbf{0} + k_2 \mathbf{0}$$

$$= \mathbf{0}$$

Alternative definition of S-invariant

Proposition:

A mapping $\mathbf{I}:P\to\mathbb{Q}$ is an S-invariant of N iff for any $t\in T$:

$$\sum_{p \in \bullet t} \mathbf{I}(p) = \sum_{p \in t \bullet} \mathbf{I}(p)$$

Exercise

Prove the proposition about the alternative characterization of S-invariants

Consequence of alternative definition

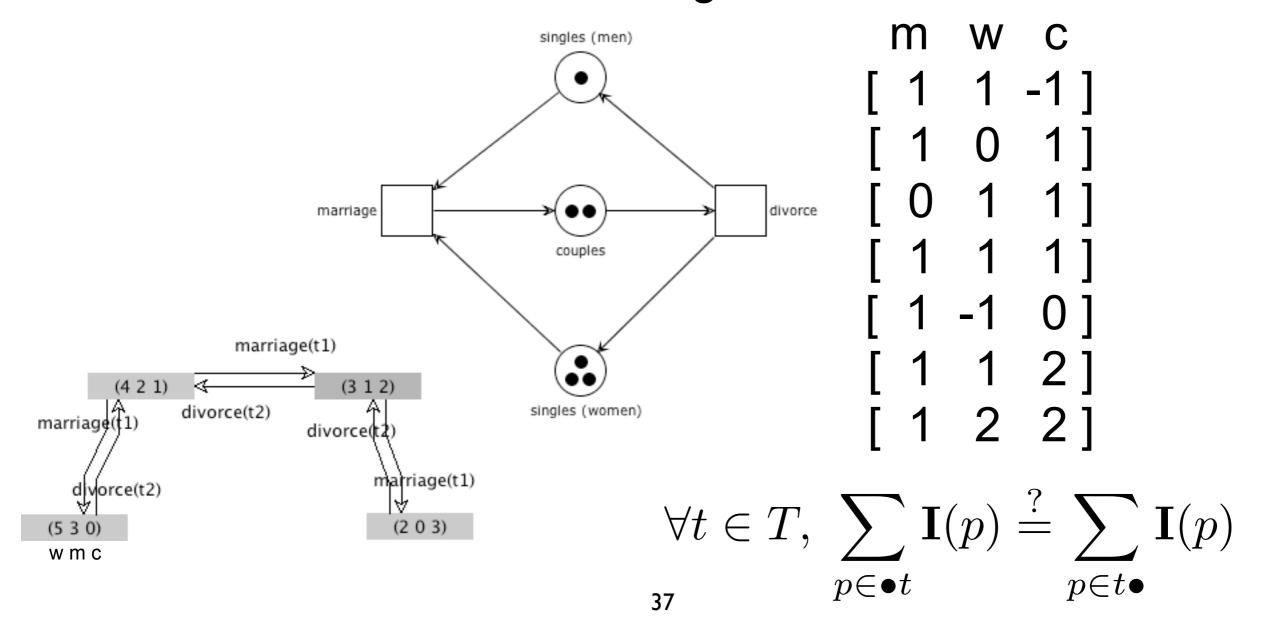
Very useful in proving S-invariance!

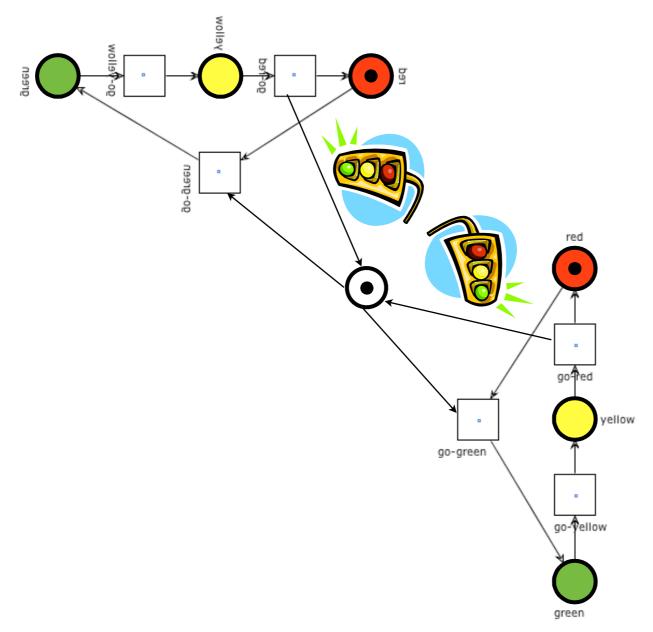
The check is possible without constructing the incidence matrix

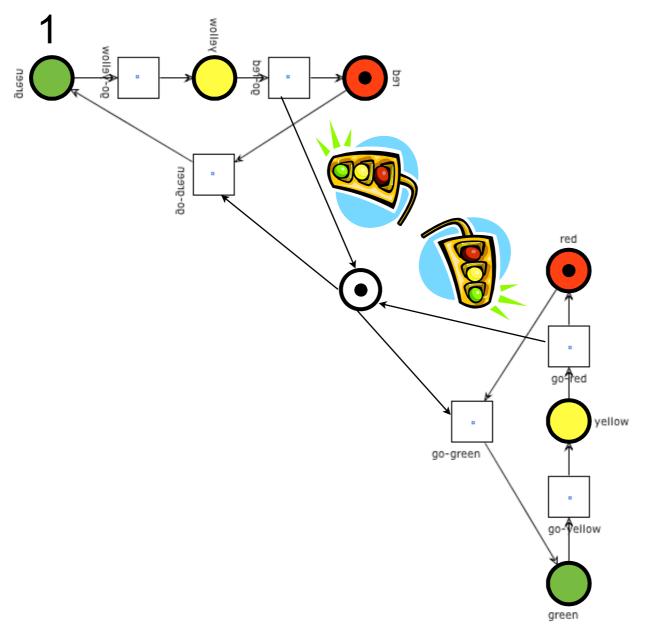
It can also help to build S-invariants directly over the picture

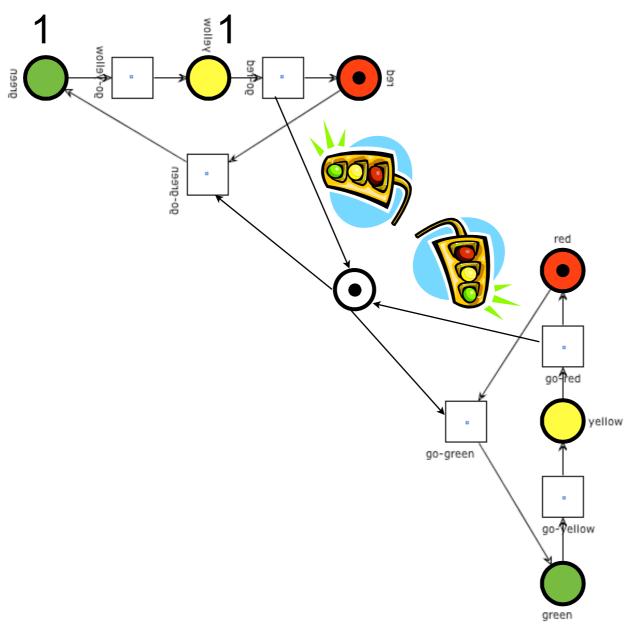
Question time

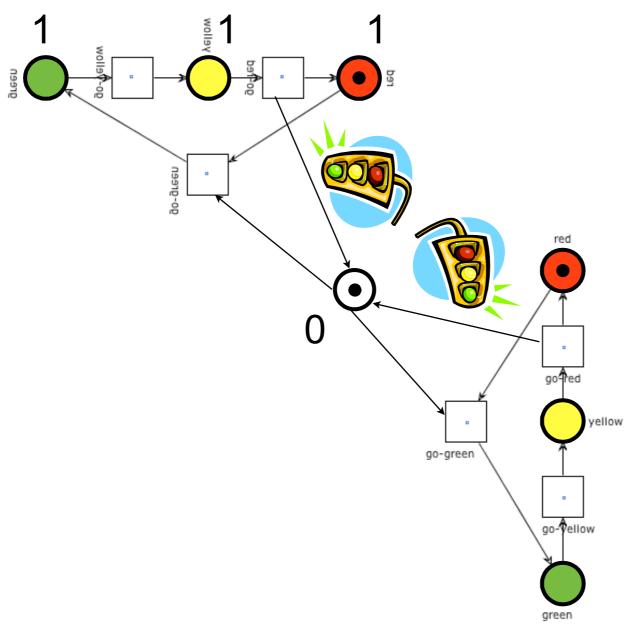
Which of the following are S-invariants?

