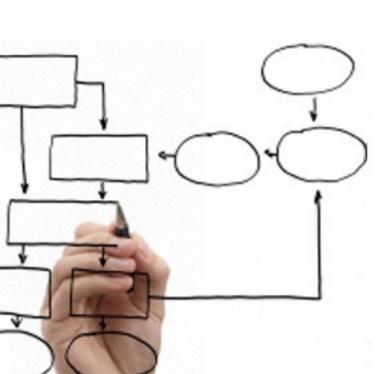
Methods for the specification and verification of business processes MPB (6 cfu, 295AA)



Roberto Bruni

http://www.di.unipi.it/~bruni

19 - Diagnosis for WF nets

Object







We study suitable diagnosis techniques for unsound Workflow nets

Diagnosing workflow processes using Woflan (article, optional reading)
http://wwwis.win.tue.nl/~wvdaalst/publications/p135.pdf

Some Pragmatic Considerations

We know that, for free-choice nets, liveness and boundedness can be decided efficiently (in polynomial time)

but we want to check soundness for a wider range of nets

Moreover, when a process is not sound, some diagnostic can be generated that indicates why it is flawed

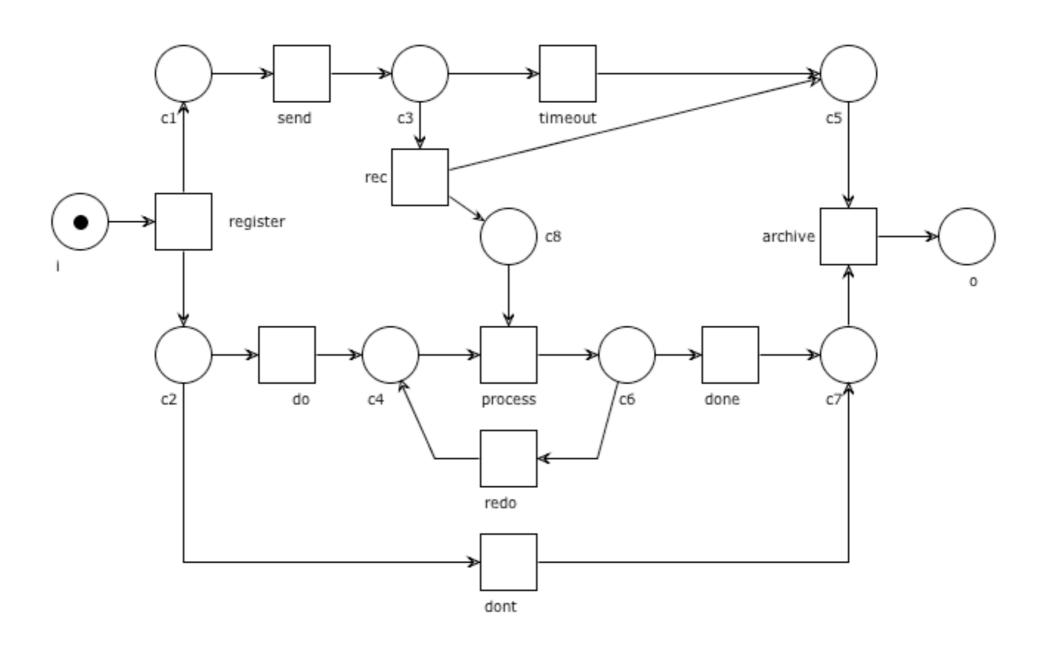
Woflan (now a ProM plugin)

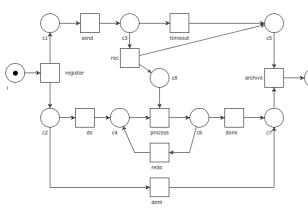


WOrkFLow ANalyzer (Windows only) http://www.win.tue.nl/woflan/

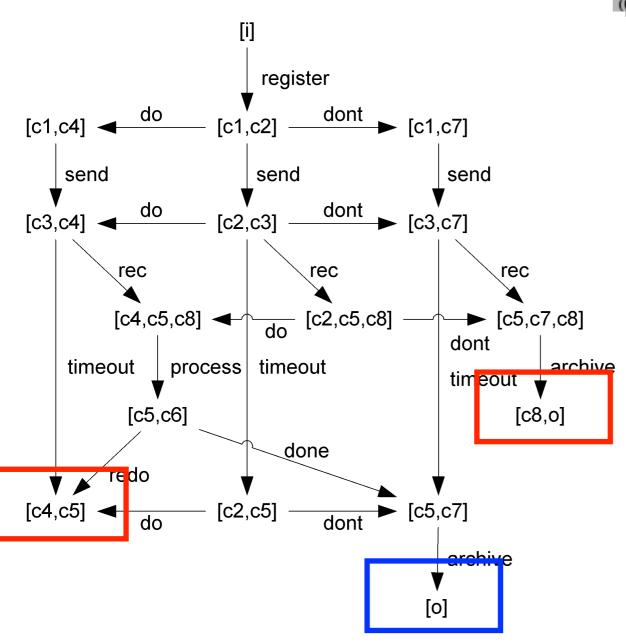
Woflan tells us if N is a sound workflow net (Is N a workflow net? Is N* bounded? Is N* live?) if not, provides some diagnostic information

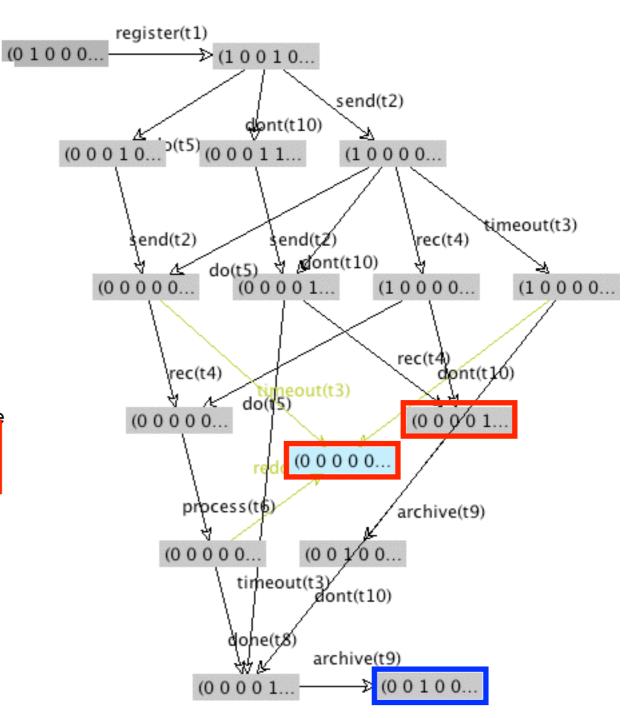
Running example



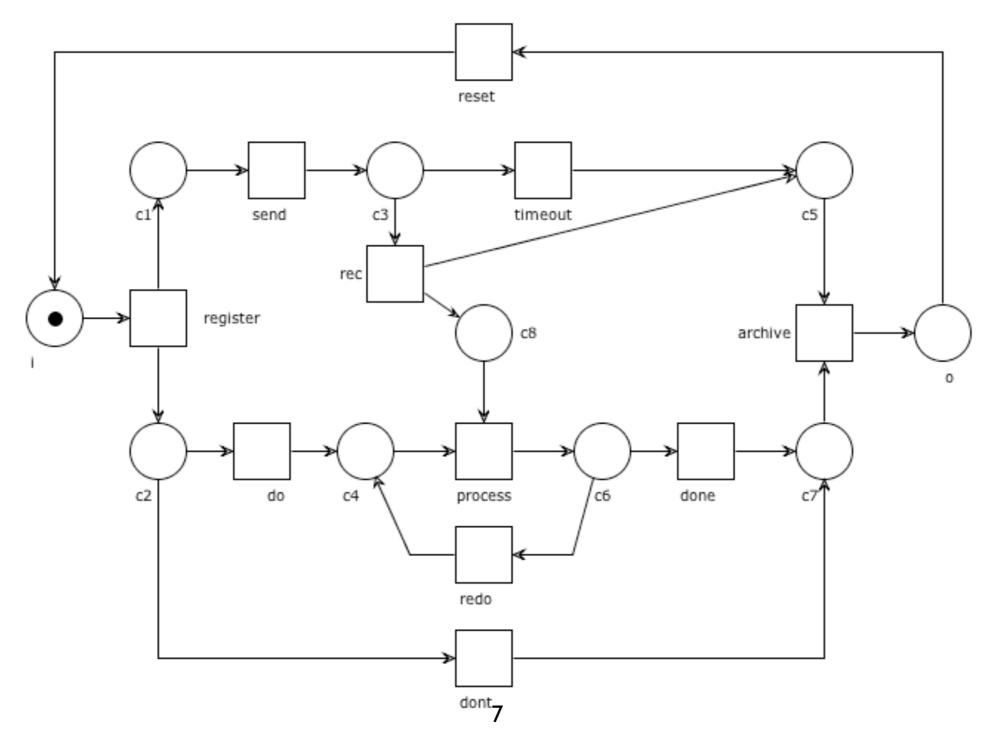


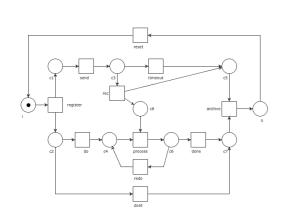
Running example



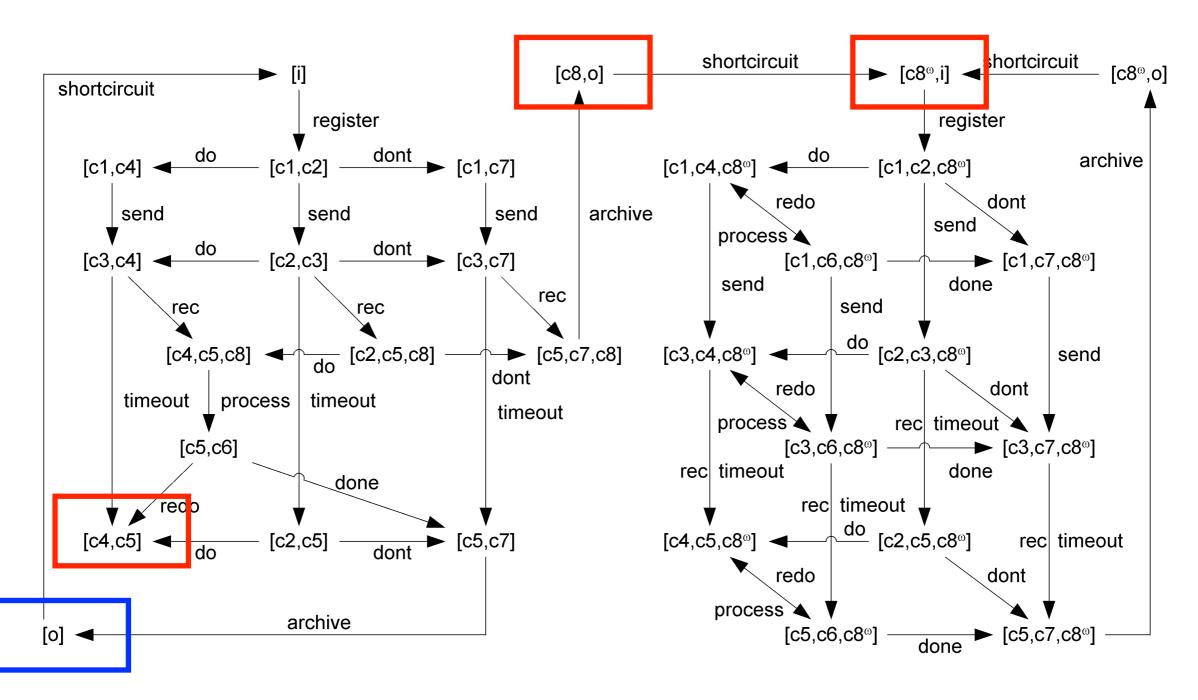


Running example: short-circuited





Running example: short-circuited



S-coverability diagnosis

Quick reminder

In a S-component, the total number of tokens in its places is constant

Any S-component induces a uniform invariant (weights 0 and 1)

