

Introduction and Overview

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Processor Parallelism



OpenCL is a programming framework for heterogeneous compute resources

OpenCL Working Group

Diverse industry participation

- Processor vendors, system OEMs, middleware vendors, application developers

Many industry-leading experts involved in OpenCL's design

- A healthy diversity of industry perspectives
- Apple made initial proposal and is very active in the working group
 - Serving as specification editor

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OpenCL Timeline

• Six months from proposal to released OpenCL 1.0 specification

- Due to a strong initial proposal and a shared commercial incentive
- Multiple conformant implementations shipping
 - Apple's Mac OS X Snow Leopard now ships with OpenCL

• 18 month cadence between OpenCL 1.0 and OpenCL 1.1

- Backwards compatibility protect software investment



OpenCL 1.1

General uplift in functionality for enhanced performance/programmability

- Including feedback from developer community

• New functionality - fully backwards compatible with OpenCL 1.0

- New data types
 - Including 3-component vectors and additional image formats
- Handling commands from multiple hosts
 - Processing buffers across multiple devices
- Operations on regions of a buffer
 - Including read, write and copy of 1D, 2D or 3D rectangular regions
- Enhanced use of events
 - To drive and control command execution
- Additional OpenCL C built-in functions
 - Such as integer clamp, shuffle and asynchronous strided copies
- Improved OpenGL interoperability
 - Efficient sharing of images and buffers by linking OpenCL and OpenGL events

OpenGL-based Ecosystem







OpenCL Overview

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It's a Heterogeneous World

• A modern platform Includes:

- One or more CPUs
- One or more GPUs
- DSP processors
- ... other?

OpenCL lets Programmers write a single <u>portable</u> program that uses <u>ALL</u> resources in the heterogeneous platform



GMCH = graphics memory control hub ICH = Input/output control hub

The BIG Idea behind OpenCL

OpenCL execution model ...

- execute a kernel at each point in a problem domain
 E.g., process a 1024 x 1024 image with one kernel invocation per pixel
- or $1024 \times 1024 = 1,048,576$ kernel executions



Data Parallel OpenCL



An N-dimension domain of work-items

• Define the "best" N-dimensioned index space for your algorithm

- Global Dimensions: 1024 x 1024
- Local Dimensions: 128 x 128

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(whole problem space) (work group ... executes together)



To use OpenCL, you must

• Define the platform

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- Execute code on the platform
- Move data around in memory
- Write (and build) programs



OpenCL Platform Model

• One Host + one or more Compute Devices

- Each Compute Device is composed of one or more Compute Units
 - Each Compute Unit is further divided into one or more Processing Elements



OpenCL Execution Model

- An OpenCL application runs on a host which submits work to the compute devices
 - Work item: the basic unit of work on an OpenCL device
 - **Kernel**: the code for a work item. Basically a C function
 - **Program**: Collection of kernels and other functions (Analogous to a dynamic library)
 - **Context**: The environment within which workitems executes ... includes devices and their memories and command queues

Applications queue kernel execution instances

- Queued in-order ... one queue to a device
- Executed in-order or out-of-order

GPU		CPU	
Queue	Context	Queue	

OpenCL Memory Model

Private Memory

-Per work-item

Local Memory

- -Shared within a workgroup
- Global/Constant Memory
 - -Visible to all workgroups
- Host Memory
 - –On the CPU



Memory management is Explicit You must move data from host -> global -> local ... *and* back

Programming kernels: OpenCL C Language

A subset of ISO C99

- But without some C99 features such as standard C99 headers, function pointers, recursion, variable length arrays, and bit fields

• A superset of ISO C99 with additions for:

- Work-items and workgroups
- Vector types
- Synchronization
- Address space qualifiers

Also includes a large set of built-in functions

- Image manipulation
- Work-item manipulation,
- Specialized math routines, etc.

Programming Kernels: Data Types

Scalar data types

- char, uchar, short, ushort, int, uint, long, ulong, float
- bool, intptr_t, ptrdiff_t, size_t, uintptr_t, void, half (storage)

Image types

- image2d_t, image3d_t, sampler_t
- Vector data types



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- Aligned at vector length
- Vector operations
- Built-in functions



Double is an optional type in OpenCL 1.0

Building Program Objects

The program object encapsulates:

- A context
- The program source/binary
- List of target devices and build options

The Build process ... to create a program object

- clCreateProgramWithSource()
- clCreateProgramWithBinary()



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OpenCL Synch: Queues & Events

- Events can be used to synchronize kernel executions between queues
- Example: 2 queues with 2 devices



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