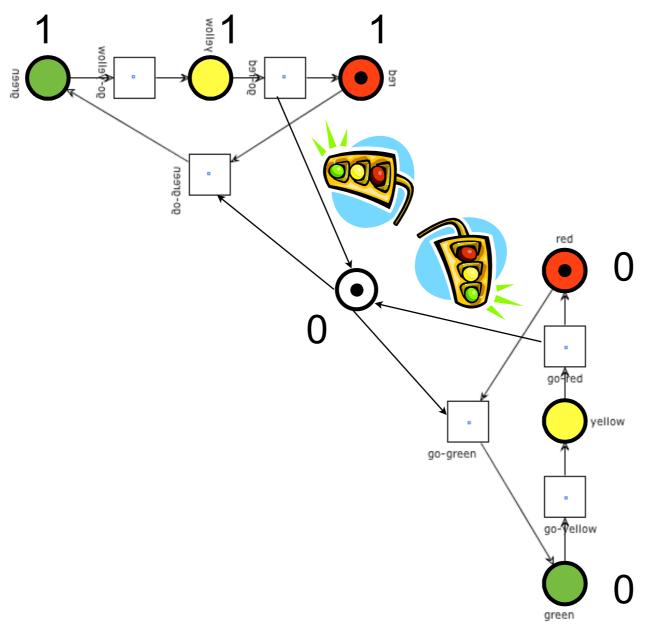


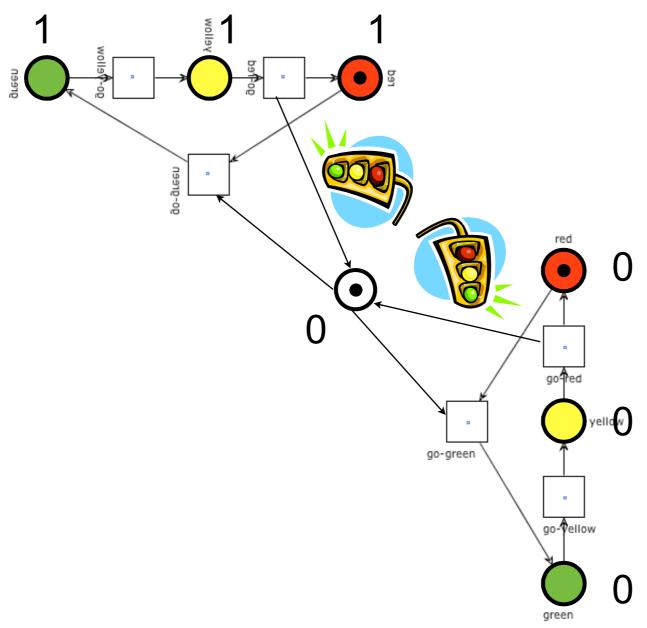


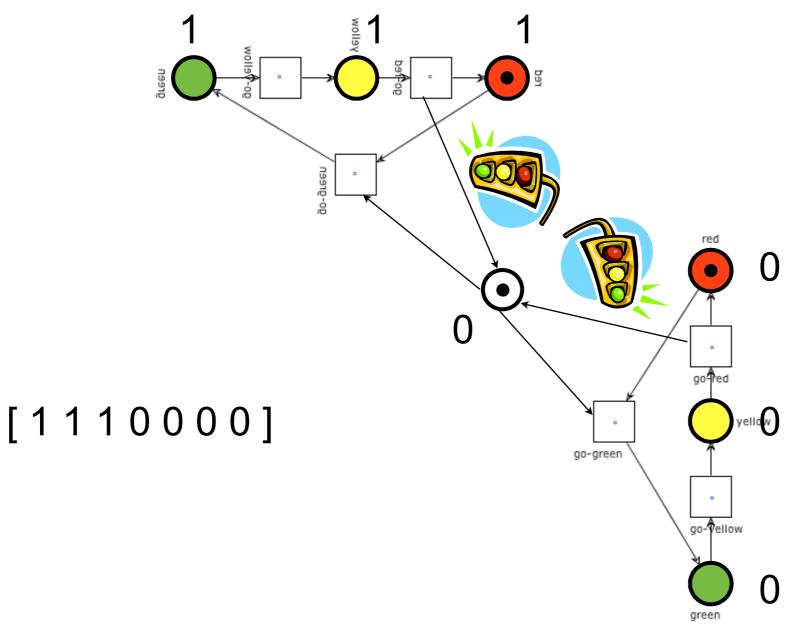


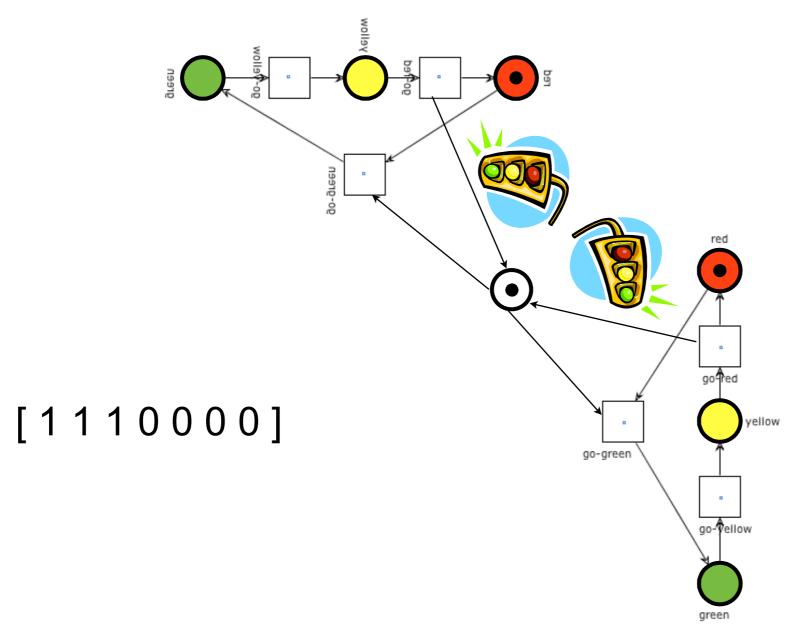


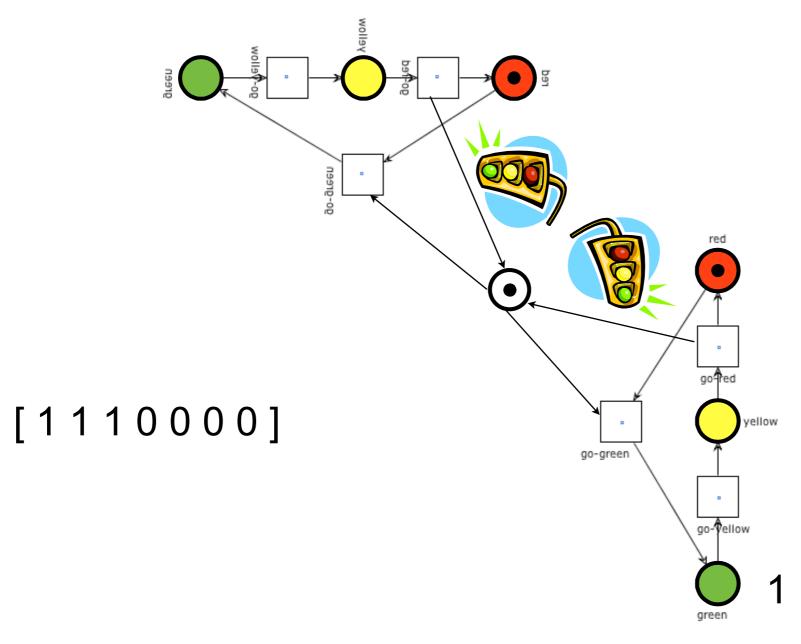


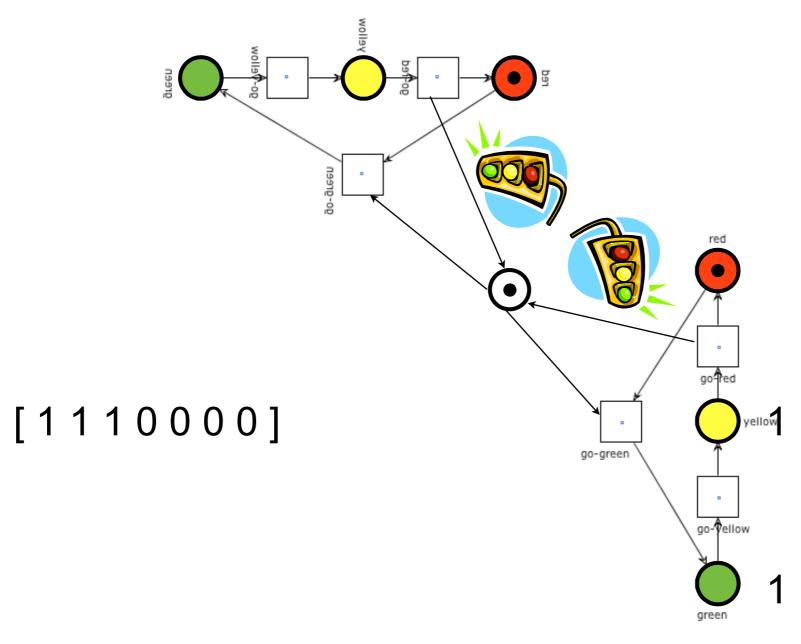


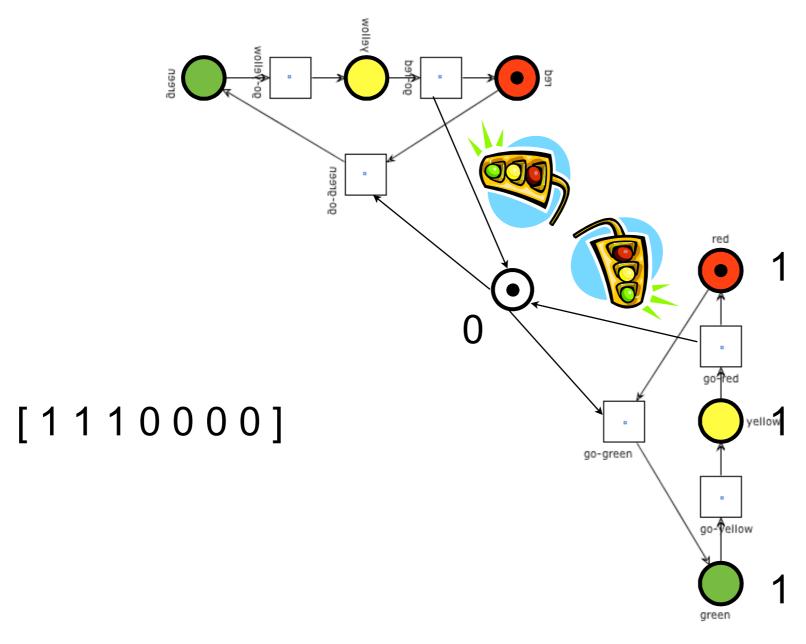


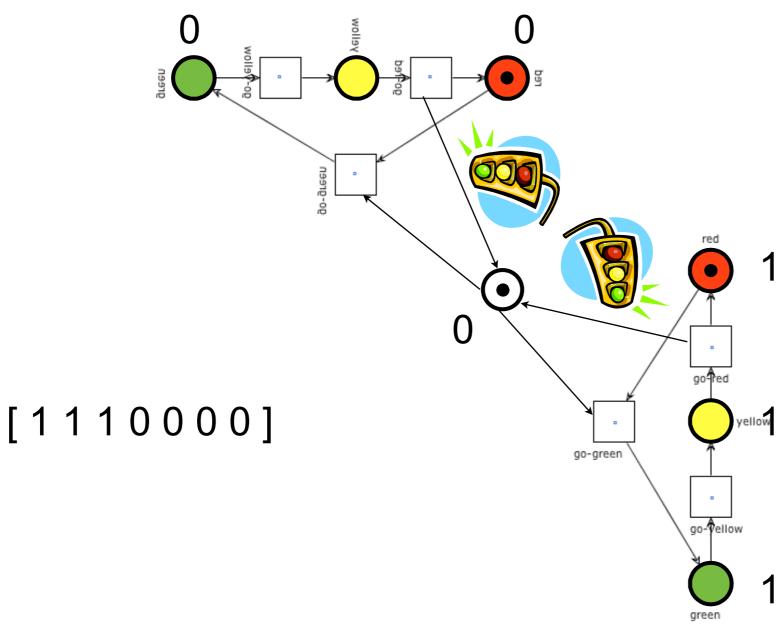


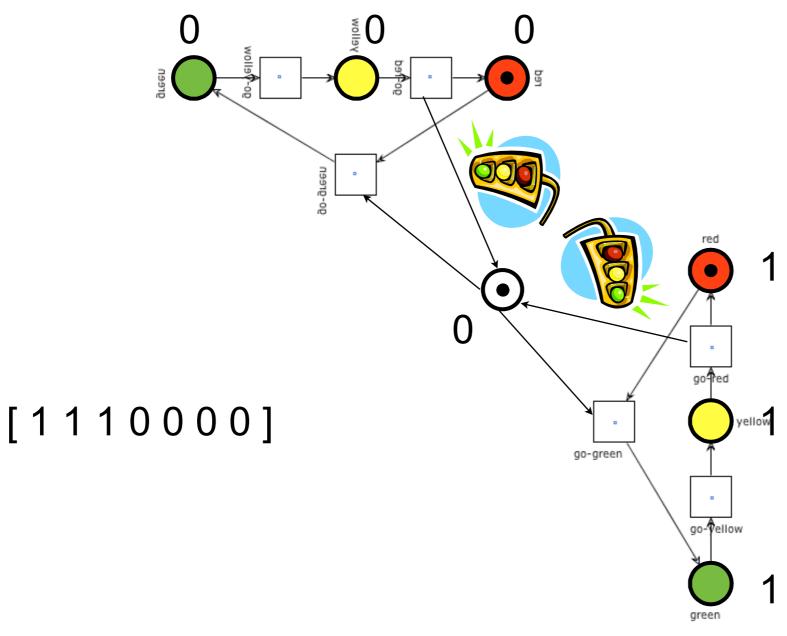


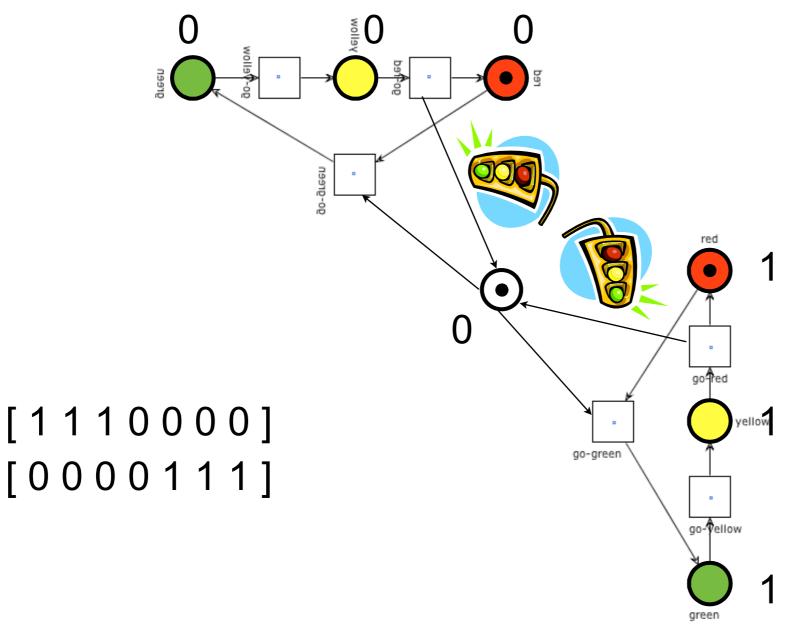


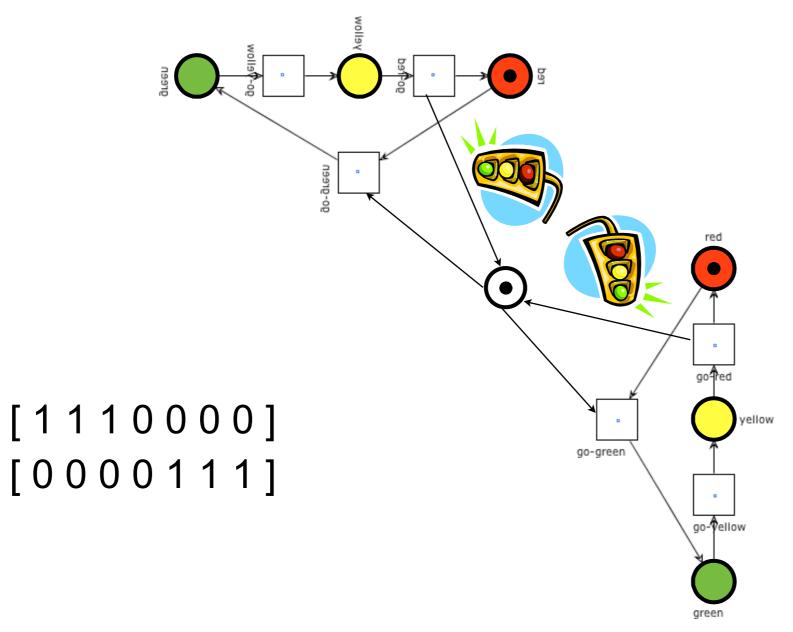


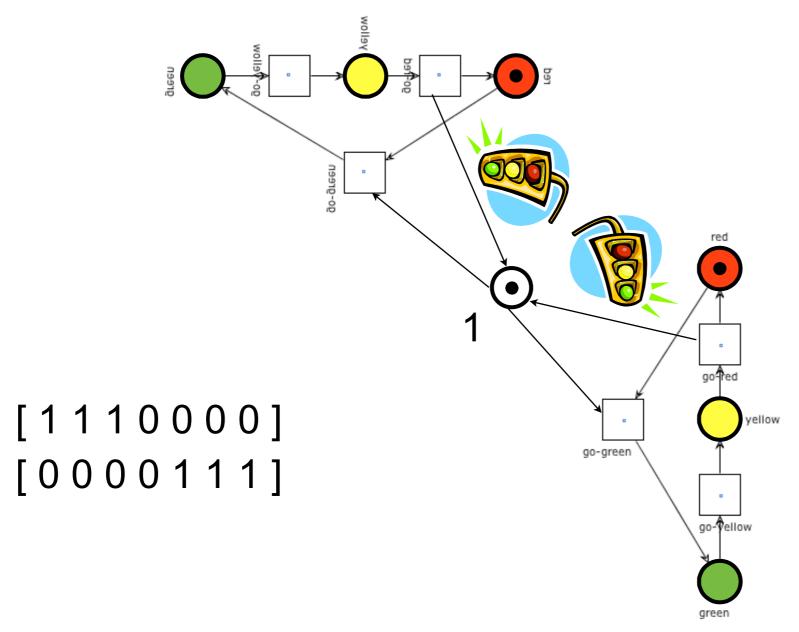