A net is **S-coverable** iff any $p \in P$ belongs to some S-component

S-coverability implies boundedness (because it induces a positive S-invariant)

S-Invariant analysis

If every place of N* is covered by a semi-positive S-invariant then N* is bounded

Places not covered by semi-positive S-invariants are potential sources of problems

S-Coverability vs Soundness

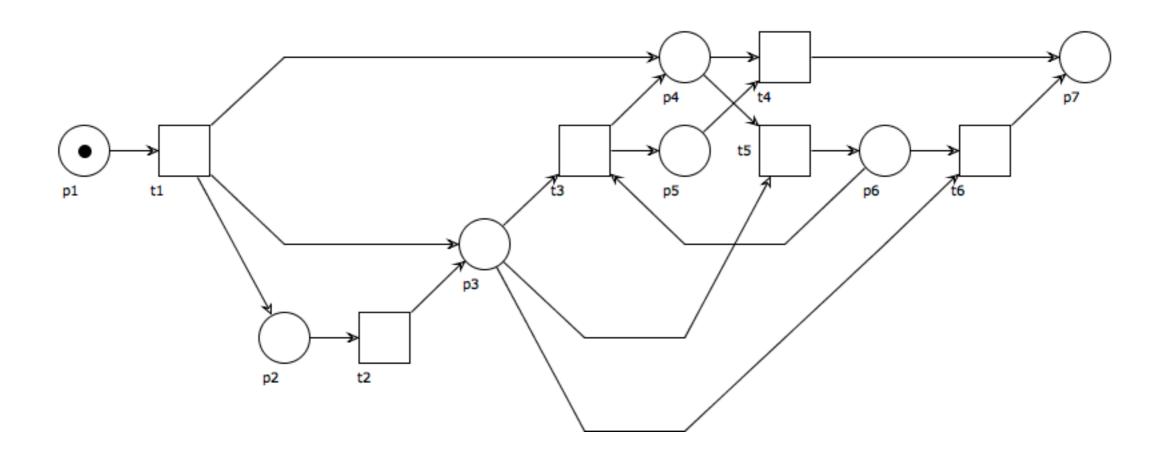
S-coverability is one of the basic requirements any workflow process definition should satisfy

Still:

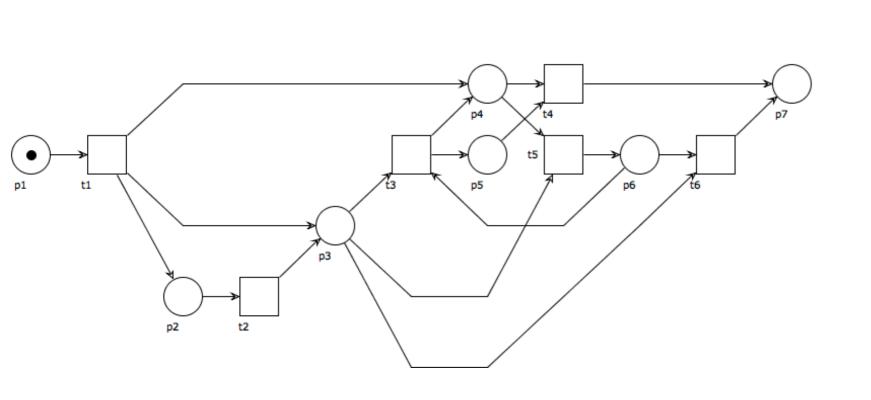
S-coverability is not a sufficient requirement for soundness N* can be S-coverable even if N is not sound

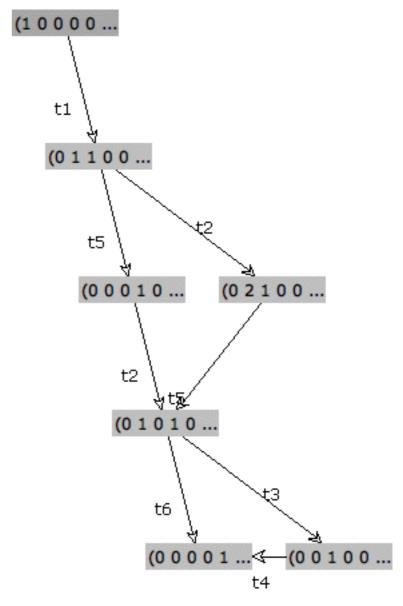
N can be sound even if N* is not S-coverable

Example: N sound but N* not S-coverable



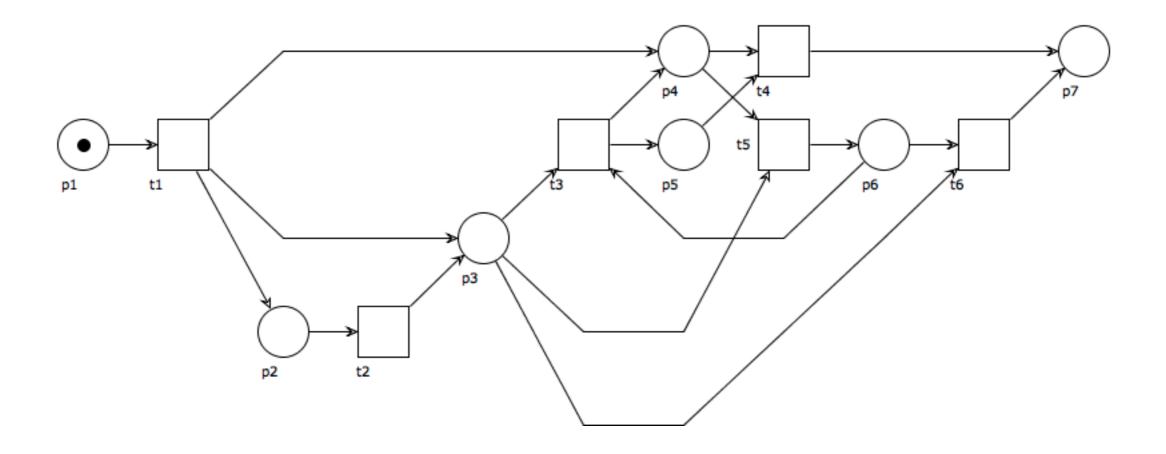
Example: N sound but N* not S-coverable





Exercises

Find all (maximal) S-components using WoPeD



Exercises

Draw a workflow net N that is S-coverable but such that N* is not live and bounded (i.e. N is not sound)

S-Coverability diagnosis

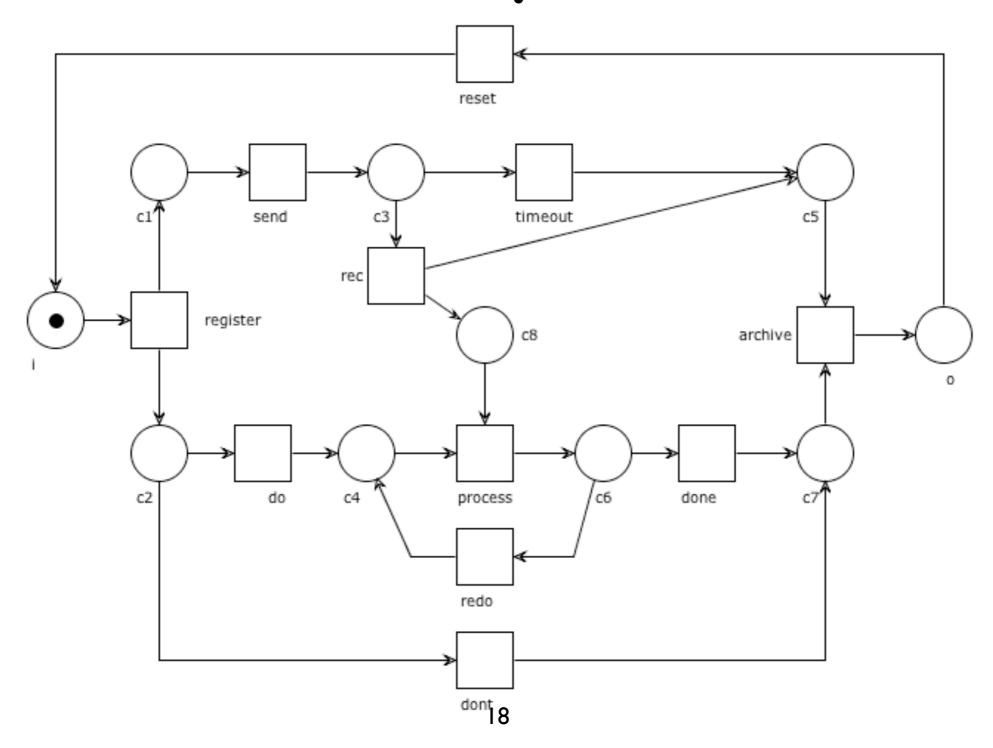
If N* is free-choice, live and bounded it must be S-coverable (S-coverability theorem)

(note that any S-component of N* includes i, o, reset, by strong-connectedness)

