



Intel Thread Building Blocks, Part V

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The Flow Graph



- Allow fast & efficient implementation of dataflow, dependency graph algorithms
 - Introduced in TBB 4
 - Evolution of the pipeline idea
- Computation represented as
 - A graph object
 - A set of nodes : computation units
 - one or more inputs and outputs
 - A set of edges : comm. channel AND dependencies
- loops? Yes, but examples are mostly DAGS
- Node execution = TBB task instantiation
- Namespace tbb::flow





The graph object



- Dynamically created by program code, using node and edge constructor methods
 - Can be run multiple times
 - Owns all tasks created during the flow graph execution
 - Executes its tasks either in a specified task_group_context, or in a newly created context
- Feeding the graph is done via enqueueing data
 - However, a less than trivial protocol is used to let the node communicate with each other with low overhead
- Interactions
 - Waiting for the graph to finish its computation
 - Registering interactions with the graph
 - Will actually cause tasks to be run within the graph
- Most examples are DAGS, but this is not mandatory
 - Generic looping graphs are much harder to design & debug









- continue_msg
 - Empty class used for dependency messages
- flow::tuple
 - Used to manage messages built of many parts
 - Supports a subset of the methods of the std::tuple
- class tagged_msg
 - Template to add a tag to a multipart message
 - A specified TagType is used to inform the receiver on the content of the message, which may be only known at runtime
 - template<typename TagType, typename T0, typename T1...typename TN> class tagged_msg;









- Several types of nodes
 - Functional
 - Buffering, filtering of messages
 - Aggregation/deaggregation (broadcast, order)









TBB Flow Graph Nodes



- Several types of nodes
 - Functional
 - Buffering, filtering of messages
 - Aggregation/deaggregation (broadcast, order)
 - Utility
- Node input and output types are defined at creation via template parameters
 - Multiple inputs are managed via tuples an read with get<0>, get<1> ...
- Node invoke user-provided functions

 Executed as tasks, so choose wisely their grain
- Can also be created in *inactive* state and be activated later on
 - Pay attention to the creation order (e.g. use reverse dependency order), or risk losing messages







Class node abstract templates



- templates helping define different types of nodes
 - abstract classes with default implementation of some methods
 - you may have to redefine some virtual methods
 - register and remove methods are for TBB internal use!
- Graph_node base template class
- Sender template class
 - Nodes that act as data/message sender
- Receiver template class
- Continue_receiver
 - Receives multiple continue_msg, computes when the number of messages hits the set threshold
- execute() is Triggered by predecessors' calling try_put()







"Functional" nodes



- These nodes compute a function
 - of the predecessor(s) input(s) if any are connected
 - send the results (data or empty message) to the successor(s)

Continue_node

- Awaits one or mode dependency messages in input
- Performs a computation and brodcasts a data/dep message to its successors
- Function_node
- Source_node
 - Strictly serial node, no predecessors, user function will generate messages that are broadcast to successors

Multifunction_node

- One input, multiple output broadcast to successors
- can be assigned a concurrency limit

Asnc_node

- One input, one output, obeys concurrency limit
- Forward messages outside TBB for external processing
- Provides a gateway tpe to return back results





Buffering nodes



Overwrite_node

- Single item buffer, can overwrite

Write_once

- Single item buffer, no overwrite unless clear() is called

Buffer_node

- Unbounded buffer (arbitrary order) toward a single successor *
- Accepts a reservation

Queue_node

- Unbounded FIFO queue toward a single successor *
- Accepts a reservation, will stall the queue

Priority_queue_node

- Uses a priority queue to a successor *, reservation will stall queue

Sequencer_node

- Unbounded buffer toward a successor *
- Sends message in strict 0...N sequence order
- Will reject duplicate sequence numbers
- A single successor:*
 - Sends messages to 1st registered successor, when one msg is refused, ignore that successor, try next one (if any)







Service nodes



- Join nodes
 - Create a tuple <T0 .. Tn> from messages received at its inputs, broadcast the tuple to all its successors
- Multifunction_node
 - Has input and a tuple of outputs
 - May spawn a new task at each input received
 - Up to a degree of concurrency if predefined
- Split_node
 - Input is a tuple, and has a tuple of outputs
 - Each component of the input tuple is sent to teh corresponding output
- Indexer_node
 - Broadcast to all output each message received on any input
 - Message is tagged with the input index
- Composite_node
 - Encapsulates a collection of (any nuber of) other nodes
 - Requires C++11
 - A tuple of inputs and a tuple of outputs forward messages in and out
 - Can also be specialized to only inputs or only outputs







- Created with the method
 make_edge(srcnode, destnode)
- Encode node dependencies
 - Use class continue_msg to activate successor nodes
- Express communications
 - A data message to a successor node activates it
 - Data sent is copied, so send references to large data items whenever it is possible
- dataflow-style activation, i.e.
 - when all inputs are present
 - independent nodes can run concurrently









- Issue with push/pull protocol
 - Nodes will switch between push message forwarding and pull forwarding to avoid the need of retries
- Potential message discard if no receiver accepts
 - Some of the nodes do not buffer the message, so if no successor accepts the message can be lost







Node push/pull/buffer policies



- Two policies for forwarding message
 - broadcast-push
 - Push to all successors that accept
 - single-push
 - Push to the 1st successors that accept
- Two policies when no successors accept
 - Buffering
 - Discarding
- Two policies for accepting messages
 - Accept
 - Accept all pushed messages
 - Switch
 - Do not accept, and switch to pull mechanisms





SUPERIC	Node	Reception Policy	try_get()	try_reserve()	Forwarding	Big
PIS	Functional Nodes					
	source_node		yes	yes	broadcast-push	TÀ DI PISA
	function_node <rejecting></rejecting>	accept/switch	no	no	broadcast-push	
	function_node <queueing></queueing>	accept	no	no	broadcast-push	
	continue_node	accept	no	no	broadcast-push	
	multifunction_node <rejecting></rejecting>	accept/switch	no	no	broadcast-push	
	multifunction_node <queueing></queueing>	accept	no	no	broadcast-push	
	Buffering Nodes					
	buffer_node	accept	yes	yes	single-push	
	priority_queue_node	accept	yes	yes	single-push	
	queue_node	accept	yes	yes	single-push	
	sequencer_node	accept	yes	yes	single-push	
	overwrite_node	accept	yes	no	broadcast-push	
	write_once_node	accept once	yes	no	broadcast-push	
	Split/Join Nodes					
	join_node <queueing></queueing>	accept	yes	no	broadcast-push	
	join_node <reserving></reserving>	switch	yes	no	broadcast-push	
	join_node <tag_matching></tag_matching>	accept	yes	no	broadcast-push	
	split_node	accept	no	no	broadcast-push	
	indexer_node	accept	no	no	broadcast-push	
	Other Nodes					
	broadcast_node	accept	no	no	broadcast-push	Da
ISTITUTO DI S DELL'INFOR	limiter_node	accept/switch	no	no	broadcast-push	r a t o r







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- Creation of dependence nodes
- Creation of typed input/output nodes
- Examples of the different types of nodes

- Che differenza tra nodi broadcast e nodi con più dipendenze in uscita?
- L'esistenza della coda in input è implicita?









• aaaa









OpenCL nodes





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- Task_scheduler_init provides means for the user to customize the scheduler
 - When the scheduler is constructed/destroyed
 - How many worker threads the scheduler uses
 - The stack size of worker threads
- Either activated immediately on construction, or subsequently
 - Via ::deferred and and initialize()
- A task scheduler init affects all subsequently created schedulers
 - Also wrt floating point settings