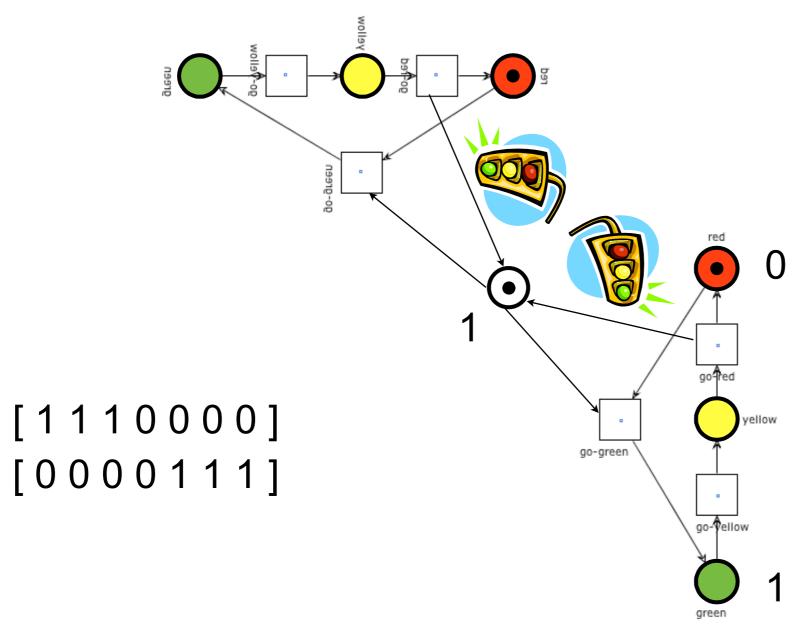


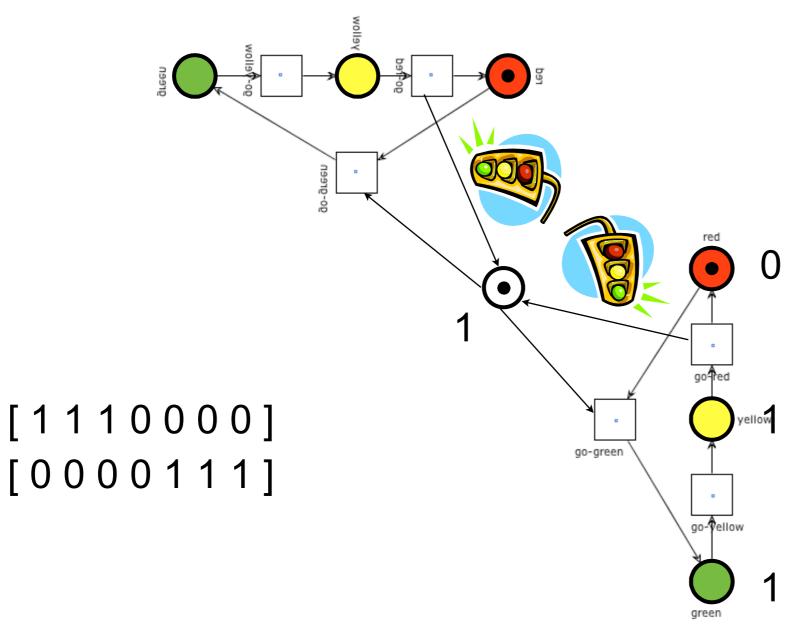


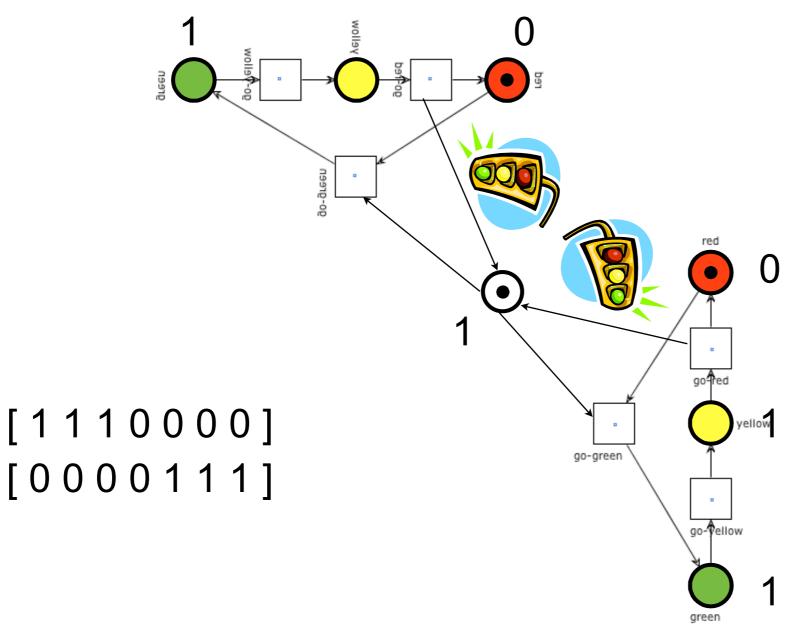


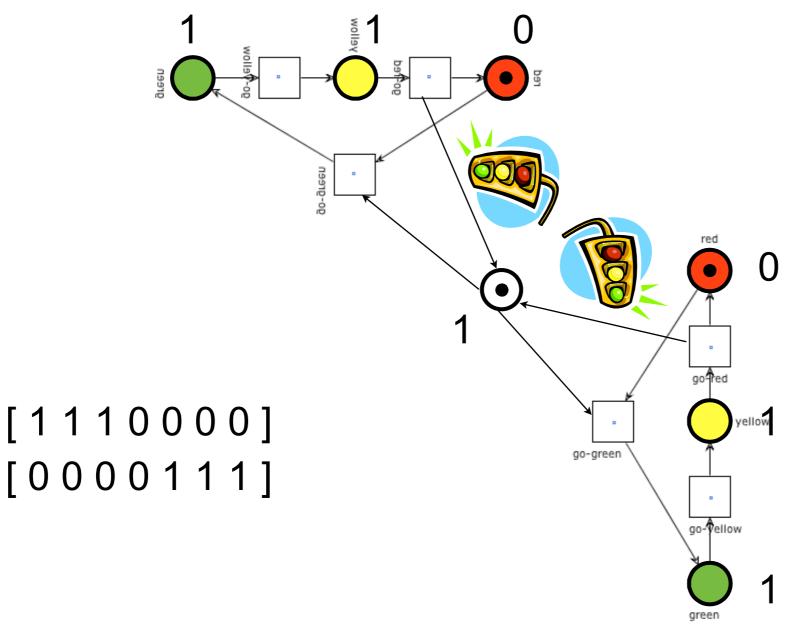


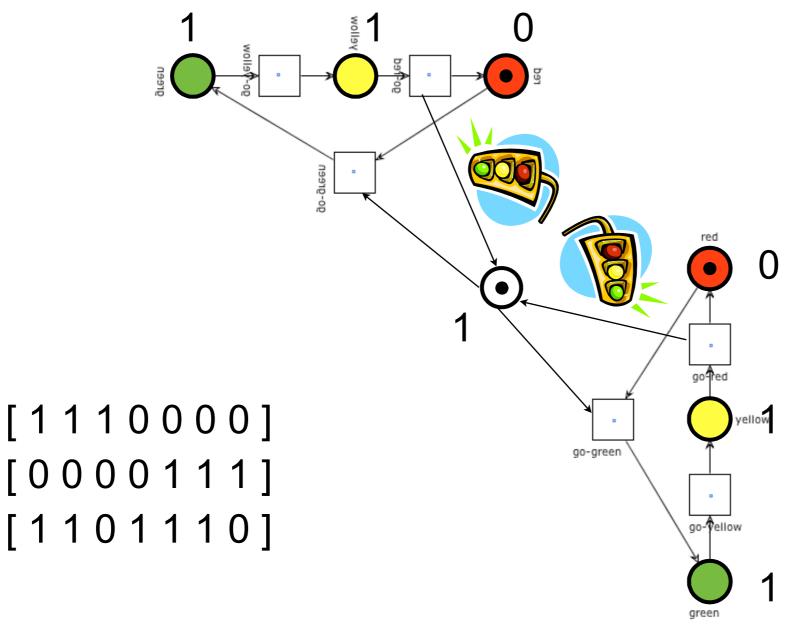


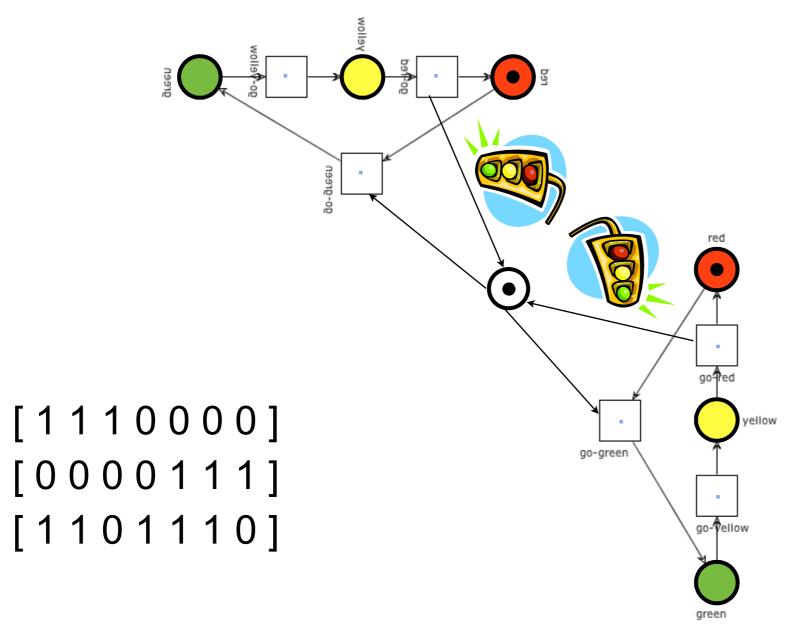


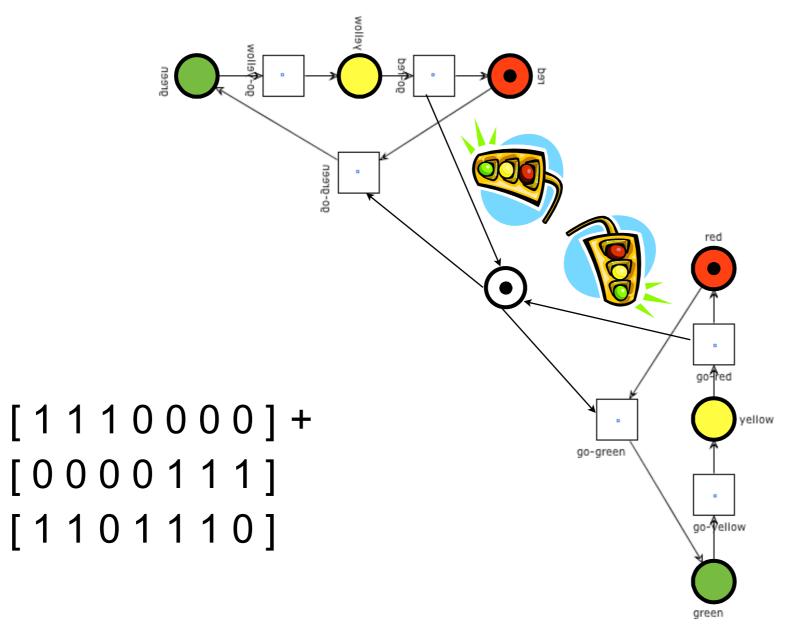


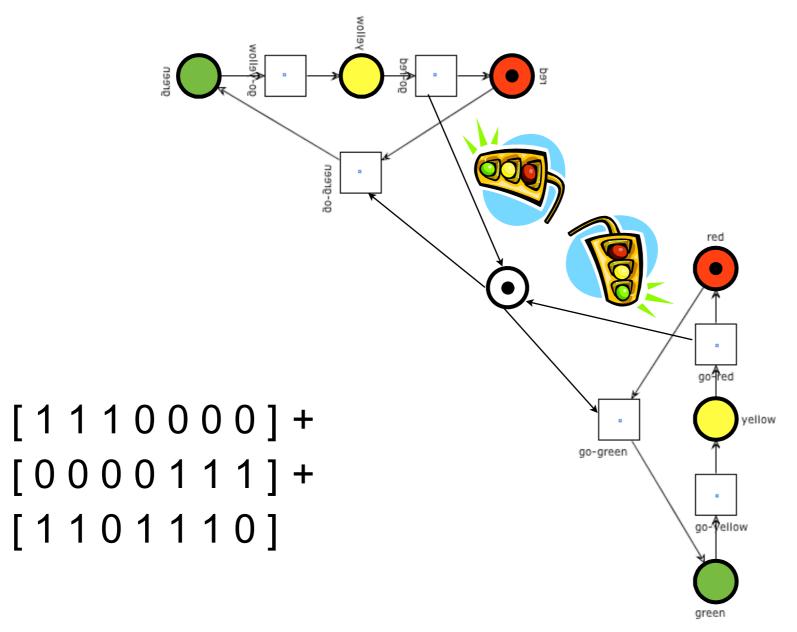


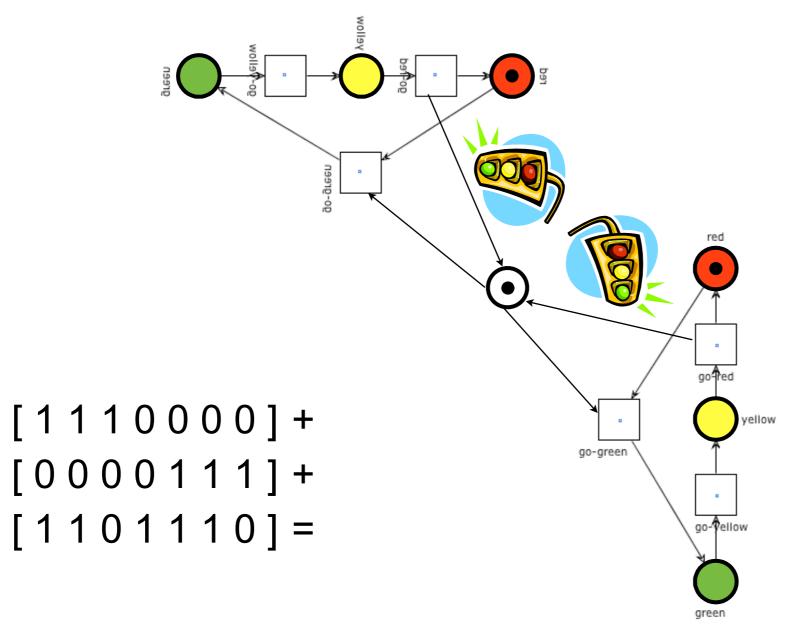


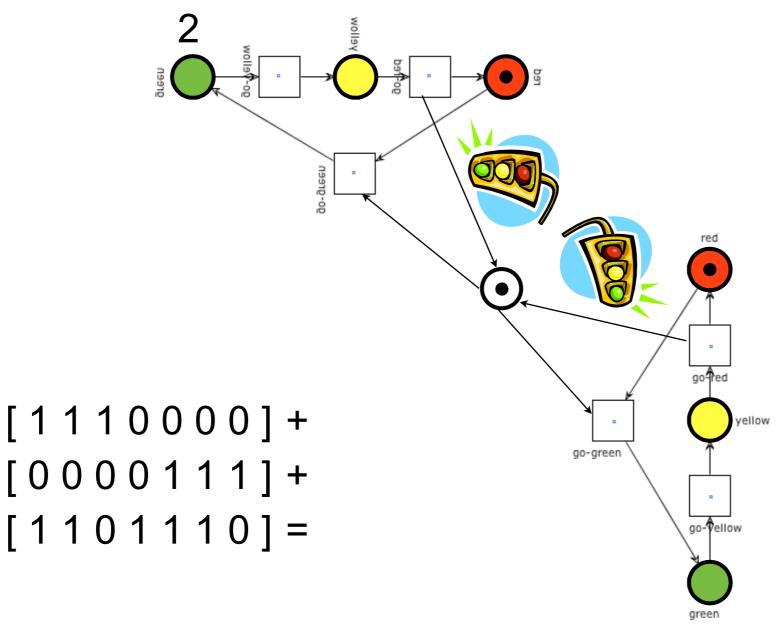


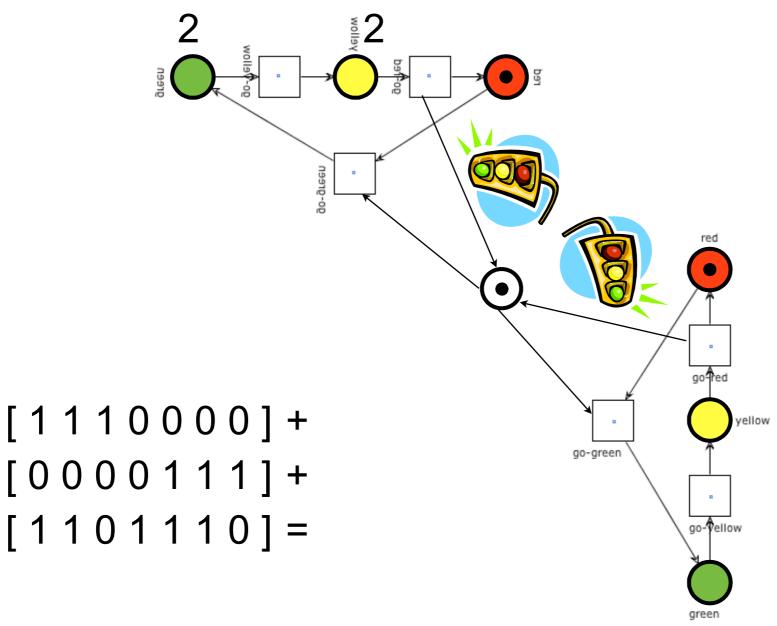