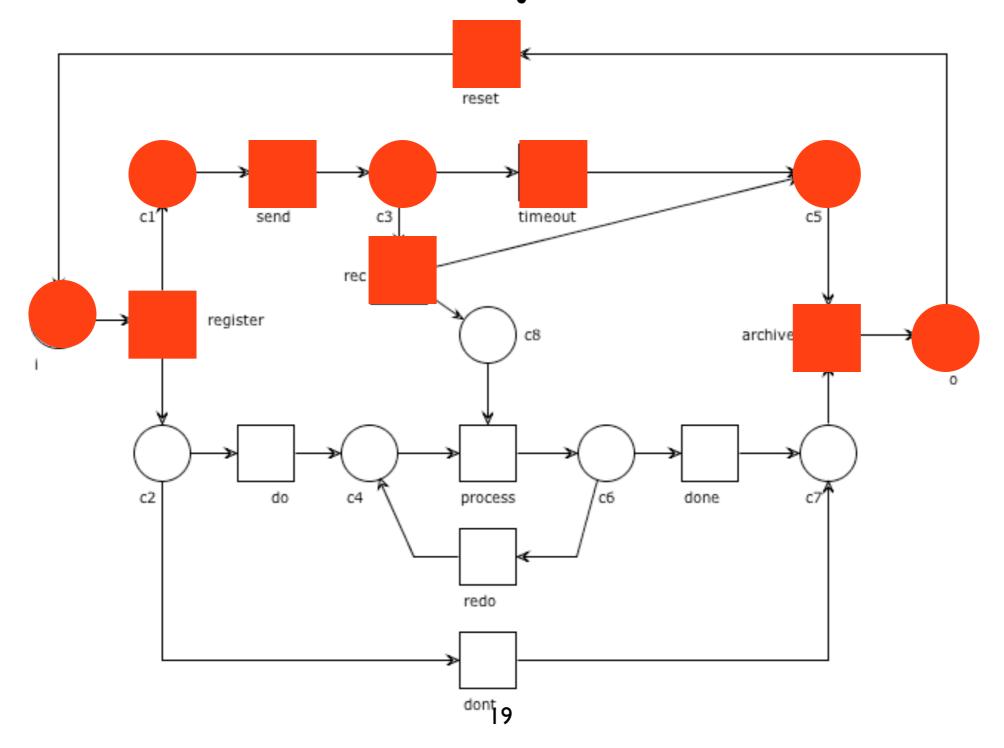
Corollary: If N is sound and free-choice, then N* must be S-coverable

N free-choice + N* not S-coverable => N not sound

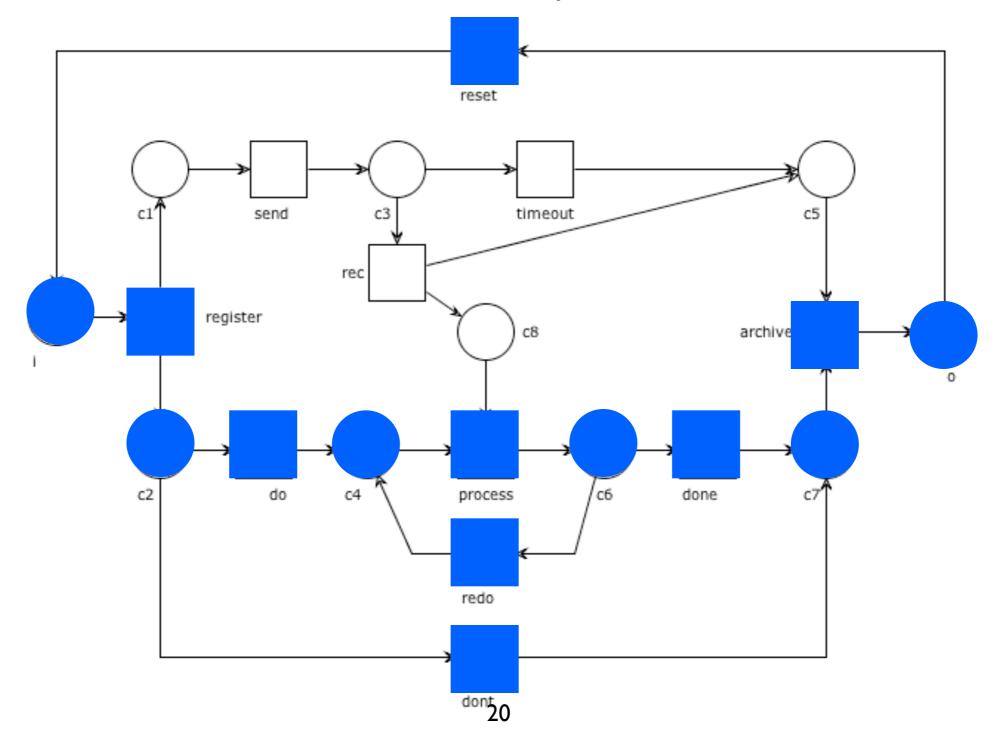
Running example: S-cover for N*?



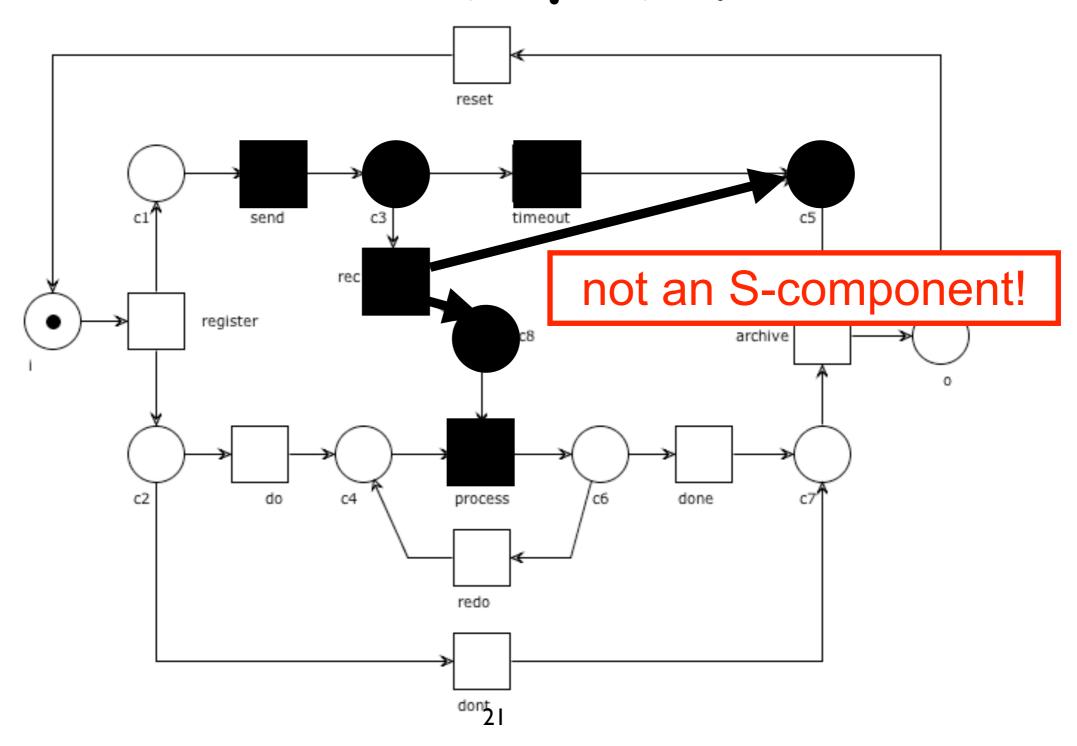
Running example: S-cover for N*?



