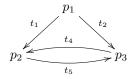
MPB – Selected solutions of mid-term exams

October 31, 2018

Ex.3 $\exists M \in [M_0\rangle$. $M(p_1) > 1$

Ex.4 1.



- 2. no, because t_3 is dead (G has no arc labelled by t_3)
- 3. yes, all states have outgoing arcs
- 4. yes, because G is finite
- 5. yes, in each reachable marking there is at most one token in each place
- 6. no, the initial marking p_1 has no incoming arc
- Ex.5 1. the Parikh vector is $\vec{\sigma} = [3\ 2\ 3\ 2\]$, thus $M = M_0 + \mathbf{N} \cdot \vec{\sigma} = 2p_2 + 2p_4 + 2p_5$
 - 2. the Parikh vector is $\vec{\sigma'} = \begin{bmatrix} 3 & 3 & 2 & 1 \end{bmatrix}$, but $M' = M_0 + \mathbf{N} \cdot \vec{\sigma} = \begin{bmatrix} -1 & 1 & 1 & 0 & 2 & 2 \end{bmatrix}$ is not a marking
- Ex.6 1. yes, every place has exactly one incoming arc and one outgoing arc 2. $\mathbf{I} = \begin{bmatrix} 3 & 1 & 2 & 1 & 1 & 2 \end{bmatrix}$
 - 3. $\mathbf{I} \cdot M_0 = 6$ and $\mathbf{I}(p_1) = 3$ thus for any $M \in [M_0)$ we have $M(p_1) \le 6/3 = 2$; note that by firing $t_2 t_4$ we get two tokens in p_1

November 2, 2017

- Ex.4 1. no because p_2 has two outgoing arcs
 - 2. the firing sequence $t_5 t_1 t_1 t_3 t_3 t_4 t_5 t_1 t_3$ leads to $2p_3$ which is a deadlock
 - 3. no, because it is not deadlock free
 - 4. places p_1, p_2, p_3, p_5 must be assigned the same weight x because of t_1, t_3, t_5 ; then because of t_2 we have x = x + y, for y the weight of p_4 , hence y = 0
 - 5. no

Ex.5 1. the Parikh vector is $\vec{\sigma} = [3\ 1\ 2\ 2\ 2]$, thus $M = M_0 + \mathbf{N} \cdot \vec{\sigma} = p_3 + p_5$

- 2. the Parikh vector is $\vec{\sigma'} = [2\ 1\ 2\ 1\ 1]$, but $M' = M_0 + \mathbf{N} \cdot \vec{\sigma} = [0\ -1\ 2\ 1\ 1]$ is not a marking
- Ex.6 1. $\mathbf{I} = \begin{bmatrix} 2 & 1 & 1 & 1 & 1 \end{bmatrix}$
 - 2. $\mathbf{I} \cdot M_0 = 2$ and $\mathbf{I}(p_1) = 2$ thus for any $M \in [M_0)$ we have $M(p_1) \le 2/2 = 1$
 - 3. the only possible T-invariants are of the form [x x x x 0 0]
 - 4. from (i) the system is bounded; from a theorem: "if a bounded system is live then it has a positive T-invariant"; since the system has no positive T-invariant then it is not live

November 3, 2016

- Ex.4 1. no: t_2 and t_5 have different pre-sets with p_2 in common

 - 3. $\mathbf{I} \cdot M = 4 \neq 3 = \mathbf{I} \cdot M_0$
 - 4. $t_1 t_2 t_3$ leads to the marking $2p_4 + p_5$ that is deadlock
 - 5. no, because it is not deadlock free
- Ex.5 1. the sequence $t_1 t_2$ leads to the marking $M_0 + p_3$
 - 2. $\mathbf{I} = [0 \ 0 \ 0 \ 0 \ 1 \ 1 \ 1]$ is semi-positive and $\mathbf{I} \cdot M_0 = 0$
 - 3. the Parikh vector is $\vec{\sigma} = [2\ 3\ 3\ 5\ 0\ 0\ 0]$, then $M = M_0 + \mathbf{N} \cdot \vec{\sigma} = [1\ 3\ 0\ -1\ 0\ 0\ 0]$ is not a marking