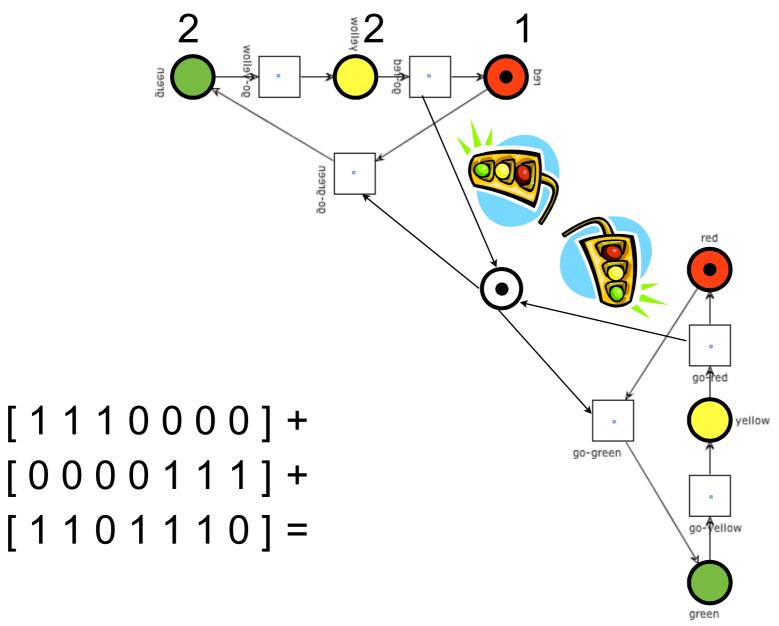


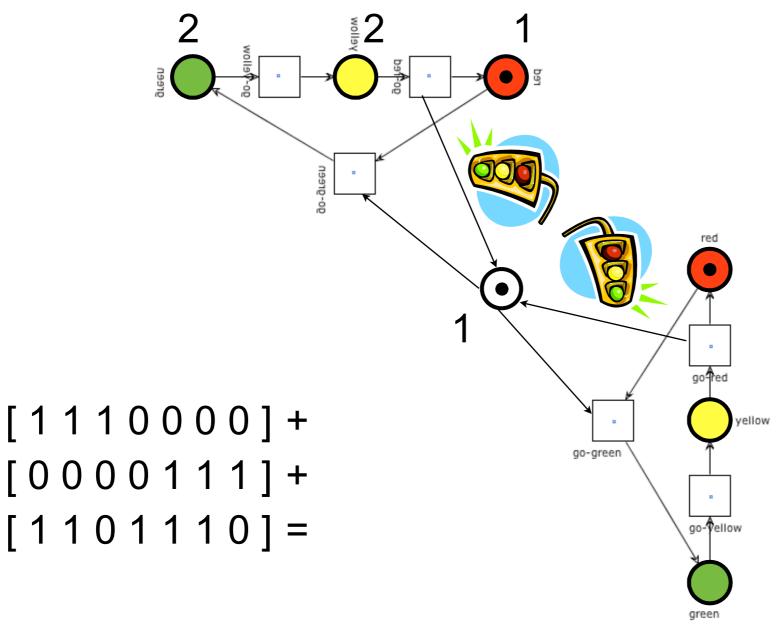


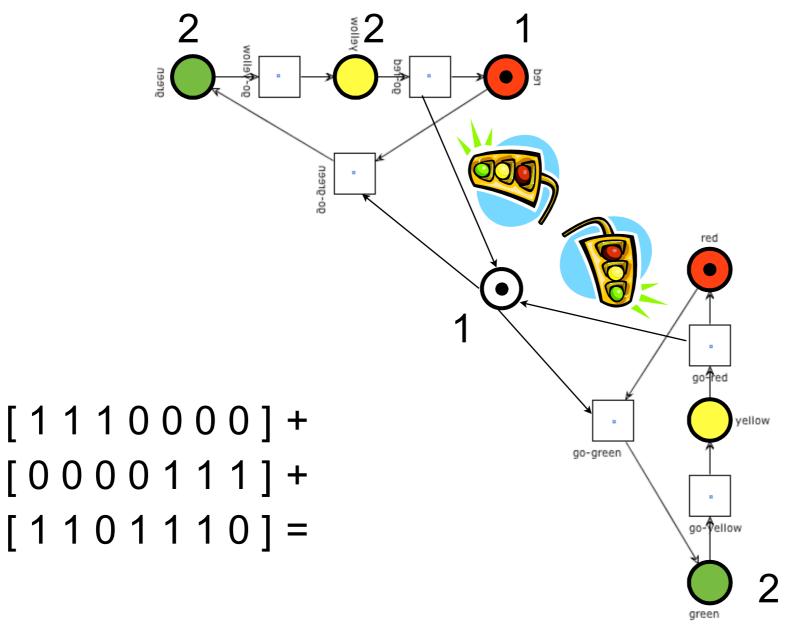




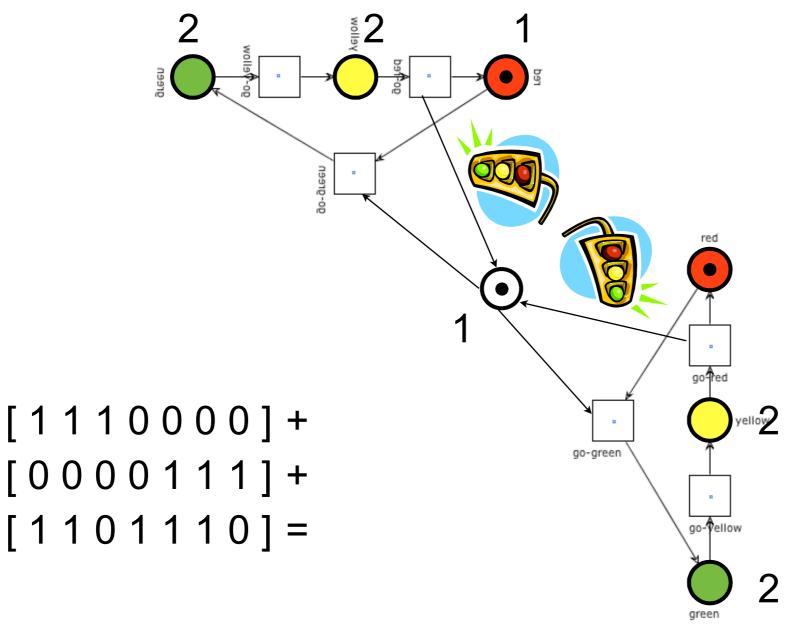




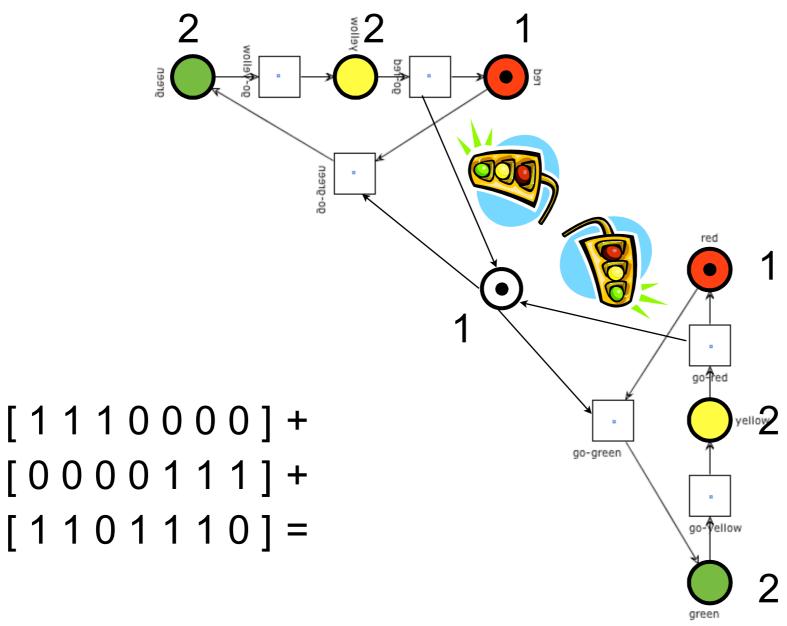




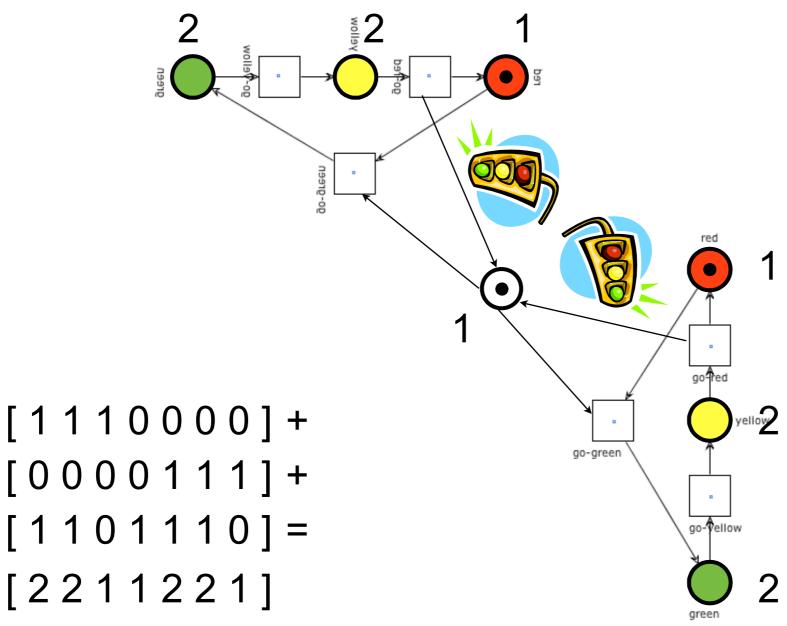
Traffic-lights example



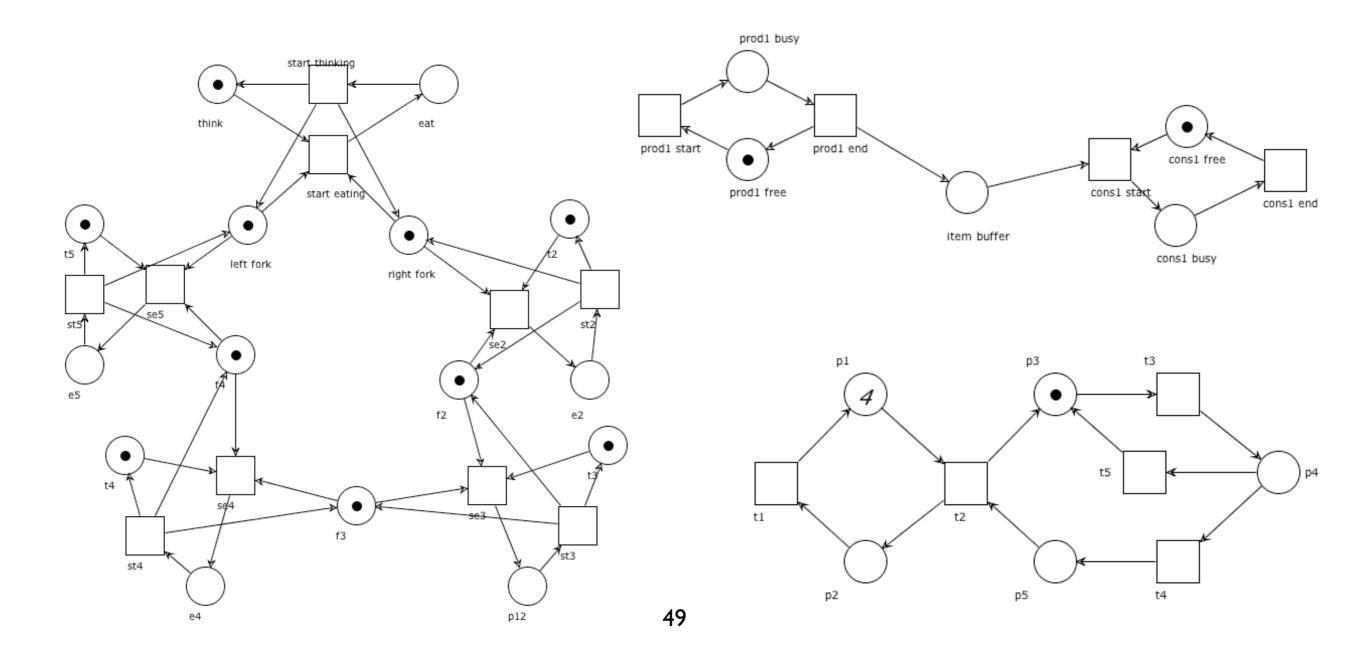
Traffic-lights example



Traffic-lights example



Define two (linearly independent) S-invariants for each of the nets below



S-invariants and system properties

Semi-positive S-invariants

```
The S-invariant I is semi-positive if I>0 (i.e. I\geq 0 and I\neq 0) all entries are non-negative and at least one is positive
```

The **support** of **I** is: $\langle \mathbf{I} \rangle = \{ p \mid \mathbf{I}(p) > 0 \}$

The S-invariant I is **positive** if $I \succ 0$ all entries are positive (i.e. I(p) > 0 for any place $p \in P$) (i.e. $\langle I \rangle = P$)

A (semi-positive) S-invariant whose coefficients are all 0 and 1 is called **uniform**

Note

Notation:
$$\bullet S = \bigcup_{s \in S} \bullet s$$

Every semi-positive invariant satisfies the equation

transitions that produce tokens in some places of the support

$$ullet \langle \mathbf{I}
angle = \langle \mathbf{I}
angle ullet$$

pre-sets of support equal post-sets of support

(the result holds for both S-invariant and T-invariant)

A sufficient condition for boundedness

Theorem:

If (P, T, F, M_0) has a positive S-invariant then it is bounded

Let $M \in [M_0]$ and let **I** be a positive S-invariant.