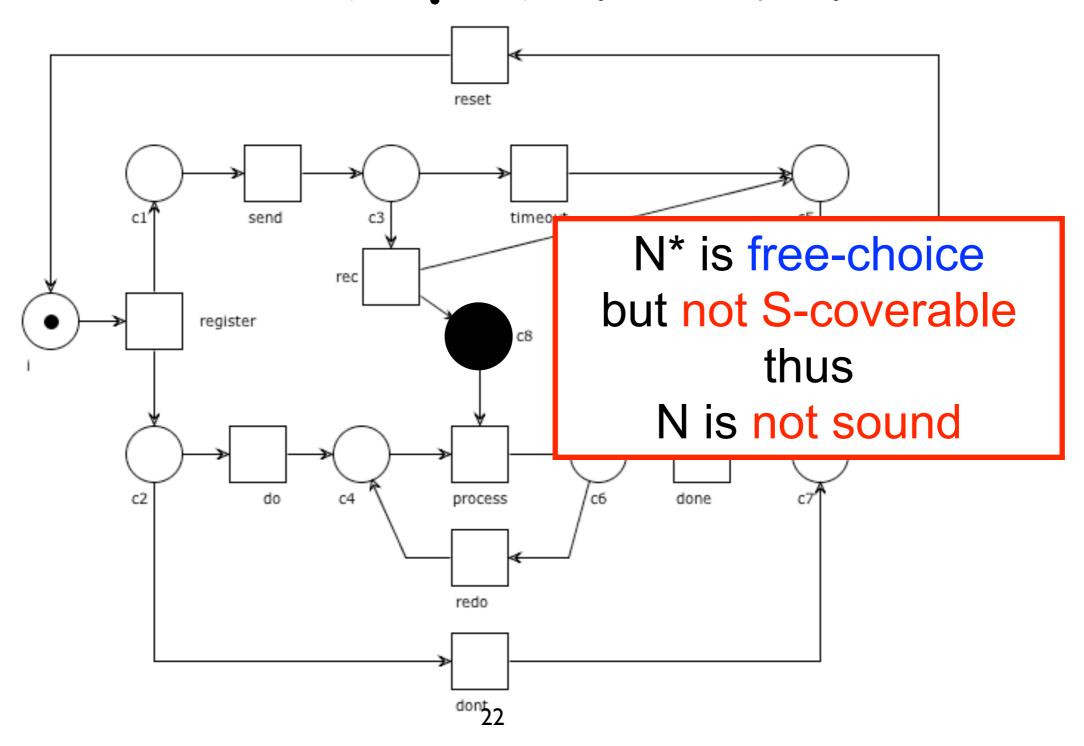
Running example: S-cover for N*



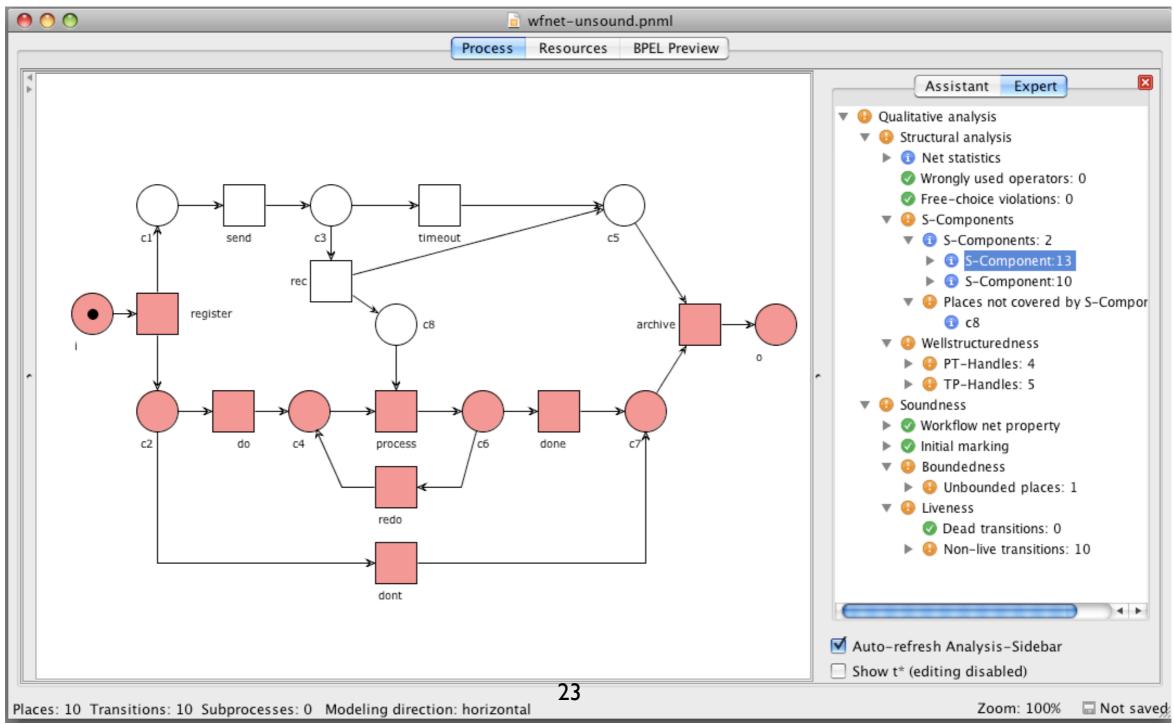
Running example: S-cover for N*



Running example: S-cover for N*? No



Running Example: WoPeD Diagnosis



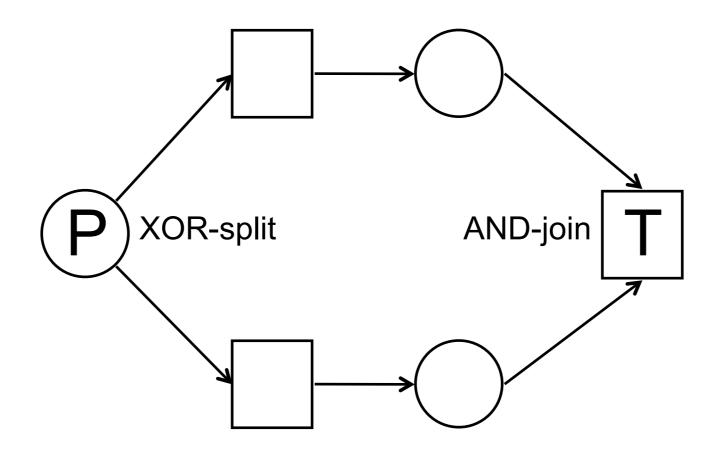
Split / Join Balancing

A good workflow design is characterized by a balance between AND/XOR-split and AND/XOR-joins

Any mismatch is a potential source of errors

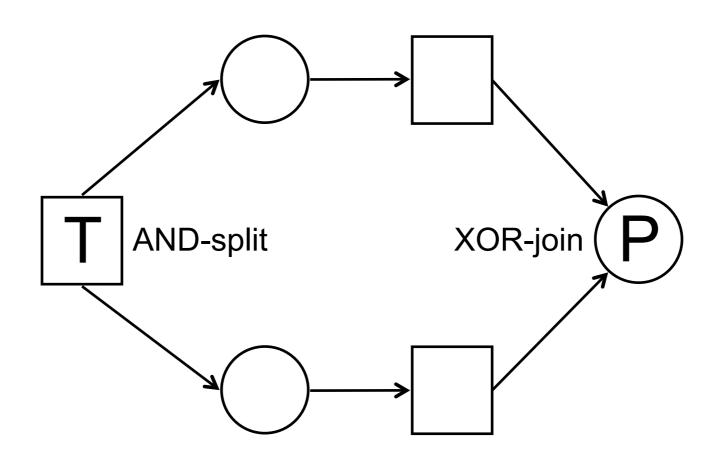
PT-handles

Two alternative flows created via a XOR-split should not be synchronized by an AND-join (the net could deadlock)



TP-handles

Two parallel flows initiated by an AND-split should not be joined by a XOR-join (multiple tokens appear in the same place)



TP- and PT-handles

Definition: A transition t and a place p form a TP-handle if there are two distinct elementary paths c₁ and c₂ from t to p such that the only nodes they have in common are t,p

Definition: A place p and a transition t form a PT-handle if there are two distinct elementary paths c₁ and c₂ from p to t such that the only nodes they have in common are p,t

Well-Structured Nets

Definition: A net is well-handled iff for any pair of nodes x and y of different kinds (one place and one transition) any two elementary paths c₁ and c₂ from x to y coincide or have some other nodes in common apart x,y

well-handled = no PT-handles and no TP-handles

Definition: A workflow net N is well-structured if N* is well-handled

S-coverability diagnosis

Theorem:

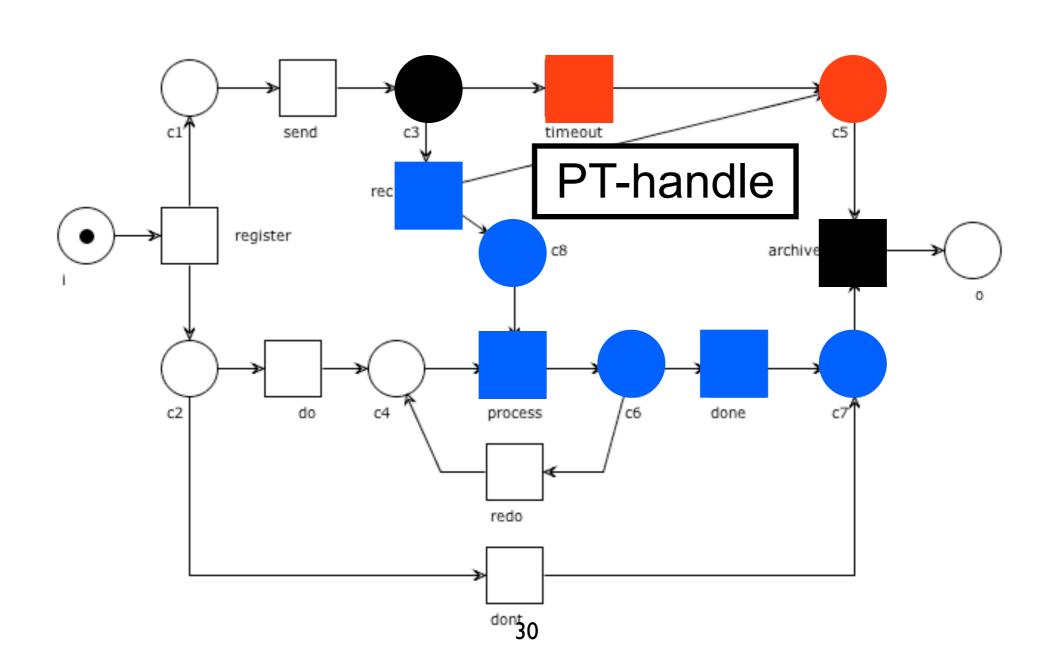
If N is sound and well-structured, then N* is S-coverable (proof omitted)

N well-structured + N* not S-coverable => N not sound

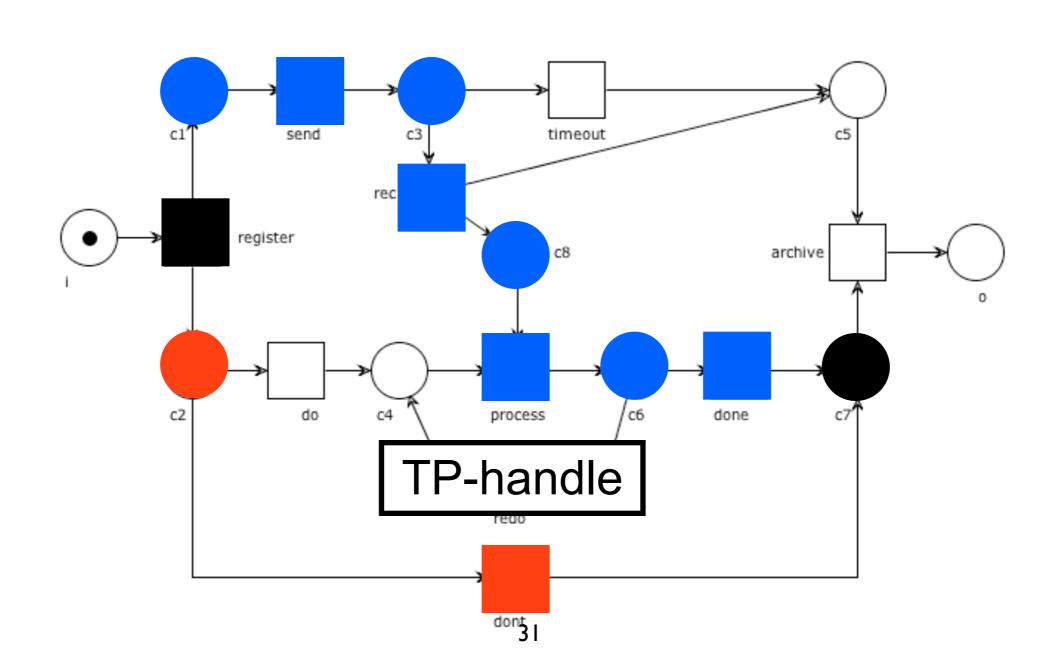
Note that

If N is not well-structured, N can still be sound especially if reset is involved in the handle (it is a symptom, not a disease)

Running example: Well-structured? No



Running example: Well-structured? No

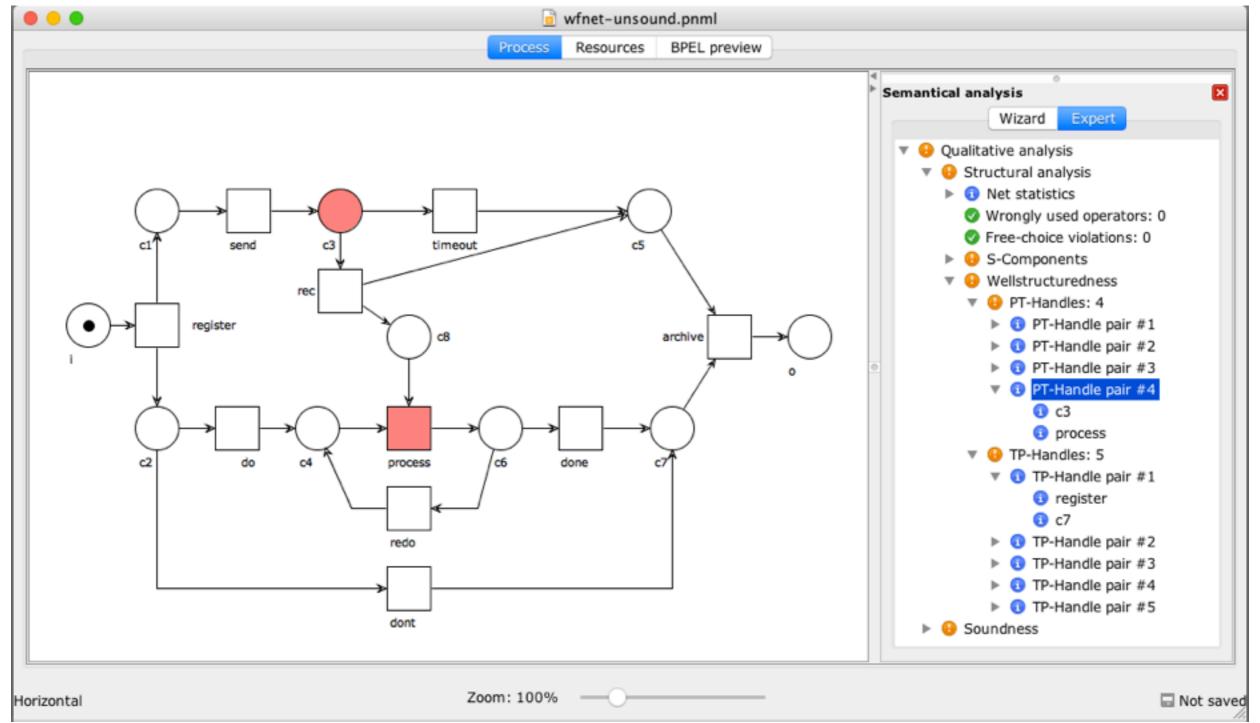


Be careful

N well-structured = N* well-handled

WoPeD marks PT/TP-handles over N* (not over N)