November 5, 2015

- Ex.3 1. no, p_1 has two incoming arcs
 - 2. yes, $\mathbf{I} = \begin{bmatrix} 1 & 1 & 1 & 1 \end{bmatrix}$ is a positive S-invariant
 - 3. no, transitions t_1, t_3, t_4 must be assigned the same weight x; then we have x = x + y, for y the weight of t_2 , hence y = 0
 - 4. no positive T-invariant + boundedness implies the system is not live
- Ex.4 1. the Parikh vector is $\vec{\sigma} = [4234]$, then $M = M_0 + \mathbf{N} \cdot \vec{\sigma} = [3001] = 3p_1 + p_4$
 - 2. $\mathbf{I} = \begin{bmatrix} 1 & 1 & 1 & 1 \end{bmatrix}$ is an S-invariant with $\mathbf{I} \cdot M = 5 \neq 4 = \mathbf{I} \cdot M_0$

Ex.5 1. yes

- 2. it has no initial place
- 3. not strongly connencted: p_3 has no outgoing arc
- 4. $\mathbf{I} = \begin{bmatrix} 2 & 1 & 1 & 2 & 1 \end{bmatrix}$ is a positive S-invariant
- 5. from (iv) it is bounded; bounded + not strongly connected implies non live

November 7, 2014

- Ex.3 1. the firing of t_2 leads to the marking p_3 that is deadlock
 - 2. not live because not deadlock free
 - 3. no, t_3 and t_4 have different pre-sets with p_2 in common
 - 4. the firing sequence $t_1 t_4 t_6 t_5$ leads to $M_0 + p_3$
- Ex.4 1. the Parikh vector is $\vec{\sigma} = [3\ 1\ 0\ 3\ 2\ 3]$, then $M = M_0 + \mathbf{N} \cdot \vec{\sigma} = [0\ 0\ 3\ 1\ 0] = 3p_3 + p_4$
 - 2. the Parikh vector is $\vec{\sigma'} = [3\ 0\ 2\ 3\ 2\ 2]$, then $M' = M_0 + \mathbf{N} \cdot \vec{\sigma} = [0\ -2\ 0\ 3\ 1]$ is not a marking
- Ex.5 1. $\mathbf{I} = \begin{bmatrix} 3 & 1 & 2 & 1 & 1 & 1 & 2 & 3 \end{bmatrix}$ is a positive S-invariant 2. $\mathbf{I} \cdot M = 6 \neq 5 = \mathbf{I} \cdot M_0$

November 6, 2013

- Ex.3 1. not live
 - 2. not place-live
 - 3. not deadlock free
 - 4. bounded
 - 5. safe
 - 6. not cyclic
- Ex.4 1. the Parikh vector is $\vec{\sigma} = [2\ 0\ 2\ 1\ 0\ 1\ 1\ 2]$, then $M = M_0 + \mathbf{N} \cdot \vec{\sigma} = [0\ 1\ 0\ 0\ 1\ 0\ 0\ 0] = p_2 + p_5$
- Ex.5 1. $\mathbf{I} = \begin{bmatrix} 2 \ 2 \ 1 \ 1 \ 1 \end{bmatrix}$ is a positive S-invariant from which we have $\mathbf{I} \cdot M = 6 \neq 5 = \mathbf{I} \cdot M_0$

November 7, 2012

- Ex.3 The net is alike the producer-consumer example with bounded buffer (2 producers, 2 consumers, 2 slots):
 - 1. live
 - 2. deadlock free
 - 3. bounded
 - 4. not safe
 - 5. cyclic
- Ex.5 1. the Parikh vector is $\vec{\sigma} = [3\ 2\ 1\ 1]$, then $M = M_0 + \mathbf{N} \cdot \vec{\sigma} = [0\ 2\ 1\ 0] = 2p_2 + p_3$
 - 2. the Parikh vector is $\vec{\sigma'} = [4 \ 3 \ 2 \ 2]$, then $M = M_0 + \mathbf{N} \cdot \vec{\sigma} = [0 \ 2 \ 1 \ 0] = 2p_2 + p_3$

November 21, 2011

Ex.3 The analysis of the T-system relies on the identification of its circuits. Let:

$$\begin{aligned} \gamma_0 &= (p_5, t_4)(t_4, p_6)(p_6, t_3)(t_3, p_4)(p_4, t_2) \\ \gamma_1 &= (p_3, t_3)(t_3, p_4)(p_4, t_2) \\ \gamma_2 &= (p_1, t_1)(t_1, p_2)(p_2, t_2) \end{aligned}$$

Note that $M_0(\gamma_0) = 3$, $M_0(\gamma_1) = 2$, and $M_0(\gamma_2) = 1$.