Let
$$p \in P$$
. Then $\mathbf{I}(p)M(p) \leq \mathbf{I} \cdot M = \mathbf{I} \cdot M_0$

Since I is positive, we can divide by I(p):

$$M(p) \leq (\mathbf{I} \cdot M_0)/\mathbf{I}(p)$$

$$\mathbf{I} \cdot M = \sum_{q \in P} \mathbf{I}(q) M(q)$$

Consequences of previous theorem

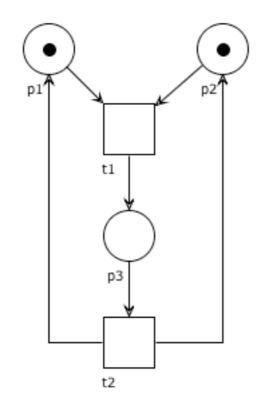
By exhibiting a positive S-invariant we can prove that the system is **bounded for any initial marking**

Note that all places in the support of a semi-positive S-invariant are **bounded for any initial marking**

$$M(p) \leq \frac{\mathbf{I} \cdot M_0}{\mathbf{I}(p)} \quad \text{this value is independent from the reachable marking M}$$

Example

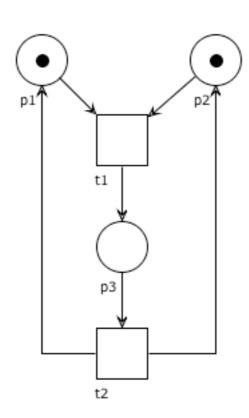
To prove that the system is bounded we can just exhibit a positive S-invariant



$$I = [1 \ 1 \ 2]$$

Example

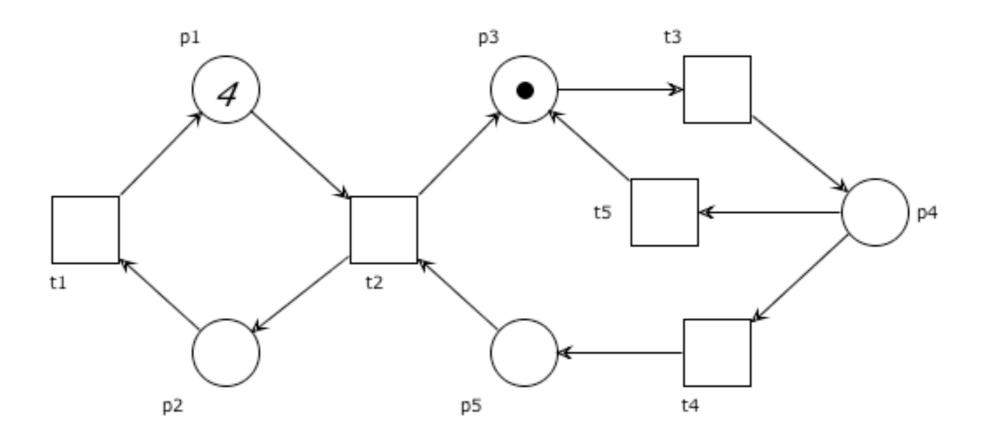
How many tokens are at most in p₃?



$$I = [1 \ 1 \ 2]$$

$$\frac{\mathbf{I} \cdot M_0}{\mathbf{I}(p_3)} = \frac{2}{2} = 1$$

Find a positive S-invariant for the net below



A necessary condition for liveness

Theorem:

If (P, T, F, M_0) is live then for every semi-positive invariant I:

$$\mathbf{I} \cdot M_0 > 0$$

Let $p \in \langle \mathbf{I} \rangle$ and take any $t \in \bullet p \cup p \bullet$.

By liveness, there are $M, M' \in [M_0]$ with $M \stackrel{t}{\longrightarrow} M'$

Then, M(p) > 0 (if $t \in p \bullet$) or M'(p) > 0 (if $t \in \bullet p$)

If
$$M(p) > 0$$
, then $\mathbf{I} \cdot M \ge \mathbf{I}(p)M(p) > 0$
If $M'(p) > 0$, then $\mathbf{I} \cdot M' \ge \mathbf{I}(p)M'(p) > 0$

In any case,
$$\mathbf{I} \cdot M_0 = \mathbf{I} \cdot M = \mathbf{I} \cdot M' > 0$$

$$\mathbf{I} \cdot M = \sum_{q \in P} \mathbf{I}(q) M(q)$$

Consequence of previous theorem

If we find a semi-positive invariant such that

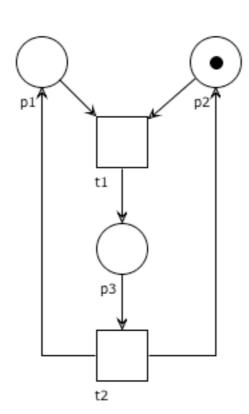
$$\mathbf{I} \cdot M_0 = 0$$

Then we can conclude that the system is not live

Example

the system is not live

It is immediate to check the counter-example



$$\begin{bmatrix} 1 & 0 & 1 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \end{bmatrix} = 0$$

$$\begin{bmatrix} 1 & 0 & 1 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \end{bmatrix} = M_0$$

Markings that agree on all S-invariant

Definition: M and M' agree on all S-invariants if for every S-invariant I we have I·M = I·M'

Note: by properties of linear algebra, this corresponds to require that the equation on \mathbf{y} M + $\mathbf{N} \cdot \mathbf{y}$ = M' has some rational-valued solution

Remark: In general, there can exist M and M' that agree on all S-invariants but such that none of them is reachable from the other

A necessary condition for reachability

Reachability is decidable, but computationally expensive (EXPSPACE-hard)

S-invariants provide a preliminary check that can be computed efficiently

Let (P, T, F, M_0) be a system.

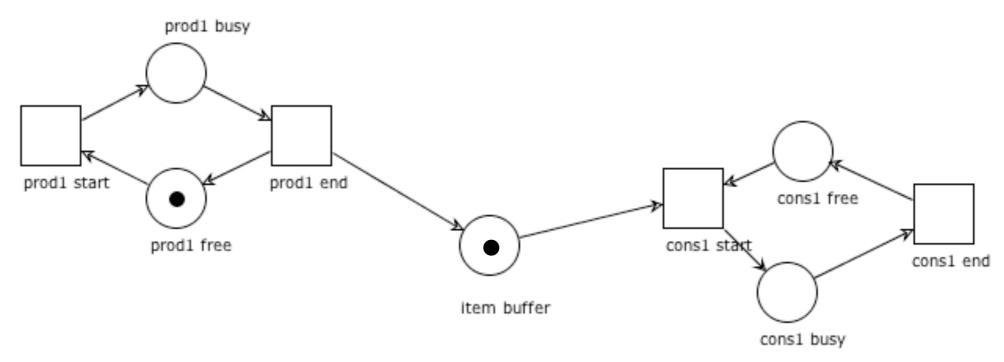
If there is an S-invariant I s.t. $\mathbf{I} \cdot M \neq \mathbf{I} \cdot M_0$ then $M \notin [M_0]$

If the equation $\mathbf{N} \cdot \mathbf{y} = M - M_0$ has no rational-valued solution, then $M \notin [M_0]$

Example

Prove that the marking

M = prod1free + cons1busy
is not reachable



$$I = [0 \ 0 \ 0 \ 1 \ 1]$$

 $I \cdot M_0 = 0 \ne 1 = I \cdot M$

S-invariants: recap

Positive S-invariant Unboundedness

=> boundedness => no positive S-invariant

Semi-positive S-invariant I and liveness => $I \cdot M_0 > 0$ Semi-positive S-invariant I and $I \cdot M_0 = 0$ => non-live

S-invariant I and M reachable S-invariant I and I·M \neq I·M₀

$$=> I \cdot M = I \cdot M_0$$

=> M not reachable

S-invariants: pay attention to implication

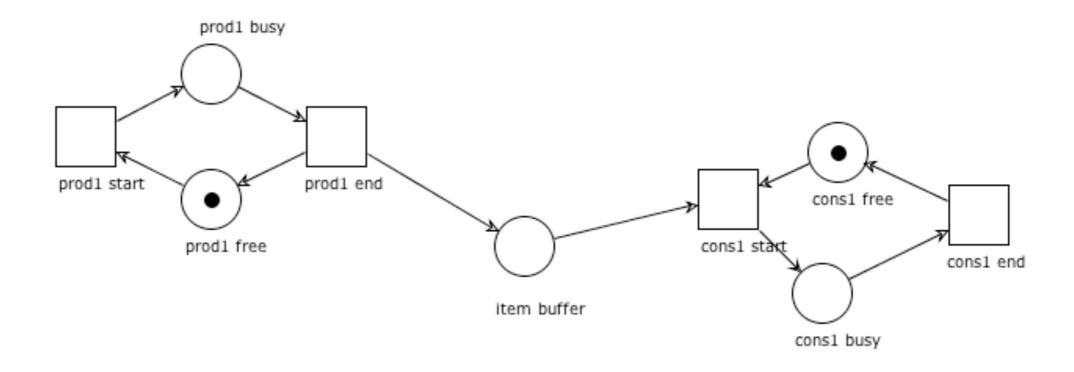
No positive S-invariant

=> maybe unbounded

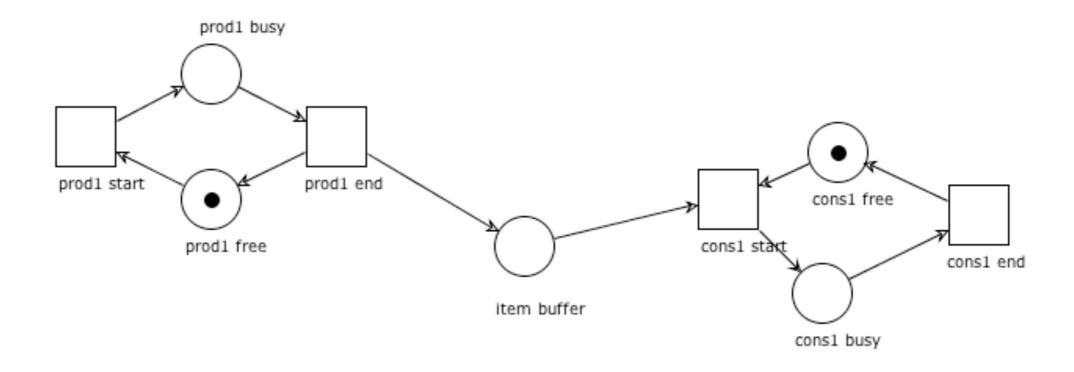
Semi-positive S-invariant I and $I \cdot M_0 > 0 => maybe$ live