Running Example: WoPeD Diagnosis



Liveness and boundedness vs Soundness requirements

Improper completion

Suppose N completes improperly: from i we can reach o+L

We can do the same on N* then we fire reset and reach i+L

we can repeat the same run and reach i+2L and then i+3L and then i+4L and then ... i+kL

then N* has some unbounded places (all p such that L(p)>0)

Unsoundness from unboundedness

Improper completion of N implies unboundeness of N*

Symptom: N* has some unbounded places

Disease: maybe proper completion does not hold for N

Consequences of boundedness

If N* is bounded, then: if o+L is reachable from i in N, then L=0

If N* is bounded, then

either N satisfies

both option to complete and proper completion or N does not satisfy option to complete

Completion option failure

Suppose N does not satisfy the "option to complete": then from i we can reach M

from which we cannot mark o

We can do the same on N* then reset is dead from M i.e. reset is non-live in N*

N* has non-live transitions (including reset)

Unsoundness from non-liveness

Option to complete fail for N implies non-liveness of N*

Symptom: reset transition is non-live in N*

Disease: maybe option to complete does not hold for N

Unsoundness from Non-Liveness

If N* is bounded and has dead transitions, then

If reset is dead

N and N* have the same finite reachability graph

hence N has the same dead tasks as N*

(except reset)

if reset is not dead the reachability graphs of N and N* differ only for $o \xrightarrow{reset} i$ (because N* is bounded)

hence N has the same dead tasks as N*

Unsoundness from Non-Liveness

Symptom: N* has non-live transitions

Disease: N could have dead tasks

Symptom: N* is bounded and has dead transitions

Disease: N has the same dead tasks as N*

Error sequences

Diagnostic information

The sets of:
unbounded places of N*
dead transitions of N*
non-live transitions of N*

may provide useful information for the diagnosis of behavioural errors (pointing to different types of errors)

Unfortunately, this information is not always sufficient to determine the exact cause of the error

Behavioural error sequences can overcome this problem

Error sequences

Rationale:

We want to find firing sequences such that:

- 1. every continuation of such sequences will lead to an error
- 2. they have minimal length (none of their prefixes satisfies the above property)

Informally:

error sequences are scenarios that capture the essence of errors made in the workflow design (violate "option to complete" or "proper completion")

Non-Live sequences: informally

A non-live sequence is a firing sequence of minimal length such that completion of the case is no longer possible

i.e. a witness for transition reset being non-live in N*

Non-Live sequences: fundamental property

Let N be such that:

N* is bounded

N (or equivalently N*) has no dead task

Then, N* is live

iff

N has no non-live sequences

Non-Live sequences: graphically

The analysis is possible in bounded systems only

Compute the RG of N*
Color in red all nodes from which there is **no path** to o

Color in green all nodes from which all paths lead to o

Color in yellow all remaining nodes (some but not all paths lead to o)

Non-Live sequences: remarks

No red node implies no yellow node

No green node implies no yellow node

Non-Live sequences: formally

Definition:

An occurrence sequence

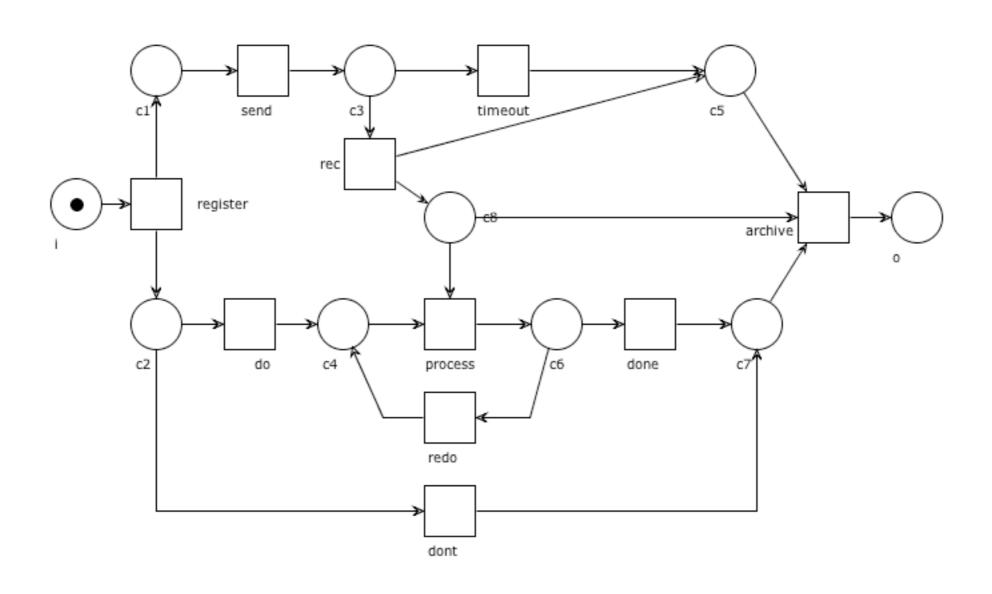
$$i \xrightarrow{t_1} M_1 \dots M_{k-1} \xrightarrow{t_k} M_k$$
 is non-live if

- all markings are distinct
- M_{k-1} is yellow
- \bullet M_k is red

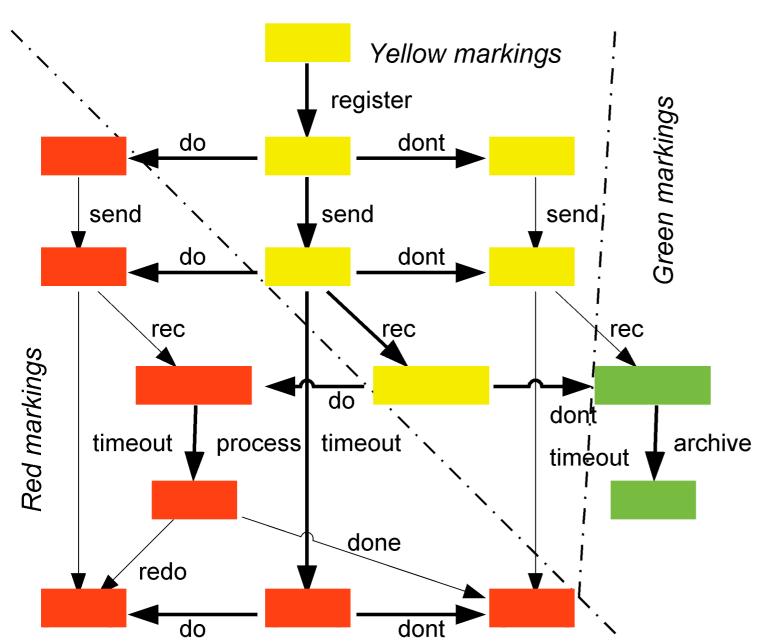
Firing t_k removes the option to complete!

Then, the firing sequence $t_1...t_k$ is also called **non-live**

Running example: slight variant



Running example variant: colored RG



Non-live sequences:

register, do

register, send, do

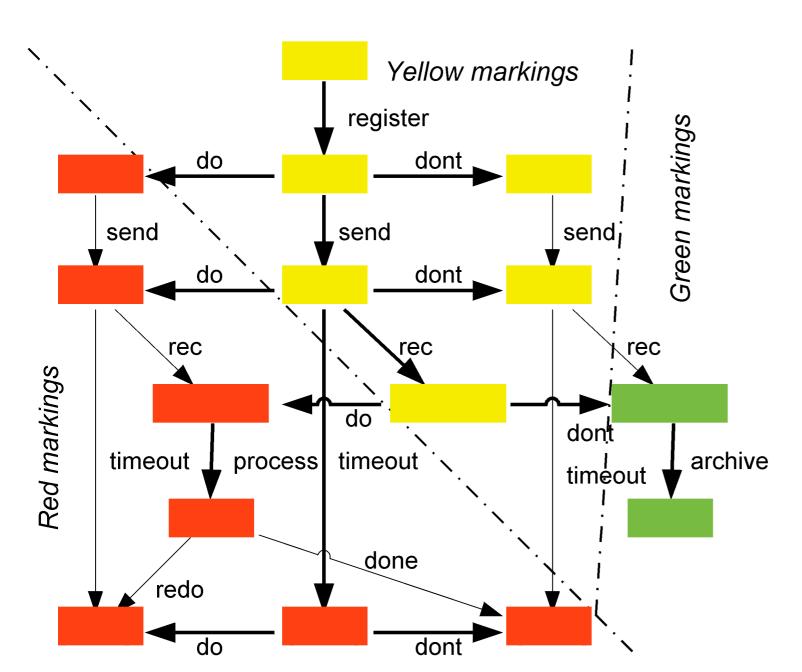
register, send, timeout

register, send, rec, do

register, send, dont, timeout

and also?