- 1. It is immediate to check that the T-system is strongly connected. By a known Lemma, since it is strongly connected, then it is bounded. Place p_5 is not 1-bounded, hence the T-system is not safe (e.g., take the firing $M_0 \xrightarrow{t_2} M'$).
- 2. It is immediate to check that all places belong to γ_0 or γ_1 or γ_2 . By a known Theorem, a T-system is live iff all of its circuits are marked at M_0 . Since γ_0 , γ_1 and γ_2 are all marked, we can conclude that the T-system is live. Note that, by a known Theorem, a live T-system is k-bounded iff every place p belongs to some circuit γ_p such that $M_0(\gamma_p) \leq k$. We can exploit this property to confirm that the Tsystem is not safe by noting that no such circuit γ with $M_0(\gamma) \leq 1$ can be found for p_5 .
- 3. The fundamental property of T-systems guarantees that the token count of a circuit is invariant under any firing. By noting that $M(\gamma_0) = M(p_5) + M(p_6) + M(p_4) = 2 \neq 3 = M_0(\gamma_0)$ we can conclude that M is not reachable from M_0 .
- Ex.4 The set **M** is stable. In fact, the fundamental property of S-systems guarantees that the token count is invariant under any firing. Therefore, taken any $M \in \mathbf{M}$, and any firing $M \xrightarrow{t} M'$, we know that $M'(P) = M(P) = M_0(P)$ and thus $M' \in \mathbf{M}$.

By the Reachability Lemma for S-system, $\mathbf{M} = [M_0\rangle$ iff the S-system is strongly connected.

Ex.5 For each vector \mathbf{I}_i we need to check that

$$\forall t \in T. \sum_{p \in \bullet t} \mathbf{I}_i(p) = \sum_{p \in t \bullet} \mathbf{I}_i(p)$$

- $\mathbf{I}_1 = [1 \ 1 \ 0 \ 0 \ 0]$ is an S-invariant.
- $-\mathbf{I}_2 = \begin{bmatrix} 0 & 0 & 1 & 1 \end{bmatrix}$ is not an S-invariant, because the above equality does not hold, e.g., for t_1 .
- **I**₃ = [2 2 1 2 1] is an S-invariant.

For each vector \mathbf{J}_i we need to check that

$$\forall p \in P. \sum_{t \in \bullet p} \mathbf{J}_i(t) = \sum_{t \in p \bullet} \mathbf{J}_i(t)$$

- $\mathbf{J}_1 = \begin{bmatrix} 1 & 2 & 2 & 1 \end{bmatrix}$ is not a T-invariant, because the above equality does not hold, e.g., for p_4 .
- **J**₂ = [1 1 1 0] is a T-invariant.
- $\mathbf{J}_3 = \begin{bmatrix} 0 \ 1 \ 0 \ 1 \end{bmatrix}$ is not a T-invariant, because the above equality does not hold, e.g., for p_3 .

May 2, 2011

Ex.3 1. S-net

- 2. not a T-net
- 3. free-choice (because S-net)
- Ex.4 1. there can exist nets with a semi-positive S-invariant but with some unbounded place (e.g., producer-consumer example with unbounded buffer)
 - 2. the existence of a positive S-invariant implies the boundedness but not the safeness (e.g., put two tokens in the same place in the initial marking)
 - 3. the existence of a positive S-invariant implies the boundedness (known theorem)

Ex.5 For each vector \mathbf{I}_i we need to check that

$$\forall t \in T. \sum_{p \in \bullet t} \mathbf{I}_i(p) = \sum_{p \in t \bullet} \mathbf{I}_i(p)$$

- 1. $\mathbf{I}_1 = \begin{bmatrix} 1 & 1 & 0 & 0 \end{bmatrix}$ is not an S-invariant, because the above equality does not hold, e.g., for t_3 .
- 2. $I_2 = [0 \ 0 \ 1 \ 1 \ 1]$ is an S-invariant.
- 3. $I_3 = [1 \ 1 \ 2 \ 2 \ 1]$ is an S-invariant.
- 4. $I_4 = \begin{bmatrix} 2 & 2 & 1 & 1 \end{bmatrix}$ is not an S-invariant, because the above equality does not hold, e.g., for t_3 .
- 5. $\mathbf{I}_5 = [1 \ 1 \ 1 \ 1 \ 0]$ is an S-invariant $(\mathbf{I}_5 = \mathbf{I}_3 \mathbf{I}_2)$.
- 6. $\mathbf{I}_6 = \begin{bmatrix} 0 & 1 & 0 & 1 & 1 \end{bmatrix}$ is not an S-invariant, because the above equality does not hold, e.g., for t_1 .