S-invariant I and I·M = I·M₀ => maybe M reachable

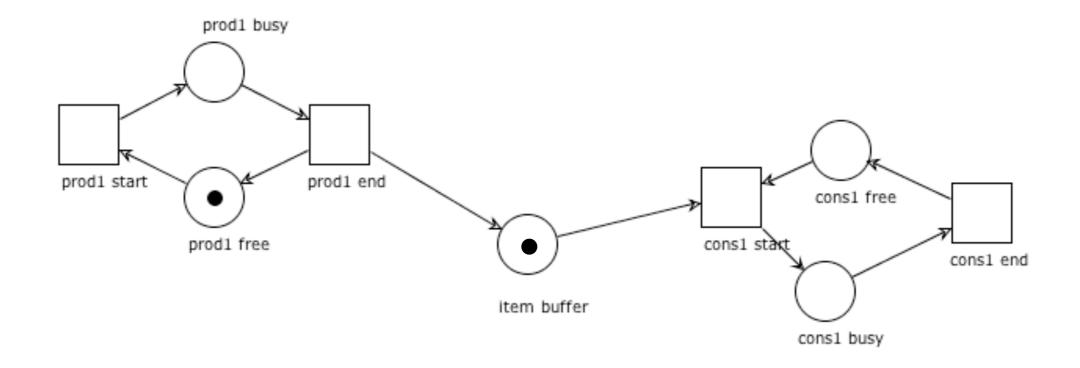
Can you find a positive S-invariant?



Can you find a positive S-invariant?



Prove that the system is not live by exhibiting a suitable S-invariant



T-invariants

Dual reasoning

The S-invariants of a net N are vectors satisfying the equation

$$\mathbf{x} \cdot \mathbf{N} = \mathbf{0}$$

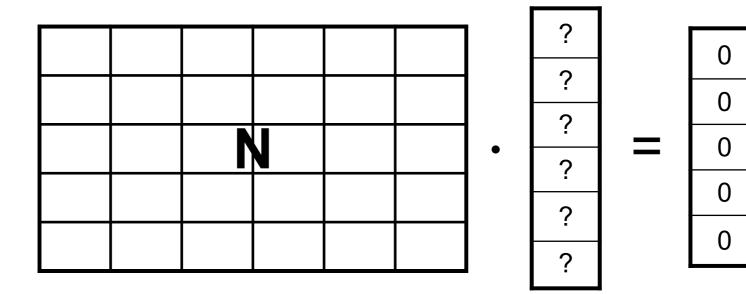
It seems natural to ask if we can find some interesting properties also for the vectors satisfying the equation

$$\mathbf{N} \cdot \mathbf{y} = \mathbf{0}$$

T-invariant (aka transition-invariant)

Definition: A **T-invariant** of a net N=(P,T,F) is a rational-valued solution **y** of the equation

$$\mathbf{N} \cdot \mathbf{y} = \mathbf{0}$$



Fundamental property of T-invariants

Proposition: Let $M \xrightarrow{\sigma} M'$.

The Parikh vector $\vec{\sigma}$ is a T-invariant iff M' = M

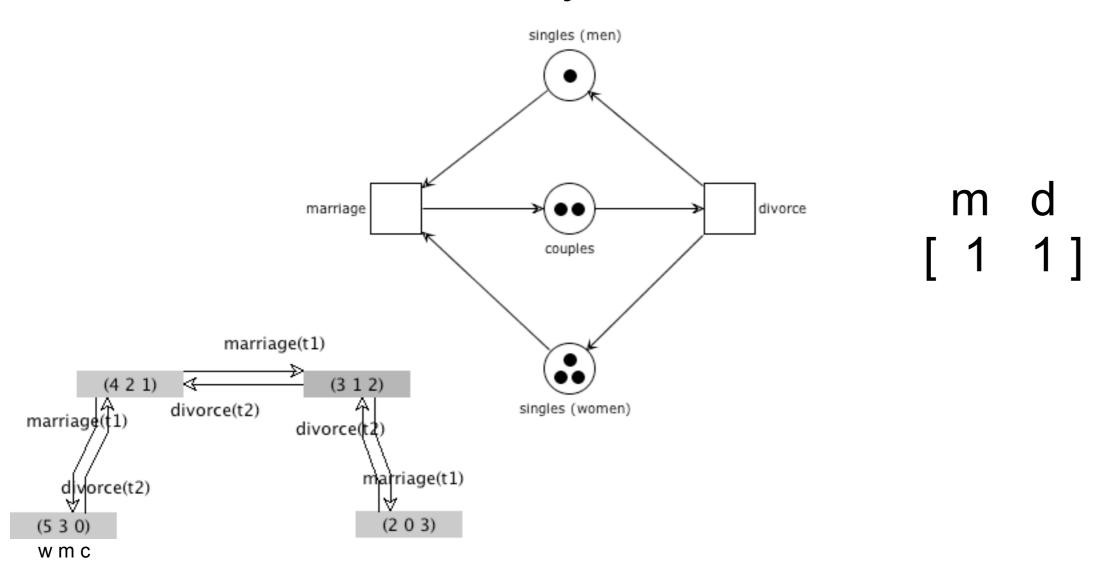
- \Rightarrow) By the marking equation lemma $M' = M + \mathbf{N} \cdot \vec{\sigma}$ Since $\vec{\sigma}$ is a T-invariant $\mathbf{N} \cdot \vec{\sigma} = \mathbf{0}$, thus M' = M.
- \Leftarrow) If $M \xrightarrow{\sigma} M$, by the marking equation lemma $M = M + \mathbf{N} \cdot \vec{\sigma}$ Thus $\mathbf{N} \cdot \vec{\sigma} = M - M = \mathbf{0}$ and $\vec{\sigma}$ is a T-invariant

Transition-invariant, intuitively

A transition-invariant assigns a **number of occurrences to each transition** such that any
occurrence sequence comprising exactly those
transitions leads to the same marking where it started
(independently from the order of execution)

Example

An easy-to-be-found T-invariant



Alternative definition of T-invariant

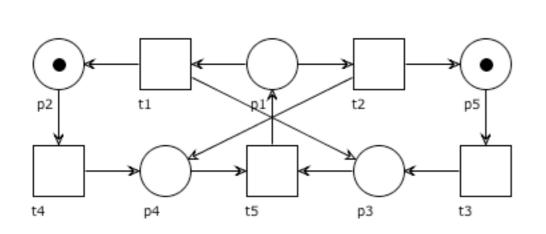
Proposition:

A mapping $\mathbf{J}:T\to\mathbb{Q}$ is a T-invariant of N iff for any $p\in P$:

$$\sum_{t \in \bullet p} \mathbf{J}(t) = \sum_{t \in p \bullet} \mathbf{J}(t)$$

Question time

Which of the following are T-invariants?



$$\forall p \in P, \ \sum_{t \in \bullet p} \mathbf{J}(t) \stackrel{?}{=} \sum_{t \in p \bullet} \mathbf{J}(t)$$

T-invariants and system properties

Pigeonhole principle

If n items are put into m slots, with n > m, then at least one slot must contain more than one item



Reproduction lemma

Lemma: Let (P, T, F, M_0) be a bounded system.

If $M_0 \xrightarrow{\sigma}$ for some infinite sequence σ , then there is a semi-positive T-invariant \mathbf{J} such that $\langle \mathbf{J} \rangle \subseteq \{ t \mid t \in \sigma \}$.

Assume $\sigma = t_1 \ t_2 \ t_3 \dots$ and $M_0 \xrightarrow{t_1} M_1 \xrightarrow{t_2} M_2 \xrightarrow{t_3} \dots$

By boundedness: $\lceil M_0 \rangle$ is finite.

By the pigeonhole principle, there are $0 \le i < j$ s.t. $M_i = M_j$ Let $\sigma' = t_{i+1}...t_j$. Then $M_i \xrightarrow{\sigma'} M_j = M_i$

By the marking equation lemma: $\vec{\sigma'}$ is a T-invariant. (fund. prop. of T-inv.) It is semi-positive, because σ' is not empty (i < j). Clearly, $\langle \mathbf{J} \rangle$ only includes transitions in σ .

Boundedness, liveness and positive T-invariant

Theorem: If a bounded system is live, then it has a positive T-invariant

By boundedness: $[M_0]$ is finite and we let $k = |[M_0]|$.

By liveness: $M_0 \xrightarrow{\sigma_1} M_1$ with $\vec{\sigma_1}(t) > 0$ for any $t \in T$

Similarly: $M_1 \xrightarrow{\sigma_2} M_2$ with $\vec{\sigma_2}(t) > 0$ for any $t \in T$

Similarly: $M_0 \xrightarrow{\sigma_1} M_1 \xrightarrow{\sigma_2} M_2 \dots \xrightarrow{\sigma_k} M_k$

By the pigeonhole principle, there are $0 \le i < j \le k$ s.t. $M_i = M_j$ Let $\sigma = \sigma_{i+1}...\sigma_j$. Then $M_i \xrightarrow{\sigma} M_j = M_i$

By the marking equation lemma: $\vec{\sigma}$ is a T-invariant. (fund. prop. of T-inv.) It is positive, because $\vec{\sigma}(t) \geq \vec{\sigma_j}(t) > 0$ for any $t \in T$.

Corollary of previous theorem

Every live and bounded system has:

a reachable marking M and an occurrence sequence $M \stackrel{\sigma}{\longrightarrow} M$

such that all transitions of N occur in σ .

T-invariants: recap

Boundedness + liveness => positive T-invariant

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No positive T-invariant => non (live + bounded)
No positive T-invariant => non-live OR unbounded
No positive T-invariant + liveness => unbounded
No positive T-invariant + boundedness => non-live
No positive T-inv. + positive S-inv. => non-live
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T-invariants: pay attention to implication

No positive T-invariant

=> maybe non live

Exhibit a system that has a positive T-invariant but is not live and bounded

Exhibit a live system that has a positive T-invariant but is not bounded