Running example variant: colored RG



Non-live sequences:

register, do

register, send, do

register, send, timeout

register, send, rec, do

register, send, dont, timeout

register, dont, send, timeout

Unbounded sequences: informally

An unbounded sequence is a firing sequence of minimal length such that every continuation invalidates proper completion

i.e. a witness for unboundedness

Unbounded sequences: fundamental property

N* is bounded iff

N has no unbounded sequences

Undesired markings: infinite-weighted markings or markings greater than o

Unbounded sequences: graphically

Compute the CG of N*

Color in green all nodes from which undesired markings are not reachable

Color in red all nodes from which no green marking is reachable (undesired markings are unavoidable)

Color in yellow all remaining nodes (undesired markings are reachable but avoidable)

Unbounded sequences: remarks

No red node implies no yellow node

No green node implies no yellow node

Restricted coverability graph (RCG)

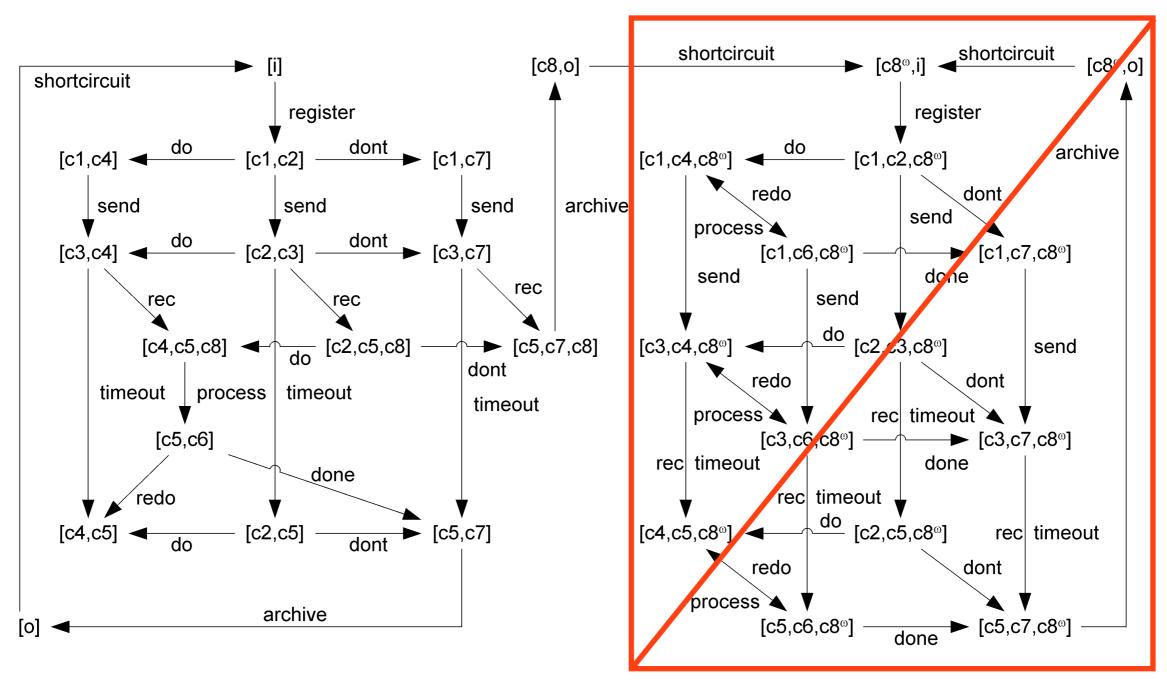
CG can become very large (intractable!)

Basic observation:

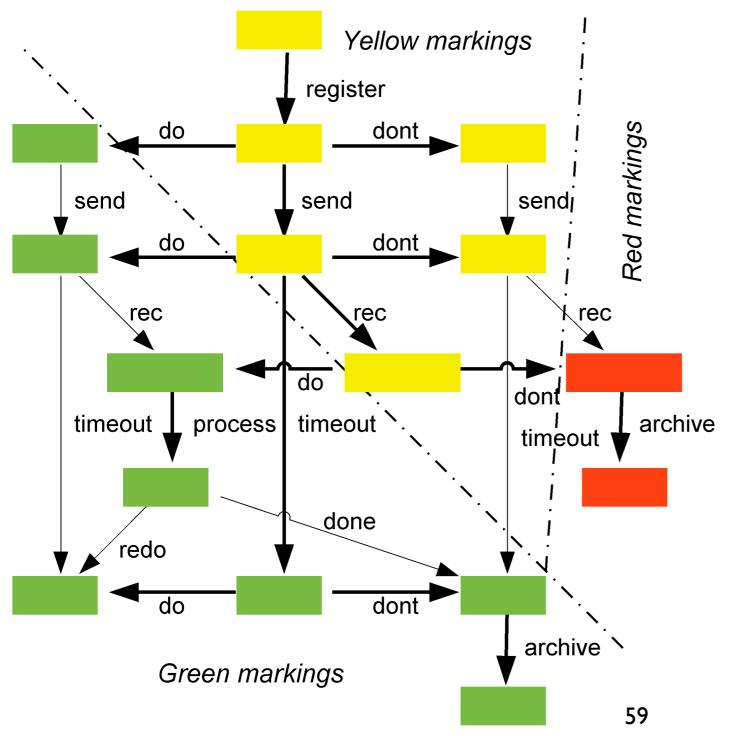
infinite-weighted markings leads to infinite-weighted markings and they will be all red

We can just avoid computing them!

Running example: RCG vs CG

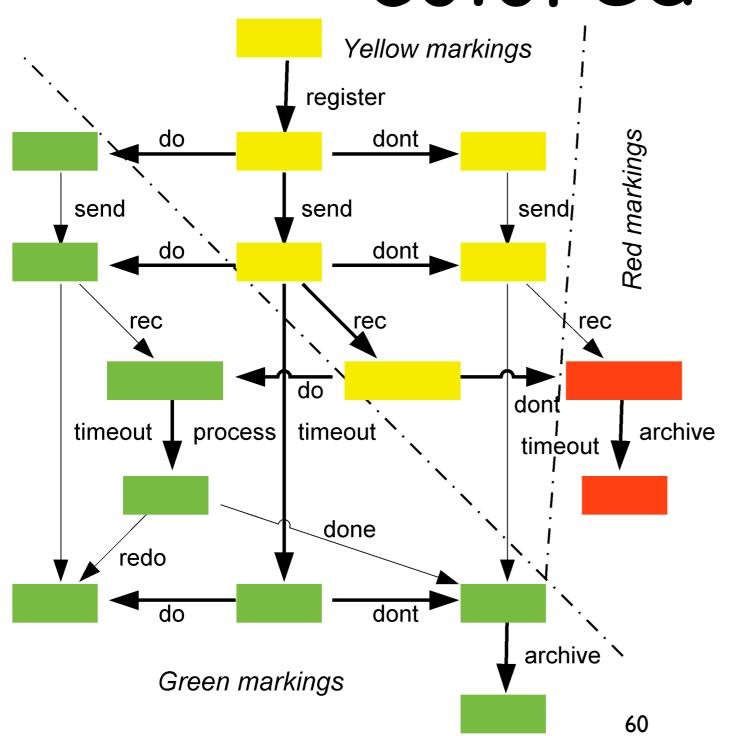


Running example: colored RCG



Unbounded sequences:
register, dont, send, rec
register, send, dont, rec
and also?

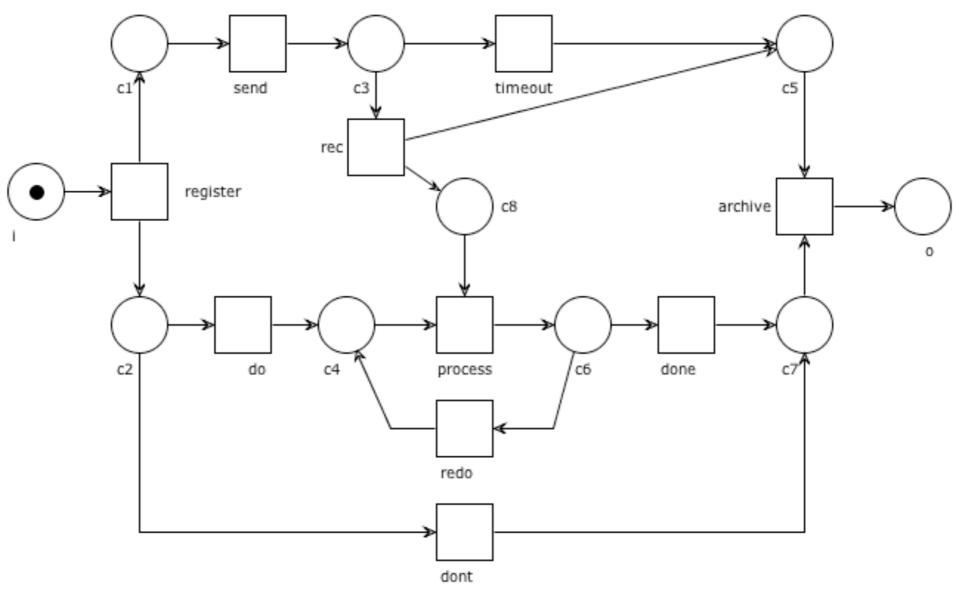
Running example: colored RCG



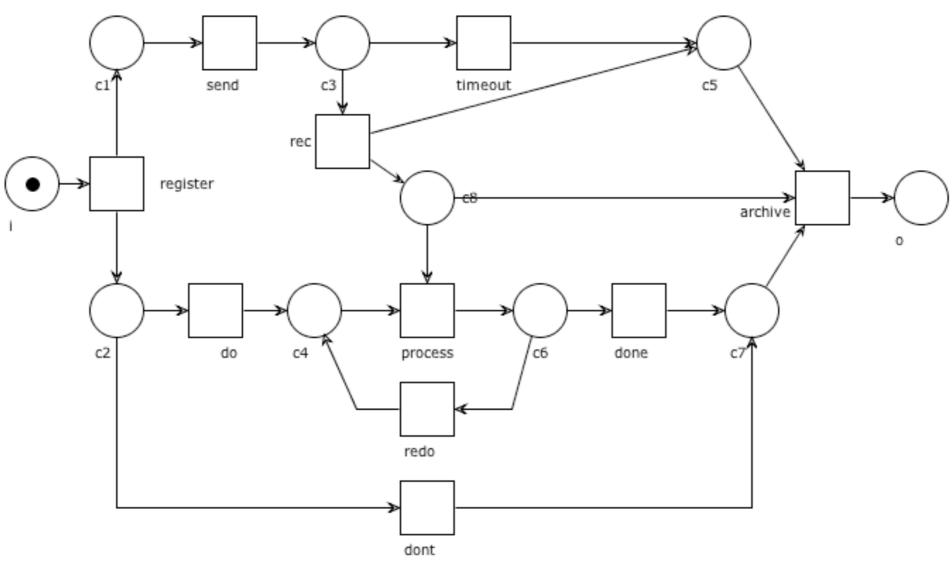
Unbounded sequences:
register, dont, send, rec
register, send, dont, rec
register, send, rec, dont

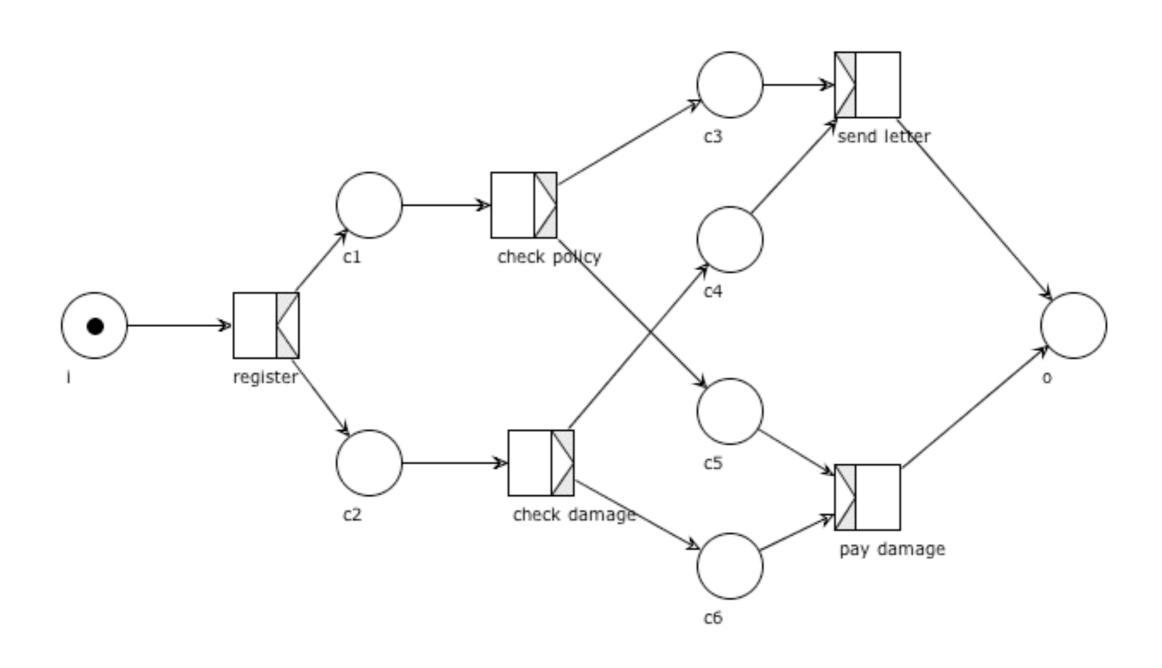
Practice with WoPeD (and Woflan)

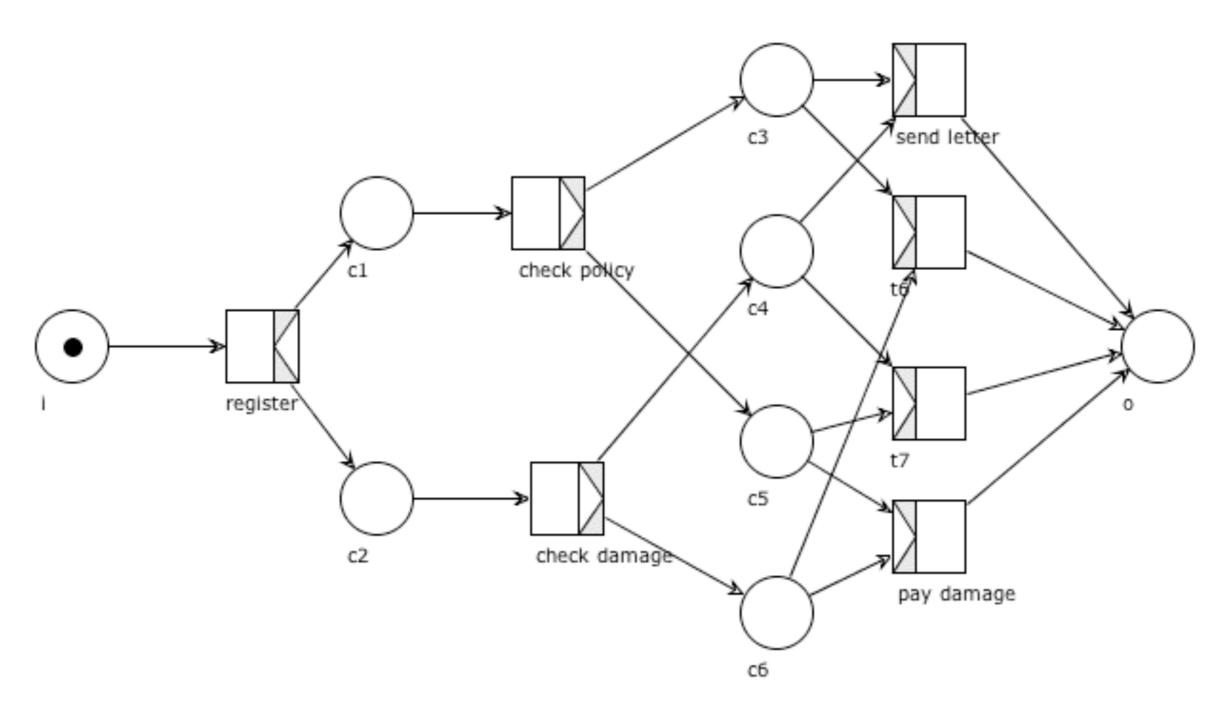
Analyse the running example

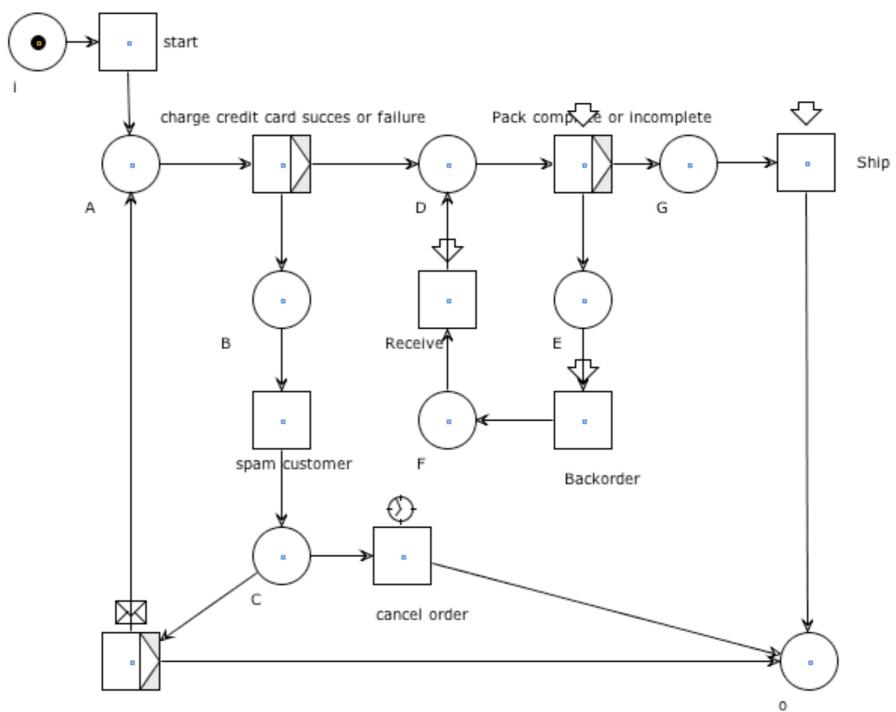


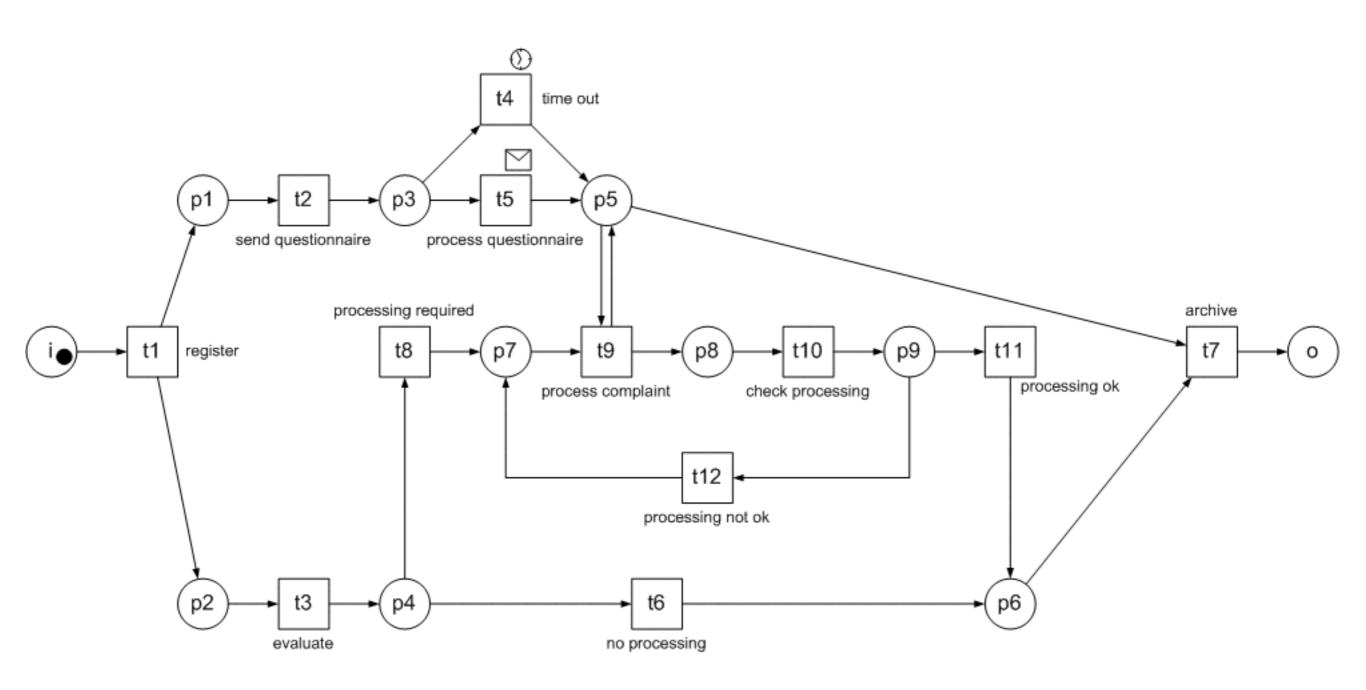
Analyse the running example variant

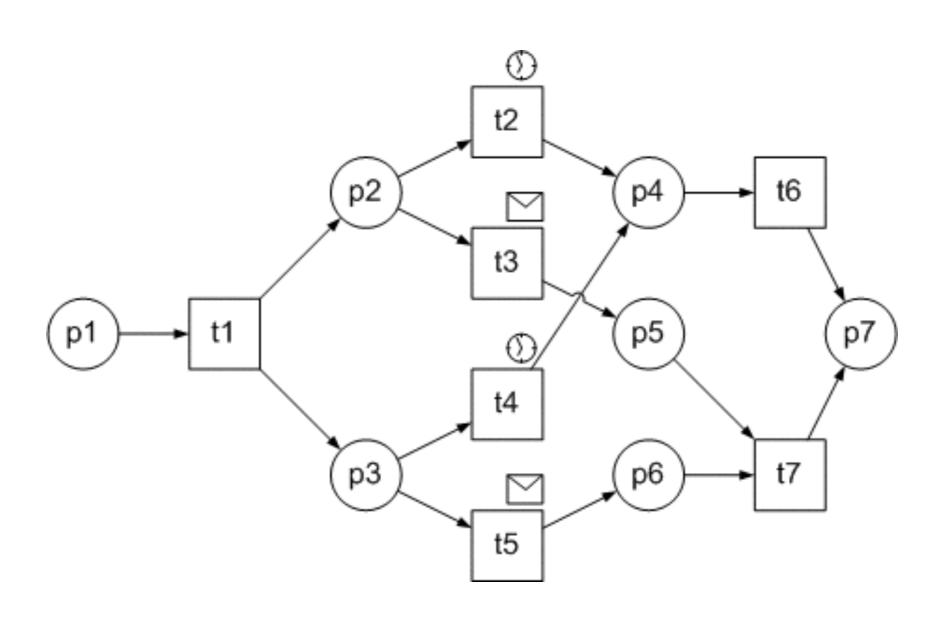




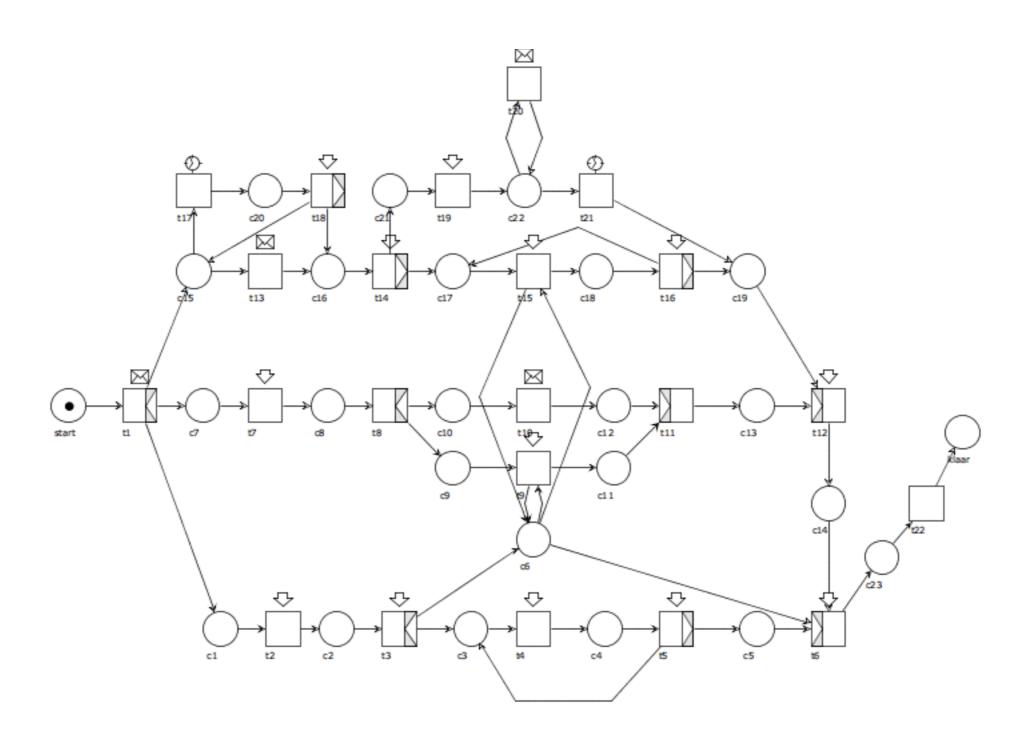




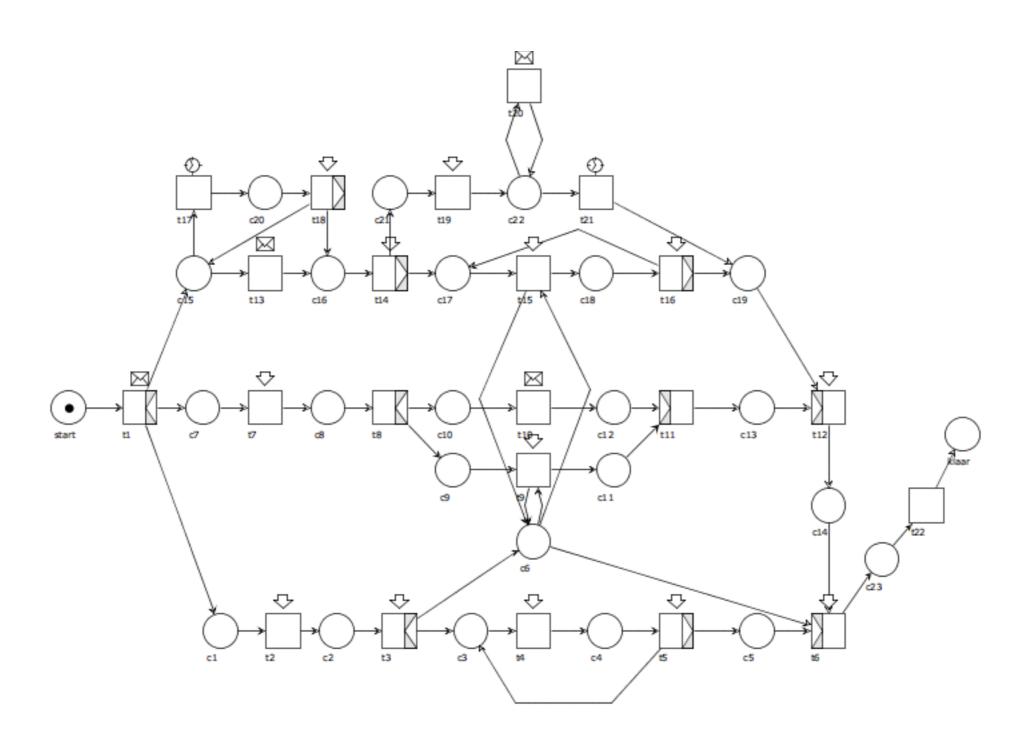




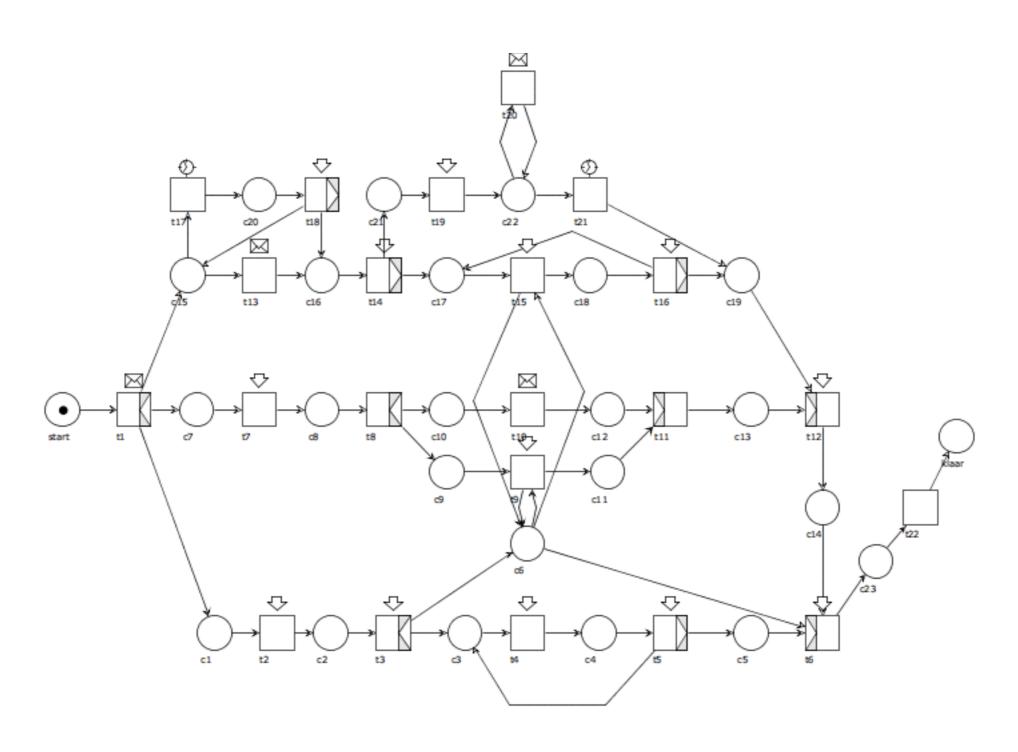
Is this net free-choice?



Is this net S-coverable?



Is this net sound?



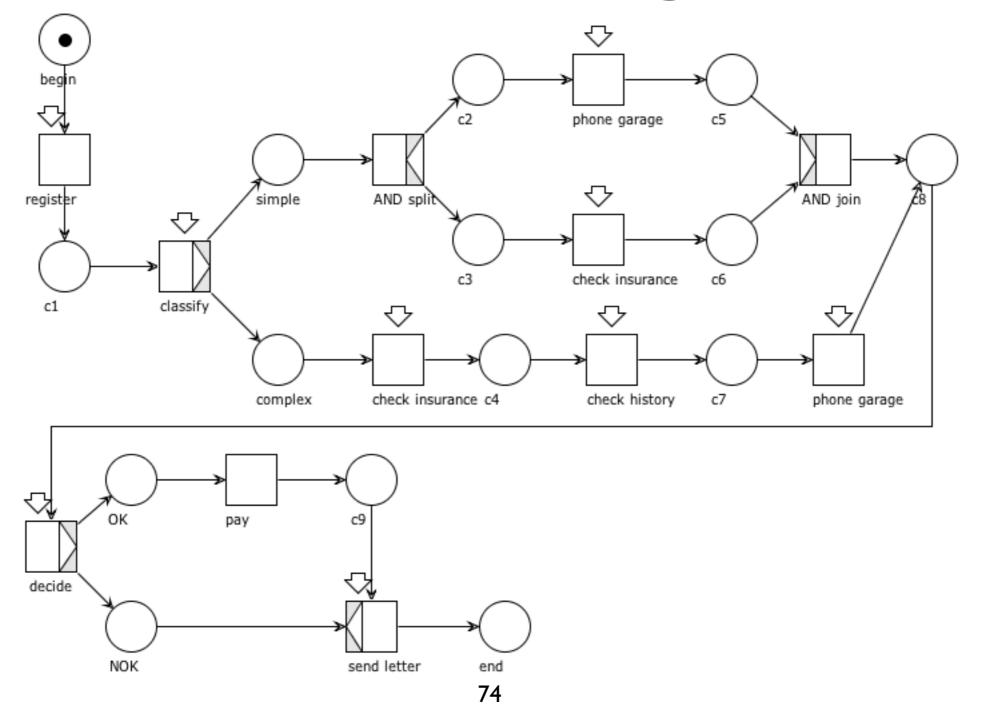
Design Example: Car Damage

- An insurance company uses the following procedure for the processing of the claims
- Every claim, reported by a customer, is registered
- After the registration, the claim is classified
- There are two categories: simple and complex claims.
 - For simple claims two tasks need to be executed: check insurance and phone garage.
 These tasks are *independent* of each other.
 - The complex claims require three tasks: check insurance, check damage history and phone garage. These tasks need to be executed sequentially in the order specified.
- After executing the two/three tasks a decision is taken with two possible outcomes: OK (positive) or NOK (negative).
- If the decision is positive, then insurance company will pay.
- In any event, the insurance company sends a letter to the customer.

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Design Example: Car Damage



Design and analysis of WF-nets

The workflow of a computer repair service (CRS) can be described as follows.

A customer brings in a defective computer and the CRS checks the defect and hands out a repair cost calculation back.

If the customer decides that the costs are acceptable, the process continues, otherwise she takes her computer home unrepaired.

The ongoing repair consists of two activities, which are executed sequentially but in an arbitrary order.

One activity is to check and repair the hardware,

whereas the other activity is to check and configure the software.

After both activities are completed, the proper system functionality is tested.

If an error is detected the repair procedure is repeated,

otherwise the repair is finished and the computer is returned.

Model the described workflow as a sound workflow net.